

# Leveraging High-throughput Molecular Simulations and Machine Learning for Formulation Design

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## Abstract

Formulations, or mixtures of chemical ingredients, are ubiquitously found across material science applications, such as thermoplastics, consumer packaged goods, and energy storage devices. However, finding formulations with optimal properties is difficult because of the non-obvious connection between the individual ingredient structures and compositions to downstream mixture properties. Computational approaches that could traverse the expansive design space offer a promising solution to finding formulations with improved properties while minimizing the number of experiments. In this work, we generated a large formulation dataset using high-throughput classical molecular dynamics simulations that resulted in more than 30,000 solvent mixtures ranging between pure component to five component systems. We developed three formulation-property relationship approaches to create machine learning models which use the ingredient structure and composition as input to predict a formulation property: formulation descriptor aggregation (FDA), formulation descriptor Set2Set (FDS2S), and formulation graph (FG). We found that FDS2S, a new approach that uses a Set2Set layer to aggregate molecular descriptors of individual ingredients, outperforms all other approaches in accurately predicting density, heat of vaporization ( $\Delta H_{vap}$ ), and enthalpy of mixing ( $\Delta H_m$ ) that were computed from molecular simulations. Feature importance analysis of FDA models reveal that specific substructures are important to predicting these formulation properties, which is useful in the design of formulations to achieve target properties. When leveraging an active learning framework to iteratively suggest the next ingredient and composition to experiment on, we found that formulation-property relationships can identify formulations with the highest property values at least two to three times faster than randomly guessing. The results demonstrate that formulation-property relationships provide valuable insight to suggest the next experiment even when starting from a limited dataset of  $\sim 100$  examples. Our research demonstrates the utility of high-throughput simulations and machine learning algorithms applied to designing formulations with promising properties, which could broadly accelerate the design of new materials for a wide range of applications, such as improving the performance of liquid electrolytes for batteries, fuel mixtures for oil and gas, solvent additives for perfumes or paints, and more.

**Keywords:** Formulations, Chemical Mixtures, Classical Molecular Dynamics Simulations, Formulation-Property Relationships, Quantitative Structure-Property Relationships, Machine Learning

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## 40 1. Introduction

41 Formulations consisting of a mixture of chemical ingredients are crucial to a wide-range  
42 of material science applications. These mixtures have multiple chemical ingredients with  
43 well-defined compositional information, but their formulation properties are challenging to  
44 predict *a priori* because they emerge from non-obvious intermolecular interactions arising  
45 between multiple ingredients that heavily depend on both molecular structure and compo-  
46 sition. Hence, tuning the chemistry and composition for a desired formulation property is  
47 often performed with trial-and-error experiments, which is challenging given the large design  
48 space of possible chemical structures and compositions.

49 As an alternative to experiments, simulating all possible interactions between molecules  
50 with classical molecular dynamics (MD) simulations is a promising approach to compute  
51 properties of multicomponent systems. For example, MD simulations have been used to  
52 study the impact of copolymer blends on polymer properties [1], cosolvents on reactivity  
53 [2, 3], and surfactants on cosmetic properties [4]. MD simulations have achieved success in  
54 not only accurately capturing experimental trends [5–7], but they have also provided physical  
55 insight into the underlying mechanisms that lead to the bulk properties of multicomponent  
56 systems, such as phase separation or solvation behavior [2]. Despite significant advances  
57 in MD, the utility of MD to simulate formulation systems is limited by the number of  
58 atoms in the system, whereby large multicomponent systems with more than  $\sim 10$  different  
59 components may be computationally expensive to simulate but highly prevalent in materials  
60 applications like paints, perfumes or fuel [8].

61 Recent developments in data-driven machine learning modeling that could map chemi-  
62 cal structure to bulk properties have shown great promise to speed up chemical discovery,  
63 namely quantitative structure-property relationships (QSPR) [9]. QSPR modeling has pri-  
64 marily been focused on single molecule structure-property predictions, where expert-defined  
65 cheminformatics descriptors or graph representations are used to train machine learning  
66 models [10]. QSPR approaches for single molecules have shown great success in the last  
67 decade, especially in the small-molecule drug discovery field [9–11]. However, developing ac-  
68 curate QSPR models for formulation systems have not been well-explored. Recent literature  
69 have shown some success on applying machine learning to multicomponent systems, namely  
70 the use of various machine learning methods to predict thermodynamic properties [12], vari-  
71 ational autoencoders to predict compositions of ingredients [13], and graph neural networks  
72 to predict a variety of formulation properties, such as viscosities of binary mixtures [14], bat-  
73 tery performance [15, 16], or optical properties of dyes [17, 18]. However, the development  
74 of QSPR models for formulation systems (*i.e.* formulation-property relationships) have been  
75 largely hindered by the lack of publicly available, comprehensive datasets to evaluate these  
76 systems, which makes rigorous benchmarking of formulation-property relationships difficult.  
77 Given a sufficiently large formulation dataset, we can begin to tune accurate machine learn-  
78 ing models that can handle chemical information aggregated from multiple ingredients and  
79 varying compositions.

80 In this work, we explore QSPR methods for formulation systems to identify the best  
81 formulation-property relationships that can accurately predict formulation properties. Given

82 the lack of publicly available experimental data, we generate a representative formulation  
83 dataset consisting of  $\sim 30,000$  miscible solvent mixtures computed by MD simulations, where  
84 ensemble-averaged properties from MD correlate well with experiments. We focus on the  
85 capabilities of formulation-property models in predicting three relevant formulation proper-  
86 ties, namely packing density, heat of vaporization ( $\Delta H_{vap}$ ), and enthalpy of mixing ( $\Delta H_m$ ).  
87 We then apply feature importance analysis tools to identify the top features relevant to  
88 formulation-property relationships for each of the formulation property, which provides use-  
89 ful insight into designing formulations for a desired property. Using the extensive formu-  
90 lation dataset generated by MD, we finally leverage an active learning framework to in-  
91 vestigate whether formulation-property models can identify the next best formulation to  
92 experiment on, starting from a small dataset size of 100 examples. This work highlights the  
93 use of high-throughput MD simulations and machine learning models for developing accu-  
94 rate formulation-property relationships, which broadly expands our capabilities to rapidly  
95 identify formulations with promising properties for materials applications.

## 96 2. Methods

### 97 2.1. Formulation dataset: Miscible solvents

98 Fig. 1A shows the workflow of selecting formulation examples given the miscibility table  
99 of 81 solvents that were tabulated against 25 solvents. We first extracted miscibility tables  
100 from the CRC handbook to identify pairs of industrially relevant solvents that were miscible  
101 with one another from Ref. [19]. Fig. 1A shows an example of binary mixtures selected by  
102 using miscibility tables of acetone, benzene, and 1,2-ethanediol. In this example, acetone  
103 and benzene are considered a formulation since they are miscible, whereas benzene and 1,2-  
104 ethanediol were not considered a formulation since they are immiscible. One limitation of  
105 using miscibility tables is that they measure miscibility with equal volumes of two liquids,  
106 which does not inform us on whether the mixture is miscible when varying compositions.  
107 We further tested whether varying compositions of binary solvent mixtures result in any  
108 immiscibilities, and we observed that the majority of the mixtures are miscible based on MD  
109 simulations (see Supporting Information Fig. S1 and Fig. S2). For an  $N$ -component system,  
110 we assumed that if every solvent pair were miscible with one another, then the entire  $N$ -  
111 component system is assumed to be miscible and considered as a viable formulation. Fig. 1B  
112 shows the number of possible unique formulations as we increase the number of components  
113 up to six. We arbitrarily selected to study up to five components, which consists of a  
114 total of 19,238 unique formulations. By using experimentally derived miscibility tables,  
115 we designed a large formulations dataset that consists of miscible solvent mixtures, where  
116 homogenous solutions are important in a variety of material science applications such as  
117 battery electrolytes, chemical reactivity, and consumer packaged goods.

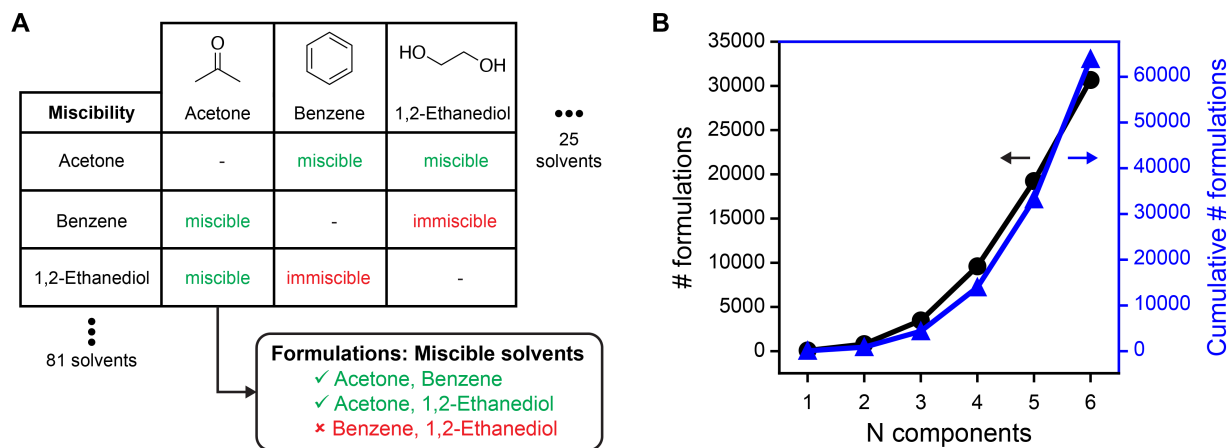


Figure 1: Formulation dataset generated from experimental miscibility tables. **A** Example of three solvents from miscibility tables extracted from Ref. [19]. Pairs of solvents that were labeled “miscible” were used to generate a formulation dataset. A total of 81 solvents were tabulated against 25 solvents for miscibility. **B** Number of unique formulations and cumulative number of unique formulations possible against the number of components using the miscibility table described in (A). The cumulative number of formulations means the cumulative sum of formulations from 1 to  $N$  components.

118 Using the 19,238 unique formulations for up to 5 components, we further varied the com-  
 119 position for binary and ternary systems as summarized in Table 1. We varied the composition  
 120 for binary mixtures such that each component is varied from 20%, 40%, 50%, 60%, 80%.  
 121 For ternary mixtures, we selected 60% of one component and 20% of other components, as  
 122 well as equimolar mixtures. Given the large possibilities of variations for quaternary and  
 123 quinary mixtures, only equimolar systems were studied here. In sum, a total of 30,142  
 124 formulation examples were studied in this work that span from pure-component systems  
 125 ( $N=1$ ) to quinary systems ( $N=5$ ).

$N$ components	Compositions	#unique formulations	#examples
1	{100}	81	81
2	{20,80} {40,60} {50,50} {60,40} {80,20}	716	3580
3	{20,20,60} {20,60,20} {60,20,20} {33,33,33}	2680	10720
4	{25,25,25,25}	6122	6122
5	{20,20,20,20,20}	9639	9639
Total		19238	30142

Table 1: Summary of formulations studied in this work as a function of number of components. Various compositions were varied as shown in brackets. For example, for binary mixtures, {20,80} means 20% of component 1 and 80% of component 2. The number of unique formulations and the total number of examples after variations of compositions are tabulated.

## 126 2.2. Classical molecular dynamics simulations

127 We performed MD simulations for all 30,142 formulation examples to generate the formu-  
128 lation labels necessary to build formulation-property relationships. For all simulations, we  
129 used the Schrödinger’s Materials Science Suite (MSS) [20], which leverages the Desmond MD  
130 engine to rapidly speed up MD computations through GPU acceleration [21]. All molecules  
131 were parameterized with the OPLS4 force field [5]. For each system, we first constructed  
132 an amorphous simulation cell with approximately 10,000 atoms. The initial density of the  
133 system in the amorphous cell structure was 0.5 g/cm<sup>3</sup>.

134 The system was equilibrated with the following procedure: (1) Brownian minimization  
135 for 150 ps; (2) a 0.5 ns *NVT* ensemble (Number of atoms, Volume, and Temperature are  
136 conserved) with 2 fs time step at temperature of 500 K and pressure of 1 atm; (3) 1 ns *NPT*  
137 ensemble (Number of atoms, Pressure, and Temperature are conserved) with 2 fs time step  
138 at temperature of 400 K and pressure of 1,000 bar; (4) 2 ns *NPT* ensemble with 2 fs time  
139 step at temperature of 300 K and pressure of 1 atm; (5) 5 ns *NPT* ensemble with 2 fs time  
140 step at the 300 K and pressure of 1 atm; (6) 10 ns *NPT* ensemble with 2 fs time step at  
141 temperature of 293 K and pressure of 1 atm. After this equilibration protocol, we take the  
142 average cell size of the last 20% of the previous step and subsequently perform 1 ns *NVT*  
143 ensemble with 2 fs time step at a temperature of 293 K. The final production run consists  
144 of a 20 ns *NVT* ensemble with 2 fs time step and temperature of 300 K, where the frames  
145 are stored at every 100 ps interval.

146 We extracted three MD descriptors from the last 10 ns of the production MD simulation:  
147 (1) packing density, (2) heat of vaporization ( $\Delta H_{vap}$ ), and (3) enthalpy of mixing ( $\Delta H_m$ ).  
148 Density was calculated by dividing the total molecular weight by the simulation cell volume  
149 and is reported in  $\text{g}/\text{cm}^3$ .

$\Delta H_{vap}$  is the amount of heat needed to convert some fraction of liquid into vapor.  $\Delta H_{vap}$  was calculated from the energy of the periodic unit cell ( $E_{cell}$ ) minus the sum of the  $N$  individual molecules,  $E_i$ , averaged over the last 10 ns of the production MD trajectory, as shown in Equation 1.

$$\Delta H_{vap} = \left\langle E_{cell} - \sum_i E_i \right\rangle + RT \quad (1)$$

150  $R$  is a gas constant with a value of  $1.9872036 \times 10^{-3} \text{ kcal K}^{-1} \text{ mol}^{-1}$ , and  $T$  is the temperature.  
151  $\Delta H_{vap}$  is reported in units of kcal/mol. While measuring  $\Delta H_{vap}$  for mixtures is challenging  
152 to measure experimentally [22],  $\Delta H_{vap}$  has been observed to correlate with temperature-  
153 dependent viscosities of pure liquids from MD simulations [23] and experiments [24]. There-  
154 fore,  $\Delta H_{vap}$  is an informative property that may be correlated to other materials properties.

155  $\Delta H_m$  is a fundamental thermodynamic property of liquid mixtures that measures the  
156 energy released or absorbed upon the mixing of pure components into a single phase in  
157 equilibrium.  $\Delta H_m$  was calculated using Equation 2 [25].

$$\Delta H_m = \langle E \rangle_m - \sum_i x_i \langle E \rangle_i + PV^E \quad (2)$$

158  $\langle E \rangle_m$  is the ensemble average cohesion energy of the mixture,  $x_i$  is the mole fraction of  
159 component  $i$ ,  $\langle E \rangle_i$  is the ensemble average cohesion energy of pure component  $i$ ,  $P$  is the  
160 pressure, and  $V^E$  is the excess volume of the mixture. Previous work have use kinetic and/or  
161 potential energies to estimate  $\Delta H_m$  [25, 26], but we observed that cohesion energy performed  
162 slightly better in agreeing with experiments (results are not explicitly shown here).  $V^E$  is  
163 calculated using Equation 3.

$$V^E = \langle V \rangle_m - \sum_i x_i \langle V \rangle_i \quad (3)$$

164  $\langle V \rangle_m$  is the ensemble average volume of the mixture, and  $\langle V \rangle_i$  is the ensemble average  
165 volume of pure component  $i$ .  $\Delta H_m$  is reported in units of kJ/mol. We treat these three MD  
166 descriptors as relevant formulation labels that are applicable to material science applications.  
167 For example, density is an important property for battery applications since it dictates  
168 the battery weight and charge mobility;  $\Delta H_{vap}$  is a property that effectively measures the  
169 cohesion energy of a liquid and has been previously observed to correlate with viscosity [23];  
170 and,  $\Delta H_m$  is important for process design that dictates properties, such as solubility and  
171 phase stability.

### 172 2.3. Formulation-property relationships

173 All formulation-property relationships were built using the DeepAutoQSAR framework,  
174 Schrödinger’s automated molecular property prediction engine [27, 28]. In DeepAutoQSAR,  
175 feature and model hyperparameter selection are iteratively improved by Bayesian optimiza-  
176 tion based on the model performance on the previous training cycle. This work extends

177 the DeepAutoQSAR workflow to be able to encode formulations as inputs, where multiple  
178 molecules with compositions are inputted rather than only single molecule property pre-  
179 dictions. We focused on formulation-property relationships that have the following ideal  
180 characteristics: (1) composition must be accounted for in the model such that variations  
181 in compositions impact property predictions; (2) models must be permutationally invariant,  
182 such that changing the order of input molecules and compositions do not change the predic-  
183 tion output; and, (3) models are flexible to the number of components, such that a model  
184 trained with binary mixtures can be used to predict ternary mixtures, quaternary mixtures,  
185 and so on. These model characteristics are important for designing formulations because  
186 composition is crucial to a formulation, ingredients can be inputted in a random order, and  
187 the inclusion or removal of particular ingredients is commonly evaluated to measure the  
188 impact of individual ingredients to formulation properties.

189 Fig. 2 summarizes three different approaches for developing formulation-property rela-  
190 tionships that satisfies the characteristics of an ideal model. Fig. 2A shows the formulation  
191 descriptor aggregation (FDA) approach where individual molecules are featurized, weighted  
192 by their corresponding compositions, then aggregated by performing a variety of statistical  
193 metrics like computing the mean, standard deviation, minimum, maximum, and median.  
194 These aggregated features are considered as formulation descriptors, which are then passed  
195 as inputs into ML models to predict formulation property. By aggregating with statistical  
196 approaches, the formulation descriptor captures the distribution of molecular properties of  
197 individual ingredients, which would be useful for property prediction. The FDA approach  
198 is analogous to matminer featurizers that perform statistical operations, such as averaging  
199 and standard deviation, to characterize inorganic materials by aggregating features from  
200 individual atomic types [29].

201 Fig. 2B shows a similar descriptor-based approach as FDA, but instead of aggregat-  
202 ing with statistical approaches, the compositionally weighted descriptors are passed into a  
203 Set2Set algorithm [30] to create a formulation descriptor vector (FDS2S). The Set2Set op-  
204 erator uses a combination of long short-term memory networks to process sequential data  
205 and softmax function as an attention layer to aggregate multiple arrays coming from multiple  
206 molecules into a single array [30]. Set2Set outputs the same array even when the order of  
207 the input array is changed, thus satisfying the requirement of permutation invariance for an  
208 ideal formulation-property model. The final array from the Set2Set layer is then passed to  
209 a fully connected layer to predict the formulation property. The usefulness of Set2Set as a  
210 way to aggregate information has been seen in several previous works, such as aggregation  
211 of reactant or product information to predict bond disassociation energies [31] or hydrolysis  
212 energies [32].

213 Fig. 2C shows a graph-based representation approach (FG), where atoms are nodes and  
214 bonds are edges. Each node vector consists of 75 atomic features and the composition of  
215 the ingredient. For each node, graph convolution operators aggregate information from the  
216 neighboring nodes and output a new atomic vector based on message passing across the  
217 molecular graph. The final learned atomic features are then outputted to a readout layer,  
218 which are then input to a fully connected neural network to predict the formulation prop-  
219 erty. Previous work have shown success in using graph-based representations for predicting  
220 viscosity of binary mixtures [14] and battery performance of electrolyte systems [15].

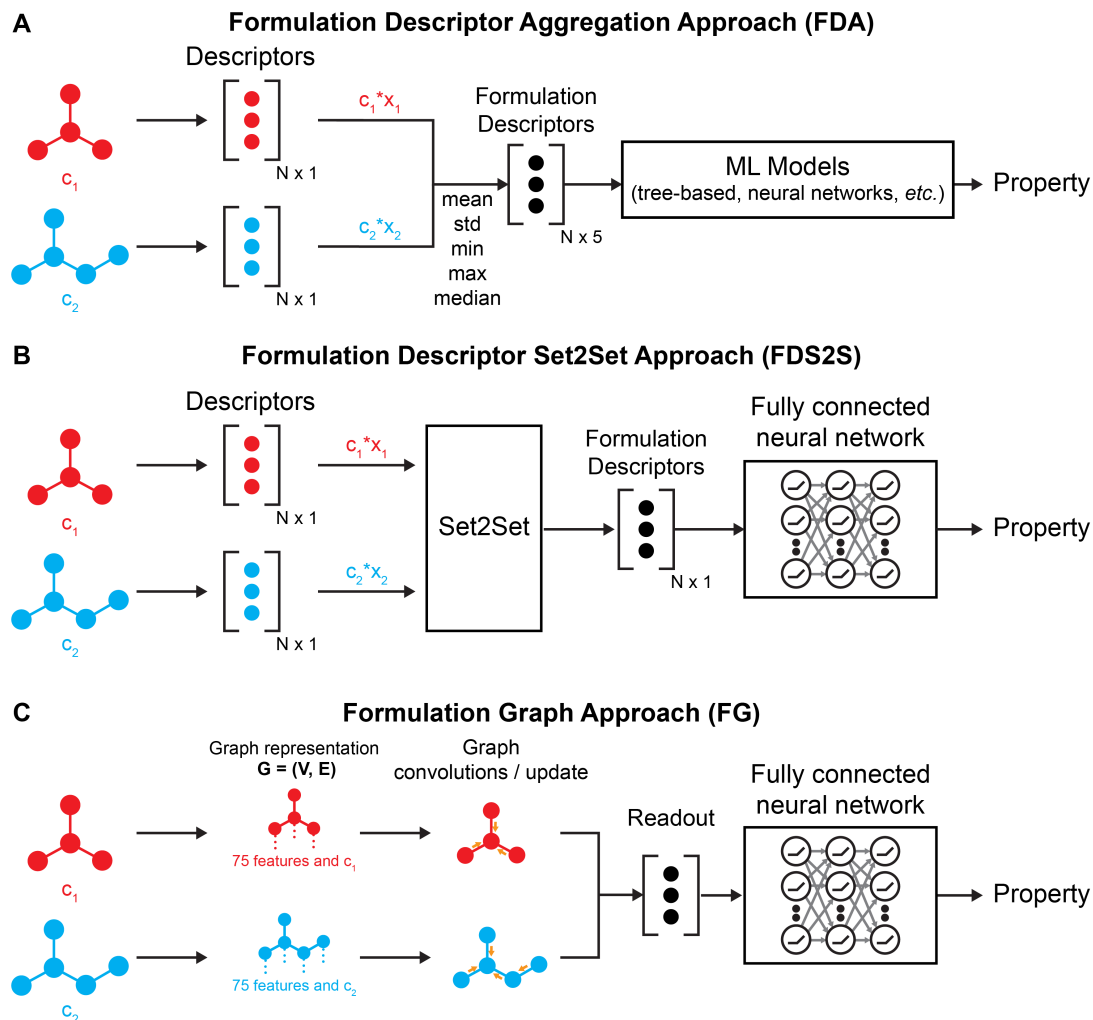


Figure 2: Schematic of formulation-property relationship approaches. **A** Formulation descriptor aggregation approach (FDA) where two molecules are featurized to generate molecular descriptors that are compositionally weighted, then aggregated by computing the mean, standard deviation (std), minimum (min), maximum (max), and median values. These aggregated features are considered as formulation descriptors that are passed into machine learning algorithms to predict formulation properties. **B** Formulation descriptor Set2Set approach (FDS2S) where two molecules are featurized to generate molecular descriptors that are compositionally weighted, then these descriptors are aggregated using a Set2Set algorithm, and finally the aggregated descriptors are passed into a fully connected neural network to predict formulation properties. **C** Formulation graph approach (FG) where two molecules are represented as graphs ( $G$ ) consisting of atoms as nodes ( $V$ ) and bonds as edges ( $E$ ). For each molecule, 75 atomic features and composition are used in the node vector. Graph convolutions and update operations are performed, followed by a readout layer and a fully connected neural network to predict formulation properties.

221 For descriptor-based approaches (*i.e.* FDA and FDS2S), four distinct molecular featur-  
 222 ization approaches were evaluated: (1) 200 RDKit descriptors; (2) Morgan fingerprints with  
 223 a size of  $\sim 500$ -2,060 and radius of  $\sim 2$ -4; (3) 167-bit MACCS keys, which are 2D structure  
 224 fingerprints commonly used to measure molecular similarity or virtual screening [33]; and,  
 225 (4) 132 matminer descriptors. Featurization for RDKit, Morgan fingerprints, and MACCS  
 226 keys were implemented using the rdkit package (Version 2023.9.5) [34], whereas matminer



227 descriptors were implemented using the matminer package (Version 0.9.0) [29]. All features  
228 were preprocessed with the following procedure: (1) constant features with variance of zero  
229 were removed; (2) correlated features with Pearson’s  $r$  greater than or equal to 0.90 were  
230 removed; and, (3) features were standardized by subtracting the mean and dividing by the  
231 standard deviation. For the FDA approach, the use of 200 RDKit descriptors as a featur-  
232 izer were omitted because of the poor generalizability to new formulations for specific data  
233 splits, which is likely because these descriptors are molecular size dependent (*e.g.* molecular  
234 weight). For the FG approach, 75 atomic features were used to featurize each of the heavy  
235 atoms. Atomic featurizations include one-hot encodings of atomic number, implicit valence,  
236 formal charge, atomic degree, number of radial electrons, hybridization, and aromaticity [28].  
237 The composition of the molecule was added as the 76th atomic feature to all nodes. Node  
238 features were preprocessed by removing correlated features with Pearson’s  $r$  greater than  
239 or equal to 0.90 and non-binary features were standardized by subtracting the mean and  
240 dividing by the standard deviation.

241 For the FDA approach, four ML algorithms were tested: elastic net, support vector re-  
242 gression, extreme gradient boosting (XGBoost) [35], and fully connected neural network. For  
243 the FDS2S approach, only a model with the Set2Set layer [30] and fully connected neural  
244 network was used. For the FG approach, ten graph-based approaches were evaluated: Graph  
245 Convolution Neural Network (GCN) [36], Pytorch version of GCN (TorchGraphConv) [37],  
246 TopK [38], GraphSAGE [39], Graph Isomorphism Network (GIN) [40], Self-Attention Graph  
247 Pooling (SAGPool) [41], EdgePool [42], GlobalAttention [40], Set2Set [30], and SortPool [43].  
248 Different GNN models differ slightly by how they aggregate information based on successes  
249 from previous literature [40, 42]. Elastic net and support vector regression were imple-  
250 mented using the scikit-learn package (Version 1.2.1)[44]. XGBoost was implemented with  
251 the xgboost package (Version 1.7.4) [35]. Fully connected neural networks and graph-based  
252 models were trained with PyTorch (Version 2.0.1) [45]. The details of each ML algorithm  
253 and hyperparameters are summarized in Ref. [28]. All formulation-property training and  
254 prediction workflows are available as the “Formulation Machine Learning” panel within the  
255 Schrödinger’s Materials Science Suite, Release 2024-2 [46].

#### 256 *2.4. Evaluation of formulation-property models*

257 Since the formulation dataset contains multiple entries with the same set of molecules with  
258 different compositions, we implemented an out-of-sample approach for data splitting, where  
259 unique formulations are iteratively introduced to the training set until it reaches 90% of the  
260 dataset and the remaining 10% of the data is placed in the testing set. Previous studies have  
261 emphasized that out-of-sample splitting is a better approach to measure model accuracy as  
262 compared to random splitting from an application standpoint because the model performance  
263 from random splitting may lead to over-optimistic model performance for datasets with  
264 repeated molecules where the same molecule could appear in both train and test sets [47].  
265 A learning curve was generated by setting aside 10% of the 30,142 formulation example  
266 dataset as the test set, where the test set is explicitly selected to be unique formulations  
267 that are not observed in the set used for training. Portions of the remaining 90% of the  
268 30,142 formulation example dataset was used to train formulation-property relationships,  
269 where the trained model was then used to evaluate the left-out test set. To alleviate possible  
270 biases of the random, out-of-sample train/test split, this procedure is repeated a total of

271 three times with different random seeds, where the average test set performance is reported  
272 and the uncertainty is estimated by computing the standard deviation of the three seeds.

273 For model training, all featurizers and model hyperparameters are selected using Deep-  
274 AutoQSAR’s Bayesian optimization approach [28]. In this approach, the training set is  
275 partitioned into five sets used for five-fold cross validation (5-CV). For each of the five folds,  
276 one set is left-out as the validation set and the remaining sets are used to train the model;  
277 this procedure is repeated five times until all of the data instances are within the left-out  
278 set exactly once. DeepAutoQSAR uses the performance of 5-CV to evaluate the model’s  
279 ability to generalize to new examples, which is used by the Bayesian optimization algorithm  
280 to select the next best featurizer and model hyperparameters to test next. A total of 20 iter-  
281 ations of model training cycles were performed, and the three best-performing models with  
282 the highest 5-CV score are selected as the final ensemble model. For training sizes larger  
283 than 10,000 examples, the training set was randomly downsampled to 10,000 examples for  
284 hyperparameter tuning to improve computational efficiency, and the three best-performing  
285 models were re-trained with the entire training set as the final ensemble model. The best  
286 hyperparameters when training the formulation-property models with 90% of the dataset  
287 are tabulated in Table S2 of the Supporting Information.

### 288 *2.5. Feature importance of formulation-property models*

289 Feature importance of formulation-property models were only applied to the FDA ap-  
290 proach because pre-defined descriptors are easier to interpret than graph-based representa-  
291 tions. Given a trained formulation-property model, feature importance was calculated using  
292 the SHapley Additive exPlanations (SHAP) approach (shap package, Version 0.42.1), which  
293 is a game theory approach to quantify the contributions of single players in a collaborative  
294 game [48, 49]. Shapley values measure the impact of a formulation descriptor to an output  
295 property by including or excluding the descriptor across a set of instances. For all SHAP  
296 calculations, we use the test set instances to measure descriptor importance. The average  
297 magnitude of Shapley values is reported (*i.e.* Mean |SHAP|), and the sign of the importance  
298 is determined by computing the Pearson’s  $r$  correlation coefficient between the Shapley and  
299 descriptor values. Positive Pearson’s  $r$  between Shapley and descriptor values indicate that  
300 the feature positively contributes to the output property, whereas negative Pearson’s  $r$  indi-  
301 cates the converse. Additional details about the SHAP method could be found in previous  
302 literature [9, 50, 51]. For an ensemble of models, the aggregation of SHAP values are used  
303 to compute the Mean |SHAP|.

### 304 *2.6. Active learning with formulation-property models*

305 Active learning is an iterative supervised learning to guide materials design, where start-  
306 ing with a small dataset, a machine learning model is trained and evaluated on a large pool  
307 of examples to suggest the next candidates to measure properties; the cycle is repeated until  
308 the desired property values are obtained. The benefit of an active learning approach is that  
309 it leverages data-driven techniques to make informed decisions on the next best candidates  
310 rather than random guessing. The suggestion of next candidates at each iteration are de-  
311 termined by the acquisition function ( $\alpha$ ), which often tries to balance between exploitation  
312 (sampling a space where a target property is achieved) and exploration (sampling a space  
313 where prediction uncertainty is high). We evaluated four acquisition functions that have

314 been studied in previous literature [52–54], where  $\mu(x)$  is the average prediction of sample  
315  $x$ ,  $\sigma(x)$  is the prediction uncertainty of sample  $x$  (estimated by computing the standard  
316 deviation of the predictions from the individual models of the ensemble):

1. **Expected improvement (EI)** acquisition function ( $\alpha_{EI}$ ) select samples based on balancing both exploration and exploitation described in Equation 4 and 5.

$$\alpha_{EI} = z\Phi(z) + \sigma(x)\phi(z) \quad (4)$$

$$z = \mu(x) - f(x^*) - \xi \quad (5)$$

317 where  $\Phi$  is the normalized cumulative distribution function,  $\phi$  is the normalized proba-  
318 bility distribution function,  $f(x^*)$  is the best performing prediction relative to the target  
319 objective, and  $\xi$  is the arbitrary constant that dictates the extent of exploration ( $\xi$  is set  
320 as zero for this work).

2. **Greedy** acquisition function ( $\alpha_{greedy}$ ) selects samples based on maximizing the target objective described in Equation 6.

$$\alpha_{greedy} = \max \mu(x) \quad (6)$$

3. **Most uncertain** acquisition function ( $\alpha_{uncertain}$ ) selects samples based on the highest prediction uncertainty described in Equation 7.

$$\alpha_{uncertain} = \max \sigma(x) \quad (7)$$

4. **Random** acquisition function selects samples randomly by assigning a random number from a uniform distribution to each sample.

327 The performance of formulation-property relationships and these acquisition functions  
328 were evaluated by setting aside 10% of the 30,142 formulation example dataset as the test  
329 set, which were explicitly selected to be unique formulations that are not sampled by the  
330 active learning workflow. For each iteration of active learning, the performance of the test  
331 set is measured to evaluate the models' ability to generalize to unseen formulations. Of the  
332 remaining 90% data, an initial batch of 100 examples were randomly selected as the training  
333 set. For each iteration, formulation-property models were trained, used to evaluate the left-  
334 out test set, and used to determine the next candidates to include in the training set based  
335 on the acquisition function. The active learning cycle was repeated with increments of 100  
336 examples until the training size reached 2,000 examples. The active learning performance  
337 was evaluated by computing the 10% left-out test set coefficient of determination ( $R^2$ ) as a  
338 measure of model generalizability and by computing the ability of the models to recapture  
339 the top 5% of structures in the training set as a function of training size. For each acquisition  
340 function, three individual runs were performed based on three random seeds to accurately  
341 measure the active learning performance. The reported performance is the average of the  
342 random seeds, and the uncertainty is measured by computing the standard deviation of

343 the performance of each seed. We arbitrarily selected to maximize all formulation proper-  
344 ties when evaluating the performance of formulation-property models in an active learning  
345 framework. For each training iteration, we enabled the DeepAutoQSAR framework to choose  
346 any of the three formulation-property relationships from Fig. 2. For featurizers, we enabled  
347 MACCS keys, Morgan fingerprint, and graph representations. For models, we enabled neural  
348 network models, Set2Set models, or GlobalAttention graph-based models [40]. These featur-  
349 izers and models were selected based on the best hyperparameters when trained with 90% of  
350 the dataset (see Table S2 in the Supporting Information). A total of 20 iterations of model  
351 training cycles were performed, and the three best-performing models with the highest 5-CV  
352 score are selected as the final ensemble model.

### 353 3. Results and Discussion

#### 354 3.1. Generating large formulation dataset with classical molecular dynamics simulations

355 We first validated whether simulation-derived properties can accurately capture experi-  
356 mental trends for industrially relevant solvents. Fig. 3A shows an example of acetone and  
357 benzene that are equally weighted and simulated with MD to compute formulation prop-  
358 erties. The simulation snapshot from Fig. 3A shows a well-mixed system of acetone and  
359 benzene, which is consistent with the experimental miscibility table in Fig. 1A. Fig. 3B  
360 shows the correlation coefficient ( $R^2$ ) between simulation-derived and experimental proper-  
361 ties for density,  $\Delta H_{vap}$ , and  $\Delta H_m$ . For all formulation properties, we observe good agreement  
362 between simulation-derived and experimental properties with a  $R^2 \geq 0.84$ . Fig. 3C-E shows  
363 the parity plot between simulation-derived and experimental properties. For density (Fig.  
364 3C), we compared the packing density of eleven pure solvents and observe a strong agree-  
365 ment against experiments with a  $R^2$  of 0.98 and root-mean-squared error (RMSE) of  $\sim 15.4$   
366  $\text{g}/\text{cm}^3$ . Similarly, we observe a strong correlation between MD simulations and experiments  
367 for  $\Delta H_{vap}$  when comparing 34 pure solvents (Fig. 3D), which achieved an  $R^2$  of 0.97 and  
368 RMSE of 3.4 kcal/mol. Density and heat of vaporization are expected to be well-captured  
369 from MD simulations since the OPLS4 forcefield is parameterized to accurately predict these  
370 properties [5]; hence, the results in Fig. 3C and 3D are consistent with the literature in that  
371 these two properties are accurately predicted with MD simulations [5–7]. On the other hand,  
372  $\Delta H_m$  is not used to parameterize the OPLS4 forcefield, but  $\Delta H_m$  has shown good agreement  
373 between experiments and MD simulations for a variety of solvents, such as nonpolar-nonpolar  
374 mixtures (*e.g.* benzene and cyclohexane) and nonpolar-polar mixtures (*e.g.* benzene and  
375 ethanol) [25]. Fig. 3E shows that simulation-derived  $\Delta H_m$  captures experimental trends  
376 for 53 binary mixture examples using the simulation protocol in this work. Given that the  
377 simulation-derived properties correlate with experiments for density,  $\Delta H_{vap}$ , and  $\Delta H_m$ , we  
378 validated that MD simulations can accurately capture formulation properties for solvent  
379 systems studied in this work.

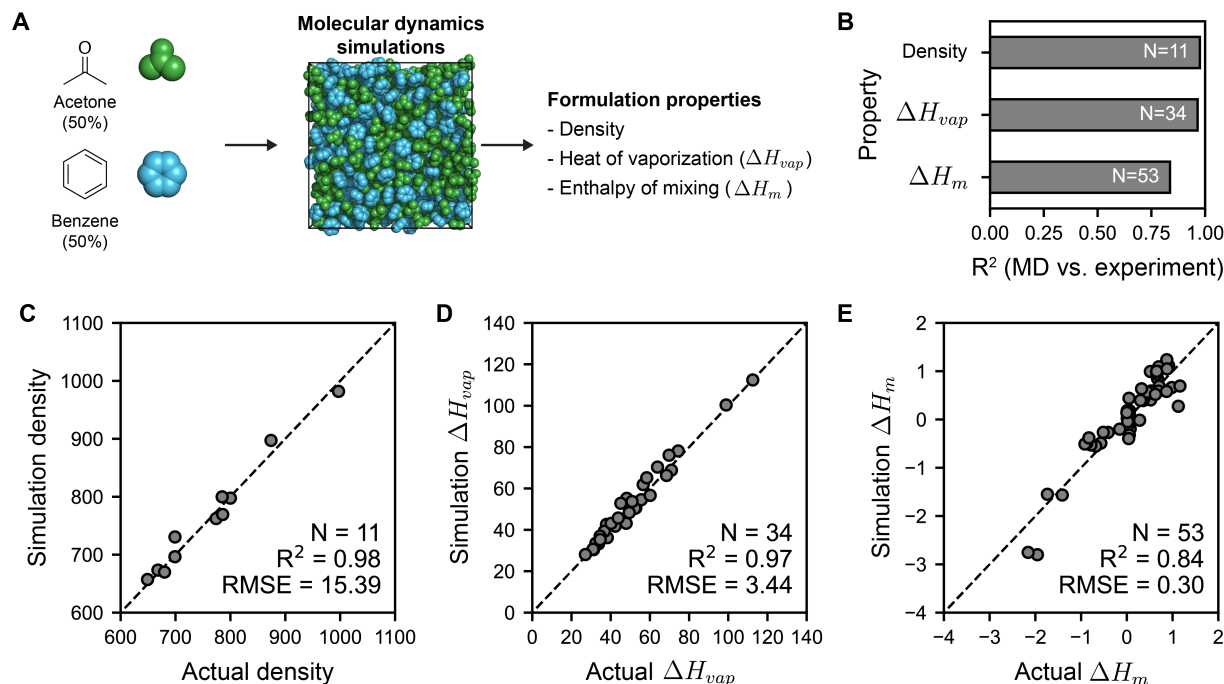


Figure 3: Generating formulation labels using classical molecular dynamics (MD) simulations and validating them against experiments. **A** Workflow to compute formulation properties by adding a 50 wt% acetone and 50 wt% benzene mixture into a MD simulation. Formulation properties are computed using the last 10 ns of a production MD run. **B** Coefficient of determination ( $R^2$ ) between MD simulation and experimental values for density, heat of vaporization ( $\Delta H_{vap}$ ), and enthalpy of mixing ( $\Delta H_m$ ).  $N$  denotes the number of datapoints used for each validation. **C** Simulation-derived versus experimental density for eleven pure solvent examples. **D** Simulation-derived versus experimental  $\Delta H_{vap}$  for 34 pure component examples. Experimental densities and  $\Delta H_{vap}$  were taken from the CRC handbook [19]. **E** Simulated versus experimental enthalpy of mixing for 54 binary mixture examples. Experimental enthalpy of mixing values were extracted from Ref. [25]. All scatter plots contain coefficient of determination ( $R^2$ ) and root-mean-squared error (RMSE) between simulation and actual values in the lower right corner. A diagonal gray dashed line is shown as a visual guide. The examples used to compare the formulation labels between MD simulations and experiments are tabulated in Table S1 of the Supporting Information.

380 Since MD simulations can accurately capture experiment trends, we then used MD sim-  
 381 ulations to generate a large formulation dataset that is useful to benchmark formulation-  
 382 property relationships. Using the miscibility table to identify miscible solvent systems rang-  
 383 ing from pure component systems ( $N = 1$ ) to quinary systems ( $N = 5$ ) as described in  
 384 Fig. 1, we performed 30,142 MD simulations and extracted the density,  $\Delta H_{vap}$ , and  $\Delta H_m$   
 385 from the production simulations (see the Methods section for simulation details). Fig. 4  
 386 shows the box and whisker plot of density,  $\Delta H_{vap}$ , and  $\Delta H_m$  computed from MD simula-  
 387 tions as a function of number of components. Fig. 4A and Fig. 4B shows that as the number  
 388 of components increase, the distribution of density and  $\Delta H_{vap}$  are more narrow as compared  
 389 to pure component systems ( $N = 1$ ). These results show that pure component systems  
 390 have a large range of properties as compared to when mixing the individual components,  
 391 and mixtures of solvents can be used to fine-tune properties to highly specific values that  
 392 is not possible when only using pure component systems. Similar to density and  $\Delta H_{vap}$ ,  
 393 Fig. 4C shows that increasing number of components results in narrower ranges for  $\Delta H_m$ .

394 However,  $\Delta H_m$  differs from the other two properties in that pure component systems will  
 395 have  $\Delta H_m = 0$  because  $\Delta H_m$  of a mixture is relative to its corresponding pure component  
 396 systems. Hence, binary systems ( $N = 2$ ) have the largest range of  $\Delta H_m$  values. Since  $\Delta H_m$   
 397 is a relative mixture property, it may be a challenging property to predict with formulation-  
 398 property relationships as the model will need to learn differences between the mixture and  
 399 its individual components. We use the 30,142 formulations with the three property labels  
 400 from MD simulations to evaluate whether the formulation-property approaches in Fig. 2 can  
 401 be used to create accurate models.

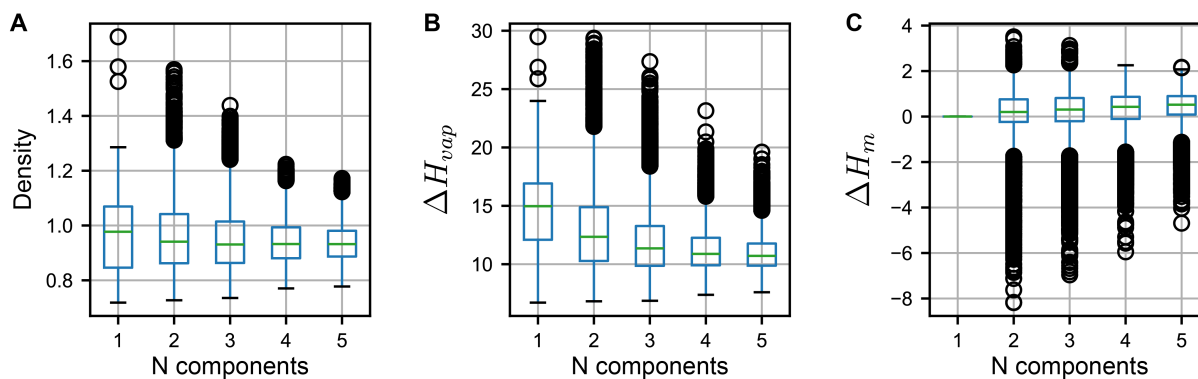


Figure 4: Distribution of the formulation labels from classical molecular dynamics simulations. Box and whisker plot between formulation labels versus number of components are shown for (A) density, (B) heat of vaporization ( $\Delta H_{vap}$ ), and (C) enthalpy of mixing ( $\Delta H_m$ ). Gray grid lines are shown as visual guides.

### 402 3.2. Performance of formulation-property models

403 We next evaluate the performance of the different formulation-structure approaches (Fig.  
 404 2) on predicting the three formulation properties extracted from MD simulations (Fig. 4).  
 405 The performance of each formulation-property approach is measured by using a learning  
 406 curve, where a machine learning algorithm is iteratively trained with incrementally increasing  
 407 training sizes to determine its prediction accuracy on a left-out test set as a function of  
 408 training set size. An ideal formulation-property model should be able to accurately predict  
 409 formulation properties at both small ( $\sim 100$  examples) and large ( $> 1000$  examples) dataset  
 410 sizes, especially since many formulation datasets are often data limited. For example, a  
 411 recent study had fewer than 200 electrolyte formulations that were experimentally available  
 412 to evaluate machine learning approaches on predicting battery charging efficiencies [15],  
 413 which makes benchmarking data-driven approaches for formulations challenging. By using  
 414 MD simulations to generate formulation labels, we can rigorously analyze the performance  
 415 of formulation-property relationships at both small and large dataset sizes, which would be  
 416 useful to identify formulation-property approaches that are accurate for a broad range of  
 417 training sizes.

418 Fig. 5A-C shows the learning curve performance of FDA, FDS2S, and FG models when  
 419 predicting density,  $\Delta H_{vap}$ , and  $\Delta H_m$ . Each learning curve shows the test set  $R^2$  as a function  
 420 of training set size. When the target property is density (Fig. 5A), all formulation-property  
 421 models achieve test set  $R^2 \sim 0.90$  when  $> 500$  training examples are available, which demon-  
 422 strates that the formulation-property models can accurately predict density with relatively

423 small dataset sizes. When the training size is less than 100, FDS2S models outperform FDA  
424 and FG approaches in predicting the test set density. Of the three target properties, density  
425 is the easiest property for formulation-property models to predict, which may be due to  
426 its general monotonic behavior as a function of composition for most binary mixtures [25].  
427 Fig. 5B shows that formulation-property models can also accurately capture  $\Delta H_{vap}$  with  
428 a test set  $R^2 \geq 0.80$  when  $>500$  training examples are available. Interestingly, FG models  
429 struggle to predict  $\Delta H_{vap}$  when the training size is less than 200, whereas descriptor-based  
430 models (FDA and FDS2S) achieve test set  $R^2 \geq 0.60$  at this limited data region. The poor  
431 prediction accuracy of FG models is likely due to poor representations generated when using  
432 graph convolution neural networks when limited data is available. Pre-defined descriptors  
433 that can better represent the material at the small data scale have been shown to outperform  
434 graph-based models, where graph models that automatically learn molecular representations  
435 through convolutional operations require sufficient amount of training data to obtain infor-  
436 mative molecular features [9, 23]. Similar to density, FDS2S outperforms the other models in  
437 predicting  $\Delta H_{vap}$  across all training sizes. Fig. 5C shows that formulation-property models  
438 generally struggle to predict  $\Delta H_m$  until the training size is at least  $\sim 5,000$  examples, which  
439 achieve a test set  $R^2 \geq 0.80$ . FDS2S performs the best in predicting  $\Delta H_m$  for majority  
440 of the training sizes. At the large training sizes, FDS2S and FG models outperform FDA  
441 models, which highlights the strength of deep neural networks and learned representations  
442 at the large data scale when predicting complex properties.  $\Delta H_m$  is a relative property of  
443 a mixture to pure component systems, which adds to the complexity of creating accurate  
444 formulation-property relationship as differences of the mixtures to pure component systems  
445 are not explicitly defined in formulation-property relationships. One possible way to im-  
446 prove the predictions to  $\Delta H_m$  is to encode descriptor differences between multiple species  
447 to improve the predictions of relative properties, such as taking differences between reactant  
448 and product feature space to improve the prediction of bond dissociation energies [31] or  
449 hydrolysis energies [32], which is a subject of future work.

450 Given that FDS2S demonstrated high test set  $R^2$  for all formulation properties in both  
451 small and large training sizes, we further analyzed the performance of FDS2S on the test  
452 set. Fig. 5D-F shows the parity plot between predicted and actual values for density,  $\Delta H_{vap}$ ,  
453 and  $\Delta H_m$  of the left-out test set when FDS2S models are trained with 90% of the data (*i.e.*  
454 training size of 27,127). Fig. 5D and Fig. 5E shows that formulation-property models can  
455 accurately predict density and  $\Delta H_{vap}$  for new formulation examples with test set  $R^2$  close  
456 to unity. Furthermore, Fig. 5E shows that properties like  $\Delta H_m$ , which are challenging to  
457 predict, can also be accurately predicted with a test set  $R^2$  of 0.96 when a large number  
458 of data points are available. The results in Fig. 5 demonstrate that the FDS2S approach  
459 achieves high accuracy in predicting all the three formulation properties, and the FDS2S  
460 approach ranks higher than the FDA and FG approach in consistently creating accurate  
461 formulation-property models for both small and large dataset sizes. From the best of our  
462 knowledge, the FDS2S approach to create accurate formulation-property models have not  
463 yet been reported in the literature, and the results from Fig. 5 suggests that FDS2S is a  
464 promising approach to leverage the strengths of traditional descriptor-based approaches (*e.g.*  
465 FDA) at the small data scale and strengths of graph-based approaches (*e.g.* FG) at the large  
466 data scale to creating accurate formulation-property models regardless of dataset size.

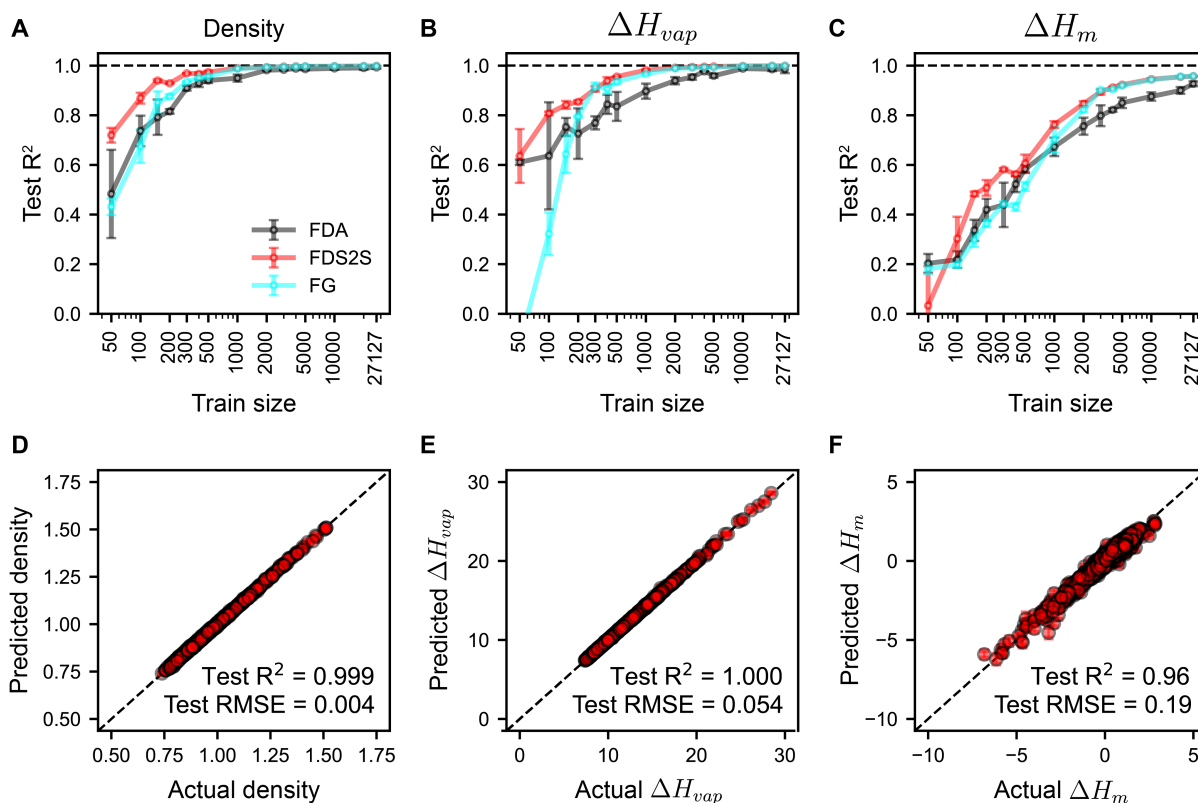


Figure 5: Performance of formulation-property relationships. Learning curve showing the left-out test set coefficient of determination ( $R^2$ ) as a function of training size when formulation-property models are trained to predict (A) density, (B) heat of vaporization ( $\Delta H_{vap}$ ), and (C) enthalpy of mixing ( $\Delta H_m$ ). The average test set  $R^2$  of three independent runs are shown, and the uncertainty is estimated by computing the standard deviation of the individual runs. Dashed black line is drawn at test set  $R^2$  of 1 as a visual guide. The parity plots between predicted and actual values of the test set when FDS2S models are trained with 90% of the data (27,127 examples) are shown for (D) density, (E)  $\Delta H_{vap}$ , and (F)  $\Delta H_m$ . For parity plots, the test set  $R^2$  and root-mean-squared error performance is shown in the bottom right and a dashed black diagonal line is drawn as a visual guide.

### 467 3.3. Feature importance of formulation-property models

468 Since machine learning models achieved a high test set accuracy ( $R^2 \geq 0.90$ ) when trained  
 469 with 90% of the data, we next sought to identify the top relevant features that were useful  
 470 to predict density,  $\Delta H_{vap}$ , and  $\Delta H_m$ . Of the formulation-property approaches shown in Fig  
 471 2, the FDA approach is the most straightforward to perform feature importance analysis  
 472 because predefined descriptors are more easy to interpret than graph-based representations.  
 473 The FDA approach perform similarly to FDS2S and FG approaches at 90% of the training  
 474 data (see training size of 27,127 in Fig. 5A-C), hence we would expect the top molecular  
 475 descriptors relevant to formulation properties from the FDA approach might be similar to  
 476 the FDS2S and FG approaches. We selected to use the SHAP approach to analyze the top  
 477 features for FDA models because the SHAP approach is model agnostic that enables the  
 478 evaluation of feature importance across different machine learning algorithms and have been  
 479 observed to capture relevant top features in previous works [23, 50, 51, 56, 57] (see Methods  
 480 section for details on how SHAP is computed).



481 Fig. 6 shows the top three descriptors using the SHAP approach for FDA models when  
482 trained to predict density,  $\Delta H_{vap}$ , and  $\Delta H_m$ ; example structures of individual solvent in-  
483 gredients are highlighted to the right of each descriptor. Fig. 6A shows that MACCS  
484 keys features were the most relevant features to accurate predictions of density. The mean  
485 MACCS keys of 160 and 114 contribute negatively to density, where the removal of low  
486 molecular weight methyl and ethyl groups lead to an increase in density. Conversely, the  
487 mean MACCS key of 107 contributes positively to density, which means that inclusion of  
488 high atomic weight halogen elements lead to an increase in density.

489 Fig. 6B shows that Morgan fingerprints were the most useful features to accurately  
490 predicting  $\Delta H_{vap}$ . The mean of the top Morgan fingerprints are all positively correlated  
491 with  $\Delta H_{vap}$ , namely the inclusion of benzene rings, hydroxyl groups, and methylene units.  
492  $\Delta H_{vap}$  is related to the cohesion energy of a solution; hence, favorable interaction energies  
493 between molecules in a mixture would typically lead to high  $\Delta H_{vap}$  values. Therefore, the  
494 inclusion of benzene rings may lead to  $\pi$ - $\pi$  stacking, which is well-known to be a favorable  
495 interaction in the literature [58]. Furthermore, the inclusion of hydroxyl groups lead to favor-  
496 able hydrogen bonding, and the inclusion of long methylene chains could lead to favorable  
497 nonpolar interactions [59]. Interestingly, Morgan fingerprint of index 46 with fingerprint  
498 size 952 (mean-MorganFingerprint\_46\_952) shows a bit-collision between benzene and hy-  
499 droxyl groups, where the bit-fingerprint is set to unity for multiple atomic environments.  
500 While bit-collisions lead to information loss of distinct atomic environments, the importance  
501 of hydroxyl groups are re-iterated in mean-MorganFingerprint\_536\_1050, which suggests  
502 that bit-collisions did not significantly impact the interpretability of top features. In sum,  
503  $\Delta H_{vap}$  can be increased by including ingredients with benzene groups, hydroxyl groups, or  
504 methylene units.

505 Similar to  $\Delta H_{vap}$ , Fig. 6C shows that Morgan fingerprints were top features relevant  
506 to predicting  $\Delta H_m$ . Interestingly, all top features relevant to  $\Delta H_m$  are nitrogen containing  
507 compounds, and they all contribute negatively to  $\Delta H_m$ . Previous literature have reported  
508 mixtures with nitrogen containing compounds, such as diethylamine and ethanol, have neg-  
509 ative  $\Delta H_m$  values with increasing diethylamine content [25], which is consistent with the  
510 top features in Fig. 6C. Therefore,  $\Delta H_m$  can be potentially tuned by including or removal  
511 of ingredients with nitrogen-containing groups. The results in Fig. 6 demonstrate that top  
512 features related to a property can be extracted from formulation-property models, which can  
513 be used to fine-tune the selection of ingredients that satisfy a desired property criteria.

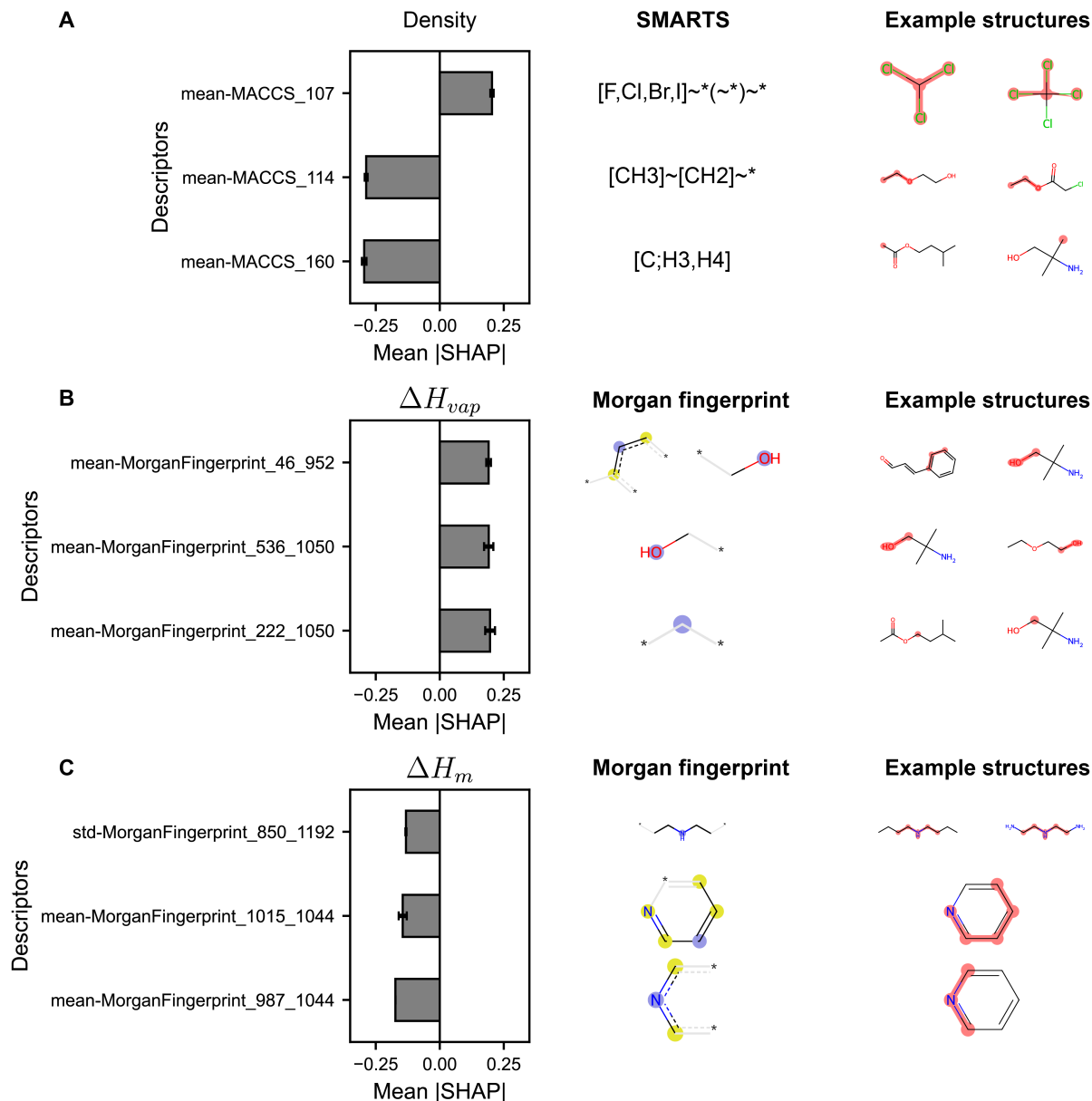


Figure 6: Feature importance from FDA models. Top three most important features measured as the average magnitude of SHapley Additive exPLanations (SHAP) values (*i.e.* Mean |SHAP|) are shown for FDA models trained with 90% of the 30,142 formulation examples to predict (A) density, (B) heat of vaporization ( $\Delta H_{vap}$ ), and (C) enthalpy of mixing ( $\Delta H_m$ ). Positive Mean |SHAP| indicates that the descriptor positively contributes to the formulation property, whereas negative Mean |SHAP| indicates the converse. The average Mean |SHAP| of three models of an ensemble is reported and the uncertainty is estimated by the computing standard deviation of the Mean |SHAP| values. For descriptors, prefixes with “mean” and “std” means that the compositionally weighted descriptor of individual ingredients was aggregated with average and standard deviation operations, respectively. For MACCS keys descriptors, the index of the MACCS key is shown in the right-most value (*e.g.* mean-MACCS\_107 means the 107th MACCS key). For Morgan fingerprint descriptors, the index and total length of the bit-fingerprint is shown as the two right-most values (*e.g.* mean-MorganFingerprint\_46\_952 means a Morgan fingerprint index of 46 with a fingerprint size of 952). SMARTS pattern for MACCS keys, Morgan fingerprints, and example structures with red highlighted patterns are illustrated to the right of the SHAP plots.

### 3.4. Active learning using formulation-property models

While formulation-property models are highly accurate with a large amount of data and can be subsequently used to extract important features relevant to a property, formulations design is often performed at the small data scale ( $\sim 100$  examples). Hence, we next evaluated whether formulation-property models are useful for identifying top candidates at the small data scale starting from 100 examples using an active learning approach. The typical approach for active learning is by using a surrogate model (*i.e.* a machine learning model) to train on a small subset of data and predict on a large pool of candidates; then, based on the predictions of the model, suggest the best candidates to evaluate in the next experiment. After the best candidates are evaluated, they are added as part of the training data, then the loop is repeated a set number of iterations until the desired property criteria is reached. The selection of best candidates from the machine learning predictions is determined based on the acquisition function. We evaluate four acquisition functions: expected improvement, greedy, most uncertain, and random acquisition functions (see Methods for details).

Fig. 7 shows the performance of using formulation-property models in an active learning framework to identify formulations with the highest density,  $\Delta H_{vap}$ , and  $\Delta H_m$ . Fig. 7A-C shows the  $R^2$  performance of formulation-property models on a 10% left out test set as a function of training size when using four distinct acquisition functions. Fig. 7D-F shows the percentage of formulations within the top 5% of density,  $\Delta H_{vap}$ , or  $\Delta H_m$  that were selected to be in the training set during the active learning iterations. For density as a target property, Fig. 7A shows that all acquisition functions result in a test set  $R^2$  of  $\sim 0.90$  when the formulation-property model with less than 500 examples. The greedy acquisition function has a lower test set  $R^2$  as compared to the other acquisition functions, suggesting that the greedy acquisition function results in models that are not as generalizable as compared to random selection. However, even though the greedy acquisition function results in less accurate models, Fig. 7D shows that the greedy acquisition function captures close to 90% of the top 5% density values after the training sizes reach  $\sim 1,500$  examples. Conversely, the expected improvement and most uncertain acquisition functions only achieve  $\sim 20\%$  of the top density candidates at the same training size. The random selection acquisition function is expected to be the worst with less than 5% of the top density values identified. At 2,000 examples, the greedy acquisition function identified formulations with the highest density values 14-folds higher than when randomly selecting formulations.

Similar to density as a target property, Fig. 7B shows that all acquisition functions result in  $\Delta H_{vap}$  models that achieve a test set  $R^2$  of  $\sim 0.90$  when the training set contains 500 examples, and the greedy acquisition function generally has lower test set  $R^2$  as compared to the other acquisition functions. Interestingly, Fig. 7E shows that greedy, expected improvement, and most uncertain perform similarly in identifying formulations with the top 5%  $\Delta H_{vap}$ . At the training size of 2,000,  $\sim 15\%$  of the top  $\Delta H_{vap}$  is identified for all acquisition functions other than random selection; the latter only identified  $\sim 5\%$  of formulations with the the top  $\Delta H_{vap}$  values. Irrespective of expected improvement, greedy, or most uncertain acquisition function choice, we observe that formulation-property models can improve the identification of formulations with high  $\Delta H_{vap}$  values 2-3 times faster than random selection.

Fig 5 demonstrated that  $\Delta H_m$  was the most challenging to predict out of the three properties for formulation-property models. Fig. 7C shows that varying acquisition functions do not dramatically improve generalizability of formulation-property models to predict  $\Delta H_m$ ;

559 the most uncertain acquisition function achieved a highest test set  $R^2$  of  $\sim 0.80$  when the  
560 training size is 2,000 examples, slightly higher than the random acquisition function. The  
561 greedy acquisition function struggled to create a generalized  $\Delta H_m$  model and achieved a test  
562 set  $R^2$  of  $\sim 0.40$  for all training sizes. Fig. 7F shows that the most uncertain acquisition  
563 function performed the best in identifying the formulations with the highest 5% of  $\Delta H_m$   
564 values, followed by expected improvement and greedy acquisition functions. Interestingly,  
565 the most uncertain acquisition function are not geared towards finding the maximum  $\Delta H_m$  as  
566 compared to expected improvement and greedy acquisition functions, but the most uncertain  
567 acquisition function still outperformed the other two approaches by choosing candidates  
568 with the highest prediction uncertainty. The results in Fig. 7F show that even though  
569 the formulation-property models may not accurately predict  $\Delta H_m$  at the small data scale,  
570 prediction uncertainties of  $\Delta H_m$  could be useful to identify formulation candidates that are  
571 outside the domain of the training data and may have extrema of  $\Delta H_m$  values. The most  
572 uncertain acquisition function achieves 2-3 times higher likelihood of selecting formulation  
573 candidates with high  $\Delta H_m$  values as compared to random selection.

574 Fig. 7 demonstrates that formulation-property models are useful to identifying the next  
575 formulation candidates as compared to random selection irrespective of the acquisition func-  
576 tion used. The selection of acquisition functions to use for an active learning workflow is  
577 highly dependent on the target property and how it is related to the underlying formulation  
578 structure. For simpler properties to predict with high test set  $R^2$  close to 0.90, such as den-  
579 sity or  $\Delta H_{vap}$ , the greedy or expected improvement acquisition function generally perform  
580 well in identifying formulations with high property values. Conversely, for difficult to predict  
581 properties, such as  $\Delta H_m$ , most uncertain and expected improvement acquisition functions  
582 that accounts for prediction uncertainty are better at identifying formulations that may  
583 be outside of the training domain and represent the extrema of property values. Overall,  
584 formulation-property relationships can serve as a powerful approach to rapidly screen for-  
585 mulations even with limited data, provide insight into important ingredient characteristics  
586 relevant to a target property through feature importance analysis, and provide suggestions  
587 of next best candidates in an active learning workflow to iteratively identify formulations  
588 satisfying a property criteria.

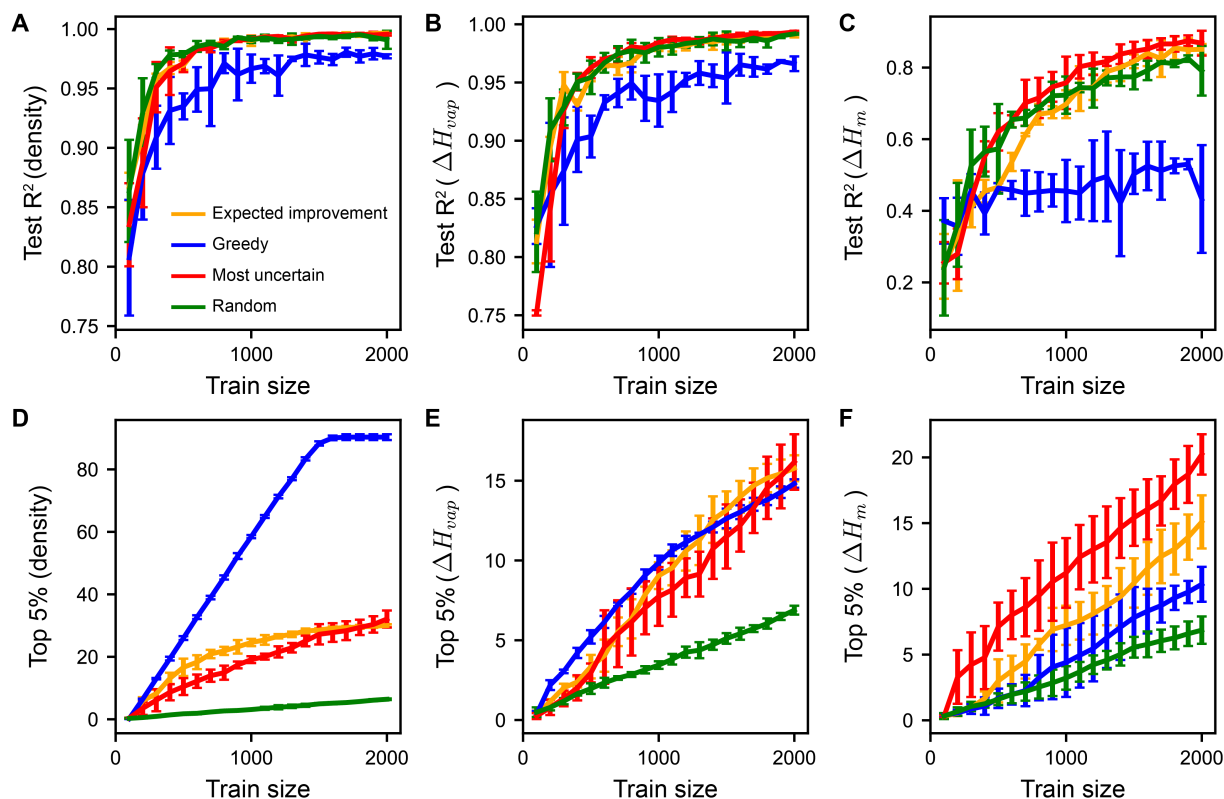


Figure 7: Active learning using formulation-property models. Left-out test set coefficient of determination ( $R^2$ ) as a function of train size when training formulation-property models to maximize (A) density, (B) heat of vaporization ( $\Delta H_{vap}$ ), and (C) enthalpy of mixing ( $\Delta H_m$ ) using an active learning approach for expected improvement, greedy, most uncertain, and random acquisition functions. 10% of the 30,142 formulation examples were randomly selected as the left-out test set such that the test set contains unique formulations that are unseen in the training data pool. The percentage of formulations that are within the top 5% of the target property as a function of training size is shown for (D) density, (E)  $\Delta H_{vap}$ , and (F)  $\Delta H_m$  for the same acquisition functions used in A-C. The reported  $R^2$  and top 5% is an average of three iterations of active learning runs with different random seeds, and the uncertainty of  $R^2$  is the standard deviation of the different seeds.

## 589 4. Conclusion

590 In this work, we developed formulation-property relationships that input ingredient structure and composition to predict formulation properties, which is broadly applicable to a wide-  
 591 range of materials applications. First, we developed a formulation dataset by identifying mis-  
 592 cible solvent mixtures based on miscibility tables and varied the number of components from  
 593 pure to five component systems that results in a total of 30,142 formulation examples (Fig.  
 594 1 and Table 1). We developed three distinct formulation-property relationships, namely the  
 595 formulation descriptor aggregation (FDA), formulation descriptor Set2Set (FDS2S), and the  
 596 formulation graph (FG) approach (Fig. 2). Then, we performed high-throughput classical  
 597 molecular dynamics (MD) simulations to generate formulation properties, such as density,  
 598 heat of vaporization ( $\Delta H_{vap}$ ), and enthalpy of mixing ( $\Delta H_m$ ), all of which correlate with  
 599 experimental data for specific solvent mixtures with a high correlation coefficient  $R^2$  greater  
 600

601 than  $\sim 0.84$  (Fig. 3). Using the large, simulation-derived formulation dataset, we found that  
602 increasing the number of components generally results in a narrower and denser property  
603 distribution, which suggests that mixtures of ingredients can allow for fine-tuning capabilities  
604 of the property space that is not possible with single component systems alone (Fig. 4). We  
605 benchmarked the different formulation-property approaches and found that the FDS2S ap-  
606 proach performed the best in accurately predicting density,  $\Delta H_{vap}$ , and  $\Delta H_m$  at both small  
607 and large data scales, achieving a test set  $R^2 \geq 0.96$  on all properties when trained with  
608 90% of the data (Fig. 5). Analyzing the top features related to the formulation properties  
609 revealed that particular substructures were important, such as the inclusion of heavy halogen  
610 atoms to increase formulation density, inclusion of benzene, hydroxyl, or methylene groups  
611 to increase  $\Delta H_{vap}$ , and inclusion of nitrogen-containing compounds to decrease  $\Delta H_m$  (Fig.  
612 6). Finally, when using formulation-property relationships in an active learning framework  
613 (Fig. 7), we observed that these models can rapidly identify the highest density,  $\Delta H_{vap}$ , and  
614  $\Delta H_m$  values at least 2-3 times more likely than random guessing, which demonstrates that  
615 these formulation-property models are useful for designing formulations even when starting  
616 with a small dataset of less than a hundred examples.

617 The results highlight the strengths of both high-throughput MD simulations and machine  
618 learning approaches in identifying formulations with promising properties. MD simulations  
619 can rapidly compute formulation properties that accurately correlate with experiments, hence  
620 enabling a way to accurately generate formulation properties for a wide-range of material  
621 systems. These simulation-derived properties were useful to benchmark machine learning  
622 workflows to identify accurate formulation-property relationships. Aside from benchmark-  
623 ing purposes, these simulation-derived properties could be used as inputs into formulation-  
624 property relationships to predict more challenging formulation properties, such as viscosity  
625 of binary mixtures [14], charging efficiency in battery electrolytes [15, 16], fuel characteristics  
626 [8], or drug solubility in solvent mixtures [60]. Future work will focus on expanding the utility  
627 of these formulation-property relationships by encoding physics-based properties to improve  
628 model accuracy, enabling the optimization of formulations using the formulation-property  
629 relationships, and evaluating feature importance tools on graph-based formulation-property  
630 models.

## 631 Conflict of Interest

632 The authors declare no competing interests.

## 633 Data Availability

634 The formulation dataset is available upon request and will be available in the supporting  
635 information upon peer-review publication under the [Creative Commons Non-Commercial  
636 4.0 International \(CC-BY-NC 4.0\) Attribution License](https://creativecommons.org/licenses/by-nc/4.0/). This license allows for the use of the  
637 dataset and the creation of adaptations, exclusively for non-commercial purposes, provided  
638 that appropriate credit is given.

## 639 Supporting Information

640 The supporting information contains the comparison of formulation labels between molec-  
641 ular dynamics simulations and experiments, analysis of miscibility for binary mixtures using  
642 molecular dynamics simulations, best hyperparameters of formulation-property models when  
643 trained with 90% of the data, and description of the formulation dataset.

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## 648 Author Contributions

649 A.K.C. and M.A.F.A. conceived the idea; A.K.C. performed the molecular dynamics sim-  
650 ulations under guidance of M.A.F.A; A.K.C. wrote and generated figures for the manuscript;  
651 A.K.C., Z.K., E.M.C., and S.G. developed the code for the machine learning workflow; M.M.  
652 developed the code and graphical user interface within the Schrödinger suite; K.L. proposed  
653 the idea for using Set2Set models; all authors modified and approved the manuscript.

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851 Table of Contents Graphic

