

# Fast and accurate modeling of thermoset fracture by active learning quantum-chemical bond scission

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## 2 **Abstract**

3 A molecular understanding of thermoset fracture is crucial for enhancing performance and  
4 durability across applications. However, achieving accurate atomistic modeling of thermoset  
5 fracture remains computationally prohibitive due to the high cost associated with quantum me-  
6 chanical methods for describing bond breaking. In this work, we introduce an active learning  
7 (AL) framework for our recently developed machine-learning based adaptable bond topology  
8 (MLABT) model that uses datasets generated via density functional theory (DFT) calcula-  
9 tions that are both minimalistic and informative. Employing MLABT integrated with AL and  
10 DFT, we explore fracture behavior in highly crosslinked thermosets, assessing the variations  
11 in fracture behavior induced by system temperature, temperature fluctuations, strain rate, cool-  
12 ing rate, and degree of crosslinking. Notably, we discover that while fracture is minimally  
13 affected by temperature, it is strongly influenced by strain rate, suggesting the absence of the  
14 time-temperature superposition in thermoset plasticity. Furthermore, while the structural dis-  
15 parities introduced by different network annealing rates influence the elastic properties, they

16 are inconsequential for thermoset fracture. In contrast, network topology emerges as the dom-  
17 inant determinant of fracture, influencing both the ultimate strain and stress. The integration  
18 of MLABT with the AL framework paves the way for efficient and DFT-accurate modeling  
19 of thermoset fracture, providing an affordable and accurate approach for calculating polymer  
20 network fracture across chemical space.

## 21 **Introduction**

22 Thermosets, characterized by the presence of irreversible polymer crosslinks and enhanced me-  
23 chanical properties, are foundational to numerous technological applications ranging from auto-  
24 motive components and aerospace structures to medical devices and protective coatings.<sup>1-3</sup> The  
25 robust nature of thermosets along with their adaptability have ushered in new horizons for mate-  
26 rial innovations.<sup>4,5</sup> Central to maximizing the potential of thermosets in these domains is an in-  
27 depth understanding of their fracture behaviors.<sup>6-10</sup> Recent advancements in computational tools  
28 and experimental techniques have provided insights into the fracture of thermosets.<sup>11-18</sup> How-  
29 ever, the atomic-scale processes governing these behaviors remain less explored. Delving into  
30 this atomic realm promises not only enhanced material predictability but also the prospect of tai-  
31 lored design.<sup>19,20</sup> Nevertheless, this pursuit presents formidable challenges: accurate atomic-level  
32 modeling of thermoset fracture necessitates substantial computational resources, especially when  
33 elucidating intricate bond breakage phenomena with quantum mechanical (QM) methods.<sup>21</sup> As  
34 the demand for higher performance materials grows, overcoming these challenges and obtaining a  
35 more comprehensive understanding of thermoset fracture at the molecular scale is imperative.

36 In our previous study, we introduced the Machine Learning based Adaptable Bonding Topology  
37 (MLABT) framework, an approach tailored for atomistic simulations of thermosets under large de-  
38 formation.<sup>22</sup> MLABT circumvents limitations of classical molecular dynamics (MD) simulations  
39 by integrating a machine learning (ML) algorithm for detection and execution of bond-breaking  
40 events (with near QM accuracy) with any underlying classical force-field. Compared to existing  
41 methods combining MD and QM,<sup>21</sup> MLABT exhibits an approximately two orders of magni-

42 tude improved computational efficiency, coupled with heightened sensitivity to rare bond-breaking  
43 events at low strains. This blend of speed and accuracy created by augmenting classical force-  
44 fields accurate at low strain with QM-quality bond-breaking detection renders MLABT a robust  
45 and chemically general tool for probing strain hardening and material failure dynamics in polymer  
46 networks.

47 While the development of MLABT is promising for modeling thermoset fracture, it is not with-  
48 out its challenges. First and foremost, generating a sufficient volume of training data using QM  
49 calculations is resource-intensive. Moreover, provided the rare nature of bond-breaking events,  
50 bond evaluations are primarily confined to a narrow strain-hardening window for efficiency rea-  
51 sons. Second, existing MLABT training data derives from configurations possessing intact cross-  
52 linked topologies, rather than those emerging *in situ* during fracture. These constraints, revolving  
53 around inefficient and insufficient configurational sampling, curtail the full potential of MLABT  
54 in offering a computationally efficient and molecularly detailed modeling paradigm for thermoset  
55 fracture. Recognizing these limitations, the field of active learning (AL),<sup>23,24</sup> defined by its ability  
56 to iteratively refine and expand training datasets, appears an apt fit for these challenges.<sup>25,26</sup>

57 In this work we integrate AL into MLABT simulations. This provides two concerted benefits  
58 for MLABT models: the ability (i) to systematically navigate the vast configurational space of  
59 thermoset fracture and (ii) to employ higher accuracy (i.e. more computationally costly) density  
60 functional theory (DFT) calculations that better capture the physics of bond breaking, by virtue  
61 of using nearly an order of magnitude less training data than previously. Empowered by this  
62 AL-DFT MLABT model, we conduct the first comprehensive exploration of thermoset fracture  
63 behaviors using a DFT-accurate bond-breaking model. We scrutinize how the stress-strain behav-  
64 iors as well as bond breakages are modulated by experimental factors including temperature, strain  
65 rate, cooling rate, and the degree of crosslinking. The results from our MLABT analysis reveal  
66 that strain rates have a more pronounced effect on bond breakages than temperature, suggesting  
67 that the time-temperature superposition principle does not hold for thermoset plasticity. Impor-  
68 tantly, network topology appears to be more influential than the stability of the glassy structure in

69 determining fracture behavior. Furthermore, we demonstrate that thermoset stress-strain behavior  
70 exhibits small variance under thermal fluctuations, indicating a certain degree of degeneracy in net-  
71 work fracture. Considering that MLABT leverages the DFT accuracy for bond breaking in fracture  
72 modeling, yet doesn't capture the brittle failure seen in experiments, we conjecture that embracing  
73 larger spatiotemporal scales in modeling will be essential for better alignment with experiments.

## 74 Methods

### 75 MLABT simulation

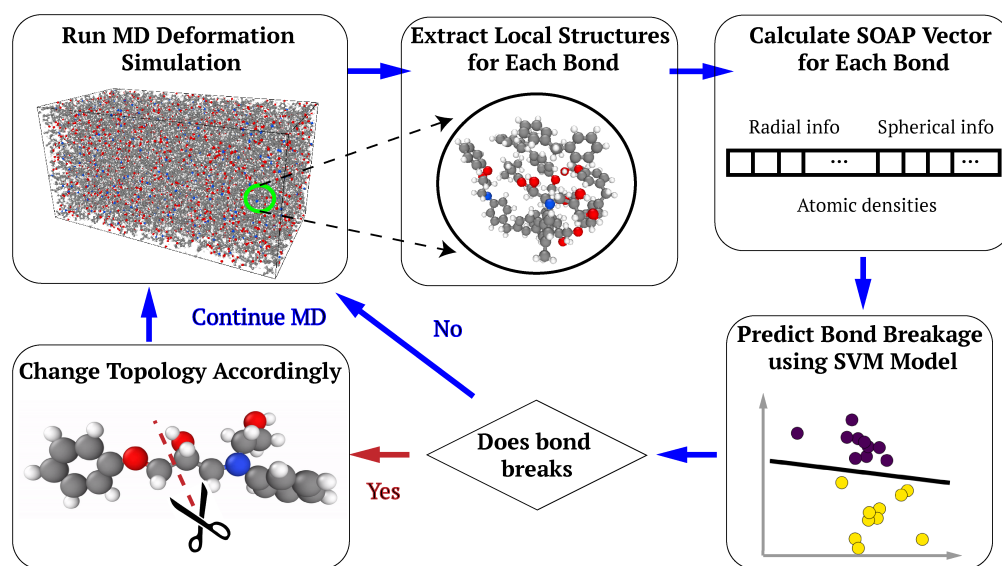


Figure 1: Schematic of the Machine-Learning-based Adaptable Bonding Topology (MLABT) method. MLABT can efficiently predict and perform bond breaking on-the-fly in MD simulations with near quantum-chemical accuracy.<sup>22</sup>

76 MLABT is a method incorporated on-the-fly with classical MD (e.g. OPLS, Amber) to accu-  
77 rately describe quantum-chemically accurate bond breaking at dramatically reduced cost, with a  
78 focus on the modeling of thermoset deformation and fracture.<sup>22</sup> As illustrated in Fig. 1, MLABT  
79 scans all potentially breakable bond types in the classical MD simulation and predicts bond rupture  
80 based on the local structures. If a bond breaks, the corresponding topology is automatically mod-  
81 ified and MD continues until the next bond breaks. We develop MLABT in an archetypal epoxy

82 polymer network, diglycidyl ether of bisphenol A (DGEBA) cured by methylene dianiline (MDA),  
83 but the approach is chemically generalizable.

84 We employ similar simulation parameters as described in our previous work.<sup>22</sup> Specifically, a  
85 cubic box containing 432 DGEBA and 216 MDA molecules (27,432 atoms in total) is utilized with  
86 periodic boundary conditions in three dimensions. Bonding topologies of networks are generated  
87 dynamically by simulating curing reactions in MD, resulting in degrees of crosslinking ranging  
88 from 77% to 98%. Structures are melted at 800 K for 200 ps and then quenched to 300 K with  
89 a constant annealing rate ranging from 0.1 K/ps to 100 K/ps. The obtained glassy structures are  
90 then used as initial conditions for MLABT deformation simulations. Only uniaxial deformations  
91 are considered in this work. During deformations, the simulation box is deformed every 1 ps at  
92 a strain rate of  $4 \times 10^9$ /s and the atomic coordinates are remapped accordingly. The two trans-  
93 verse directions are allowed to relax under  $P=1$  atm to avoid the accumulation of artificial stress.  
94 We apply the Optimized Potentials for Liquid Simulations All Atoms (OPLS-AA) force-field with  
95 the Large-scale Atomic/Molecular Massively Parallel Simulator (LAMMPS) in all MD simula-  
96 tions.<sup>27,28</sup> Simulated glass transition temperature, density, and elastic properties are all in good  
97 agreement with experiments and previous simulations.<sup>11,29–31</sup>

98 Central to MLABT is the ML model tasked with predicting bond breakages by analyzing the  
99 bond's instantaneous surroundings. To characterize the local structure, we employ the Smooth  
100 Overlap of Atomic Positions (SOAP) descriptor, representing a Gaussian smeared local atomic  
101 density based on spherical harmonics and radial basis functions.<sup>32–34</sup> We apply the support vector  
102 machine (SVM) with the radial basis function kernel as the classifier.<sup>35</sup> More details can be found  
103 in the reference.<sup>22</sup> Considering the additional cost of ML prediction that requires the computation  
104 of the SOAP vectors for all the relevant atoms, we perform the scanning of bond breaking every  
105 0.001 true strain. In our testing, as long as the evaluation frequency is greater than one check every  
106  $\Delta\varepsilon = 0.01$ , no evident difference is observed in the resultant deformation behavior, as illustrated  
107 in Fig. S3 of the Supporting Information. In addition, due to the instability of the structures with  
108 broken bonds simulated with OPLS-AA, a timestep of 0.25 fs is utilized in MLABT simulations.

109 Tuning force fields or adding hydrogens to broken bonds could solve this instability issue, but is  
110 not performed in the present study.

## 111 **Iterative MLABT-based active learning**

112 To improve the generalization ability of MLABT across the entire fracture process, the ML model  
113 in this work undergoes iterative refinement, enriched progressively by the incorporation of AL. AL  
114 is a data-driven methodology primarily aimed at optimizing the process of data labeling and model  
115 training.<sup>36</sup> Distinct from traditional ML frameworks, where a model is trained on a pre-labeled  
116 dataset, AL centers on the model actively selecting the most informative data points from a vast  
117 unlabeled pool of data.<sup>37,38</sup> Here, we harness the power of AL to elucidate the fracture behaviors  
118 of thermosets, minimizing costs of QM computations while maximizing predictive generalization  
119 ability at diverse deformation conditions.

120 The overall AL workflow is illustrated in Fig. 2. We start sampling highly strained configura-  
121 tions in MD simulations and extracting the local structures that potentially contain broken bonds  
122 for QM geometry optimization.<sup>22</sup> Data pre-screening requires an artificial threshold based either  
123 on bond length or stretching energy, which could limit the applicability of the ML model in early  
124 bond breaking prediction. To achieve a high fidelity model, we utilize the more accurate DFT  
125 method PBEh-3c that improves upon our previous work using the semi-empirical tight-binding  
126 method GFN2-xTB.<sup>22,39</sup> Due to the increased computational cost of PBEh-3c, our computational  
127 budget permitted generating a smaller initial training dataset, containing around 5,000 data points.  
128 The initial SVM model is fit using 80% of the data and applied to kickstart the AL campaign.

129 To include representative and diverse local structures during deformation into the model train-  
130 ing, we employ an iterative pool-based AL strategy, as illustrated in Fig. 2. In each AL iteration,  
131 we collect all inputs (SOAP vectors) of the potentially breakable bonds (around 4,000 bonds per  
132 frame) in all frames (around 1,250 frames per trajectory) of a MLABT trajectory, which is gener-  
133 ated based on the latest re-trained ML model, as an unlabeled data pool. Note that this step takes  
134 no additional computational cost since SOAP vectors of these bonds were already computed while

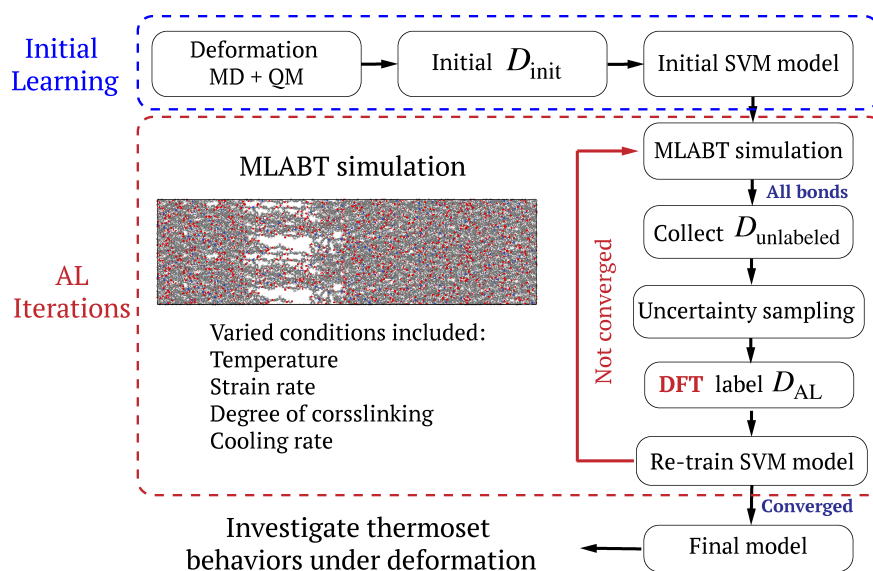


Figure 2: Workflow of the iterative active learning framework for MLABT.

135 performing MLABT simulations. By doing this, the unlabeled data pool in one iteration already  
 136 contains comprehensive information of in situ chemical bond local environments within a broad  
 137 range of strains throughout the thermoset fracture process. To further improve the model's gener-  
 138 alization ability, we introduce some variations in conditions of MLABT simulations during the AL  
 139 iterations. In the second iteration, we include simulations at various temperatures from 100 K to  
 140 400 K. In the third iteration, we include simulations starting from initial structures with different  
 141 bonding topologies. In the fourth iteration, we include simulations with different strain rates and  
 142 with initial structures in different degrees of crosslinking (78% to 98%). Over all iterations, around  
 143 85 million unlabeled data instances are collected cumulatively for AL querying.

#### 144 Active learning query strategy

145 To select the most informative data instances (local configurations) from the large pool of unlabeled  
 146 data for DFT labeling, we use uncertainty sampling, along with the SVM classifier. In the context  
 147 of SVM, uncertainty sampling can be intuitively understood by examining the decision function  
 148 for each prediction.<sup>40,41</sup> For a data point, the absolute value of the decision function  $|f(x)| =$   
 149  $|\sum_i^N \alpha_i \gamma_i \kappa(x_i, x) + b|$  represents its distance to the decision boundary, where  $\kappa(x_i, x) = \langle \phi(x_i) \phi(x) \rangle$

150 is a kernel function and  $\alpha_i \gamma_i \phi(x_i)$  forms a weight vector. The smaller this absolute value, the closer  
151 the data point is to the decision boundary, which indicates a higher level of uncertainty. Thus,  
152 querying data points with the smallest absolute decision functions maximizes the information gain,  
153 refining our model with each iteration.

154 However, an inherent challenge emerges when adopting this approach: as our model and data  
155 evolve across iterations, the absolute values of the decision function can shift, rendering them non-  
156 comparable across different AL cycles. This poses a problem when trying to maintain a consistent  
157 measure of uncertainty across multiple iterations. To circumvent this challenge, we employ Platt  
158 scaling—a method wherein a logistic regression model is trained using the decision function’s  
159 outputs.<sup>42</sup> Through this process, the SVM’s raw decision values are transformed into calibrated  
160 probabilities, providing a consistent measure of uncertainty irrespective of the active learning it-  
161 eration. Within our binary classification context  $P(1|x) = 1 - P(-1|x)$ , the uncertainty associated  
162 with each instance  $x$  (SOAP vectors) is defined as

$$u(x) = 1 - \max(P(1|x), P(-1|x)) = 0.5 - |P(1|x) - 0.5| \quad (1)$$

163 Under this formulation, data points with probabilities closer to 0.5 are deemed to have maximum  
164 uncertainty, as they lie in regions where the model is most uncertain about its classifications.

165 Using the outlined query strategy, bonds with maximum uncertainty are identified within each  
166 snapshot of the MLABT simulation. To regulate the number of bonds selected in each AL iter-  
167 ation, we apply an uncertainty threshold of 0.05. For every selected bond, its local environment  
168 is extracted from the large MD configuration. This isolated environment is then subjected to full  
169 optimization via DFT calculations, as in the initial dataset generation.<sup>43</sup> Each batch of labeled data  
170 from the AL is partitioned into a training set (comprising 80% of the data) and a testing set (ac-  
171 counting for the remaining 20%). Subsequently, the SVM model is retrained, incorporating both  
172 the initial dataset and the cumulative new AL training data. Test data are composed of both the  
173 initial data and the cumulative AL test data, as well as unseen data from a new MLABT trajectory



174 (with maximum uncertainty in every snapshot) based on the final model. Detailed results on the  
175 model convergence are presented in the subsequent section.

## 176 Results

### 177 Active learning performance

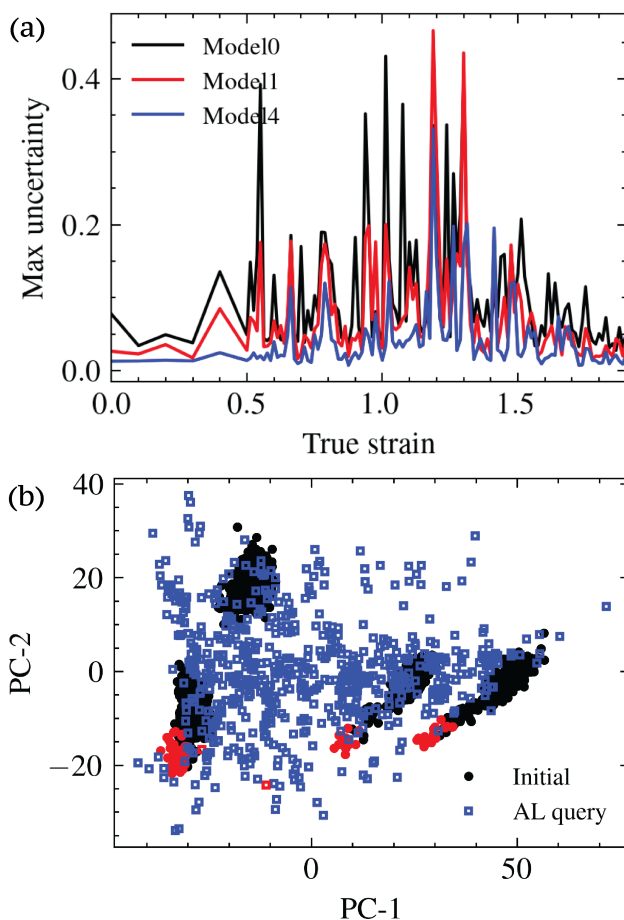


Figure 3: (a) Max uncertainty of bond breaking prediction in MLABT simulations after AL iterations. ‘Model 0’ denotes the model trained by the initial data, ‘Model 1’ and ‘Model 4’ denotes the updated models after the first and fourth AL iteration, respectively. (b) Initial data and AL data visualized by principle component analysis of the SOAP vectors. The red points represent bonds that are found broken in DFT calculations. The evident difference in data distributions demonstrates that AL explores diverse regions in feature space that are distinct from the initial sampling.

178 The AL framework in this work is based on the query strategy of uncertainty sampling, as detailed  
179 in the Methods section. Since bond breaking events are rare even in material fracture, the majority  
180 of bond breaking uncertainties are simply zero, even for the initial ML model with a small dataset,  
181 as shown in Fig. S1 of the Supporting Information. However, the maximum uncertainty during the  
182 deformation could be high if the bond instance lies closer to the poorly trained decision boundary.  
183 As shown in Fig. 3A, the initial model shows high peaks in uncertainty around strains of 0.5-  
184 0.6, where the bonds start to break, and around strain of 0.9-1.3, where the bonds break rapidly  
185 and the resulting stress reaches a maximum. The strain region in between has relatively lower  
186 uncertainty, because it is where the initial data are generated. The uncertainty for larger strains  
187 ( $>1.3$ ) decreases, due to weaker interaction between strained bonds in the system that is poorly  
188 crosslinked. Nevertheless, the bonds with maximum uncertainty above a threshold of 0.05 in each  
189 snapshot are selected, and their local configurations are optimized with DFT to determine bond  
190 breaking.

191 Next, we compare the local environments of the AL selected bonds with the bonds in the initial  
192 dataset, which are selected by bond stretching energy from configurations in a narrow range of  
193 strain, in the reduced dimensions by principle component analysis (PCA). The linear transforma-  
194 tion (coefficients) is constructed based on the SOAP vectors of the bonds in the initial dataset. As  
195 shown in Fig. 3B, the local environments in the initial dataset form four separated clusters. The  
196 right two clusters are associated with the ‘CT-CA’ bonds (connecting the  $sp^3$  carbon and the aro-  
197 matic carbon) located on both DGEBA and MDA, and the left two clusters are associated with the  
198 ‘CT-CT’ bonds on DGEBA. Note that only those ‘CT-CT’ bonds on the DGEBA backbone (the  
199 bottom left cluster) are breakable in deformation, while those on DGEBA side chains (the top left  
200 cluster) are not. We could remove those from training data, but in this work, they are kept to en-  
201 hance generalizability. On the other hand, the local environments selected by AL are scattered over  
202 the principal component space and distributed densely in regions between the clusters. This result  
203 demonstrates the ability of AL to explore the diverse feature space that is unseen in the initial data.  
204 As such, including these AL environments in the model training can improve the generalization

205 ability of MLABT for simulating thermoset deformations under diverse conditions.

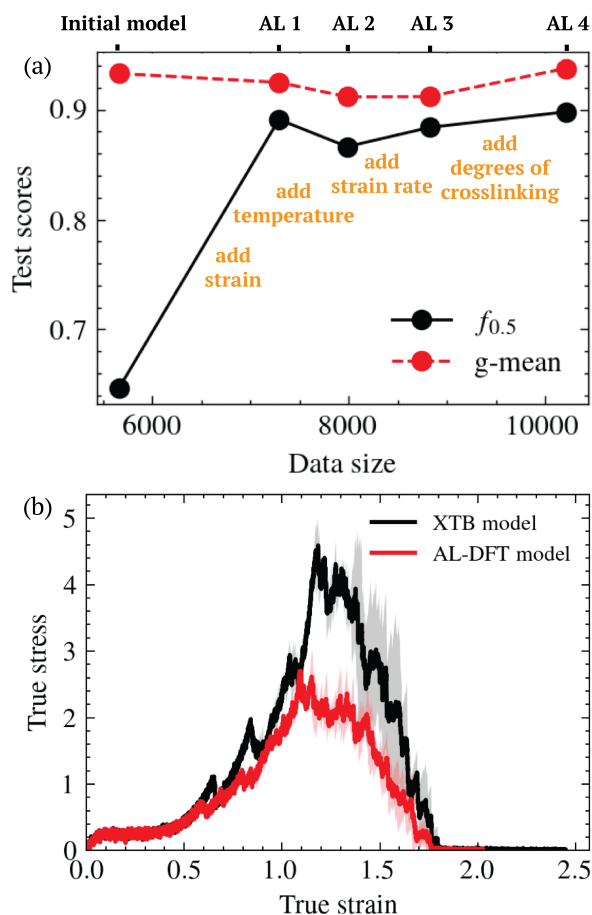


Figure 4: (a)  $f_{0.5}$  and geometric mean of the ML model as trained after each AL iteration. (b) Comparison of stress-strain curves simulated by AL-DFT MLABT model and with the xTB model at 300 K. The xTB model overestimates the ultimate stress, compared to the AL-DFT MLABT model and previous simulations.<sup>44</sup> The shadow regions represent the standard deviations induced by randomness in initial velocity generation over three independent trajectories (same for subsequent figures).

206 Figure 4A shows the performance of the ML model on the test set after each AL iteration. The  
207 selection of the scoring metrics considering the imbalanced classification was discussed in previous  
208 work.<sup>22,45</sup> It can be seen that the initial model exhibits an excellent geometry mean, whereas  $f_{0.5}$   
209 is relatively low, indicating a higher rate of false positives on regions outside of the initial training  
210 region. Once the model is updated with the AL selected data from the entire strain range using  
211 varied deformation and temperatures,  $f_{0.5}$  improves immediately while geometric mean remains  
212 almost unchanged. With more AL iterations including deformations using various strain rates

213 and configurations with various degrees of crosslinking, the performance of the model remains  
214 almost unchanged, whereas the maximum uncertainty decreases evidently (Fig. 3). After the  
215 fourth AL iteration, the maximum uncertainty is almost zero before the first bond breaking, and  
216 it remains above 0.15 only in a narrow strain range around 1.2. This performance is reflected  
217 in the distribution of prediction uncertainty, as shown in Fig. S1B and S1C of the Supporting  
218 Information. In addition, the number of bonds in the same deformation trajectory with uncertainty  
219 above 0.05 decreases with more AL iterations, but the rate of decrease slows after the second  
220 iteration, as shown in Fig. S2A of the Supporting Information. These features all suggest that the  
221 model in the AL framework is converging. To confirm the convergence, we apply the models after  
222 each iteration in MLABT simulations with identical initial conditions (positions, velocities). The  
223 results of the models after the second iterations are very similar, especially at  $\varepsilon < 1.5$ , as shown  
224 in the Fig. S2B of Supporting Information. As such, we end the AL campaign and employ the  
225 model after the fourth iteration as the final model (denoted as ‘AL-DFT’) in this work for further  
226 investigation.

227 MLABT simulations with the new AL-DFT MLABT model provide more accurate results on  
228 thermoset fracture than with the previously reported ‘xTB’ model. As shown in the stress-strain  
229 curves (SSC) in Fig. 4B, although the two models produce similar strains for the fracture initiation  
230 (the first bond breaking), the ultimate stress, and the material failure, the ultimate stress of AL-  
231 DFT MLABT is roughly one half of that of xTB, showing improved agreement with previous  
232 simulations (1-3 GPa).<sup>44</sup> This reduced ultimate stress is induced by an increase of broken bonds  
233 and already appears in the initial model, suggesting that the GFN2-xTB method compared to DFT  
234 underestimates the probability of bond breaking. In addition, we find that simple models only  
235 using bond length as the breakage criterion, as reported in earlier simulations,<sup>21,46</sup> delay early bond  
236 breaking events and fail to model the necking regime after the ultimate stress, as shown in Fig. S4  
237 of the Supporting Information. Furthermore, the shadow regions in Fig. 4B shows the standard  
238 deviation caused by randomness in velocity initialization, i.e., random seeds in generating initial  
239 atom velocities from the Maxwell–Boltzmann distribution. Although the specific broken bonds

240 and locations are different, the overall variance in the SSC during strain hardening is small. This  
241 suggests that there is some degeneracy in fracture initiation sites during thermoset deformation that  
242 result from velocity initialization, but they weakly affect the overall mechanical properties. The  
243 variation of ultimate stress and failure is stronger, probably due to the accumulated differences  
244 in bond breaking resulting in evident differences in the broken topology. We note that to our  
245 knowledge this study represents the first QM-informed atomistic study to report error bars in stress-  
246 strain curves of thermoset fracture, as for traditional approaches such error bars would be too  
247 computationally costly to compute.

248 **Bond breaking during deformation**

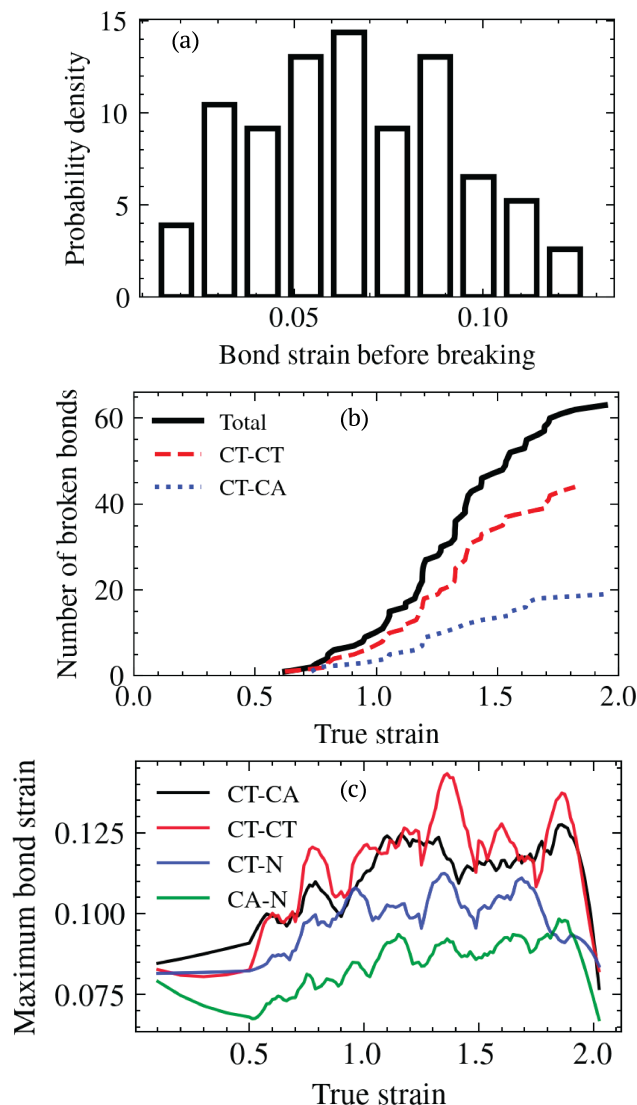


Figure 5: (a) Bond strain distribution immediately before bond breakage during MLABT simulations in the highly crosslinked system (98%) at 300 K with a strain rate of  $4 \times 10^9/s$ . (b) The numbers of broken bonds in the two dominant broken bond types as a function of strain. (c) The maximum bond strains for various bond types as a function of strain.

249 The more accurate AL-DFT MLABT model enables investigation of the bond breaking chemistry  
 250 during thermoset fracture. Figure 5A shows the distribution of bond strain, defined as  $(l - l_0)/l_0$ ,  
 251 where  $l$  is the instantaneous bond length and  $l_0$  is the equilibrium bond length, immediately before  
 252 bond breaking during MLABT simulations in the highly crosslinked system (98%) at 300 K with  
 253 a strain rate of  $4 \times 10^9/s$ . Similar results are observed at other conditions. It is surprising that the

254 bond breakages occur at much smaller bond strains than previously expected.<sup>47</sup> The maximum  
255 value around 0.12 is even smaller than the threshold value used in Barr's method for pre-screening  
256 local configurations that potentially contain broken bonds,<sup>21</sup> suggesting that the methods based on  
257 artificial criteria and QM calculations can delay bond breaking during deformation.

258 The actual types of broken bonds in MLABT simulations of thermoset fracture are found to  
259 align with those revealed in QM calculations. Note that although we observed two types of broken  
260 bonds in strained DGEBA+MDA by QM calculations (both DFT and xTB), it does not guarantee  
261 these two types are actually broken during thermoset fracture because the local environments with  
262 evolving topology could become very different. As shown in Fig. 5B, the numbers of broken bonds  
263 decomposed into the two types show a consistent ratio throughout the entire fracture process. This  
264 ratio, i.e., approximately 2:1 for 'CT-CT' and 'CT-CA', is in agreement with the observations in the  
265 DFT calculations. This suggests that the bond breaking mechanism in epoxy thermosets remains  
266 consistent during fracture, independent of global strain. Furthermore, because our ML model is  
267 designed for only predicting these two types, we need to evaluate the possibility of bond breaking  
268 in other bond types during fracture. Figure 5C illustrates the maximum bond strain for four types  
269 of potentially broken bonds in the entire MLABT simulation. The 'CT-CT' and 'CT-CA' bonds  
270 indeed exhibit the highest maximum bond strain, with 'CT-CT' frequently being slightly higher  
271 than 'CT-CA'. This is consistent with the fact that only these two types were broken and that 'CT-  
272 CT' bonds have a higher probability of rupture. The maximum bond strain of 'CT-N' or 'CA-N'  
273 are evidently lower and cannot exceed those of the two broken types in the entire fracture range,  
274 confirming that they cannot break and negligibly contribute to the ML bond breaking model.

## 275 **Fracture behaviors by MLABT**

276 Utilizing AL-DFT MLABT simulations, we can efficiently probe the fracture behaviors of poly-  
277 mer networks at the atomic scale, combining the molecular precision and computational efficiency  
278 of classical MD with bond-breaking fidelity approaching that of DFT. It is imperative to recognize,  
279 however, that both the lengthscale and timescale exert significant influence on the network topol-

280 ogy's formation and its dynamical response. We focus on extracting physical insights, specifically  
281 examining how the bond breaking events and fracture behaviors of polymer networks are modu-  
282 lated by factors such as temperature, strain rates, cooling rates, and the degree of crosslinking.

### 283 Temperature effect

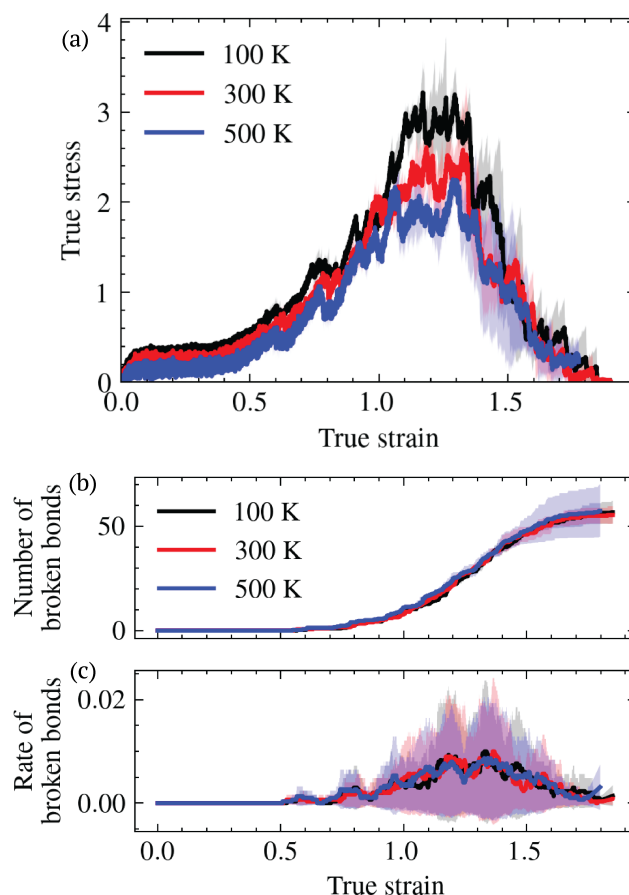


Figure 6: (a) Stress-strain curves of the same initial structure (98% crosslinked) simulated by AL-DFT MLABT at three temperatures with the same strain rate of  $4 \times 10^9$ /s. (b)-(c) Corresponding number (b) and rate (c) of the bond breaking events during deformation.

284 First, we assessed the impact of temperature, held constant during deformation, on the fracture  
285 behavior of thermosets. Figure 6 displays (a) the SSC, (b) the count of broken bonds, and (c) the  
286 rate of bond breakage (as deduced from the slope in (b)) at three distinct temperatures, 100 K, 300  
287 K, and 500 K, in MLABT simulations of a 98% crosslinked system subjected to a strain rate of  
288  $4 \times 10^9$ /s. These temperatures are all below the glass transition temperature ( $T_g \sim 541$  K). In gen-



289 eral, bond breaking events appear temperature-insensitive, with temperature only influencing the  
290 ultimate stress as a consequence of the temperature effect before yielding. Specifically, a decrease  
291 in temperature enhances the elastic modulus and the corresponding yield stress, in agreement with  
292 previous experiments and simulations.<sup>48</sup> However, the frequency of bond breakage events remain  
293 consistent in the plastic regime, and consequently, the characteristic strains for fracture initiation,  
294 peak stress, and ultimate failure also exhibit temperature independence. Only the stresses during  
295 strain softening and hardening vary as a result of the effect on the elastic regime, which was also  
296 observed in previous MD simulations without considering bond breaking.<sup>49</sup> These findings suggest  
297 that bond rupture in amorphous polymer networks may not be characterized as a simple activation  
298 reaction. The potential reason may be related to heterogeneous local stresses that arise depending  
299 on the global strain and the network topology.<sup>50,51</sup> Additional temperature-dependent behaviors in  
300 experiments, such as increased brittleness at lower temperatures,<sup>52</sup> could be attributed to factors  
301 like crystallinity, entanglements, or effects occurring over extended spatiotemporal scales.

302 Moreover, we find that the resultant stress is generally correlated with the bond breakage rate,  
303 a trend consistently observed across all conditions evaluated in this study. As the count of bonds  
304 on the edge of breaking surges during strain hardening, the cumulative stress also rises until the  
305 bond breakage rate peaks, resulting in the ultimate stress. Following this, as the bond breaking rate  
306 diminishes, so does the stress, until failure ensues. The total count of bonds required to rupture the  
307 thermoset is approximately 55, around 0.2% of the total bonds or 1.5% of the potentially breakable  
308 bond types in the system, which is notably smaller than the number of reactions needed for network  
309 gelation.

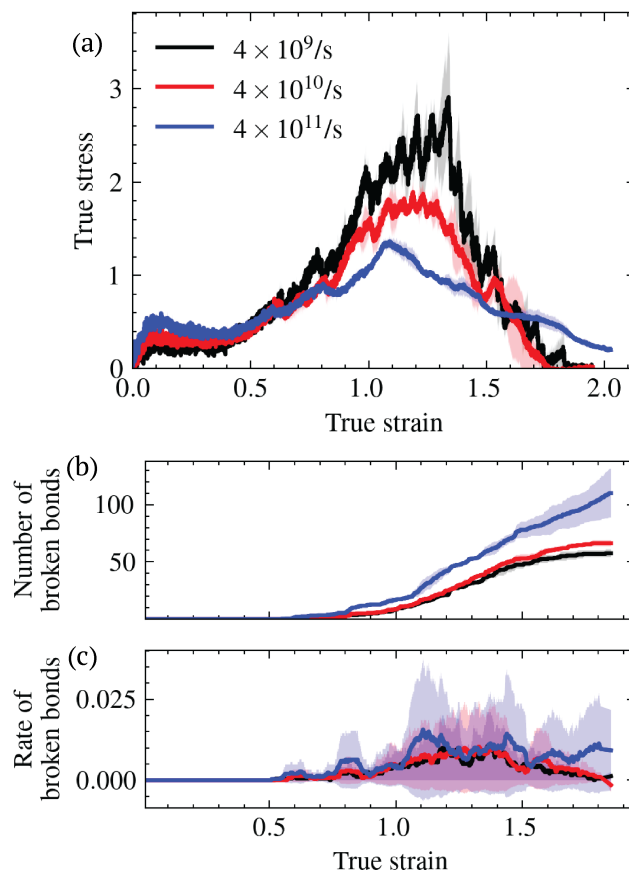


Figure 7: (a) Stress-strain curves of the same initial structure (98% crosslinked) simulated by MLABT with three strain rates at 300 K. (b)-(c) Corresponding number (b) and rate (c) of the bond breaking events during deformation.

311 Next, we investigate the effect of strain rate on the thermoset fracture behavior. As shown in Fig. 7,  
 312 distinct from temperature, strain rate not only strongly affects the elastic behavior but also plastic  
 313 and fracture behaviors. In the elastic regime, a larger strain rate results in higher elastic modulus  
 314 and yield stress (Fig 7A), in agreement with previous experiments and simulations.<sup>46,47,53–55</sup> Thus,  
 315 a more noticeable strain softening regime is observed at larger strain rates. More interestingly, the  
 316 bond breaking occurs more rapidly at higher strain rates, although the characteristic strains for  
 317 fracture initiation (first bond breaking) and ultimate stress are almost independent of strain rate,  
 318 as shown in Fig. 7B and C. Consequently, more bonds are broken in deformation with a large  
 319 strain rate and the resultant ultimate stress is evidently reduced. The reason for this result is that

320 at large strain rates with little stress release, bond breakages do not occur in the most productive  
321 way, i.e., breaking apart the network using as few cuts as possible. Hence, the system could  
322 remain connected even though a large number of bonds have broken, and as a result, the system  
323 exhibits reduced ultimate stress and behaves more ductile at large strain rates, as shown in Fig. 7A.  
324 Note that this effect might converge at low strain rates, as the stress is fully relaxed once a bond  
325 breaks when the associated timescale is closer to or even longer than the stress field propagation  
326 time, which is supported by the smaller difference in the effect when changing the strain rate from  
327  $4 \times 10^{10}/\text{s}$  to  $4 \times 10^9/\text{s}$ .

328 The MLABT results suggest a distinct disparity between effects of strain rate and temperature  
329 within the plastic regime, although the time-temperature superposition (TTS) is well-known for  
330 elucidating the viscoelastic behavior of polymers. To confirm this, we conduct three simulations  
331 with various strain rates and temperatures, in which the temperatures are specifically selected to  
332 neutralize the timescale difference induced by strain rates based on  $\alpha$  relaxation times computed  
333 from the self-intermediate scattering functions. As detailed in Fig. S6 of the Supporting Infor-  
334 mation, although the stress-strain curves are almost identical in the linear regime (excluding the  
335 yielding point) as expected from the TTS of elasticity, the bond breaking behaviors in the plastic  
336 regime are very different, suggesting that TTS is not obeyed in the plasticity of thermosets.

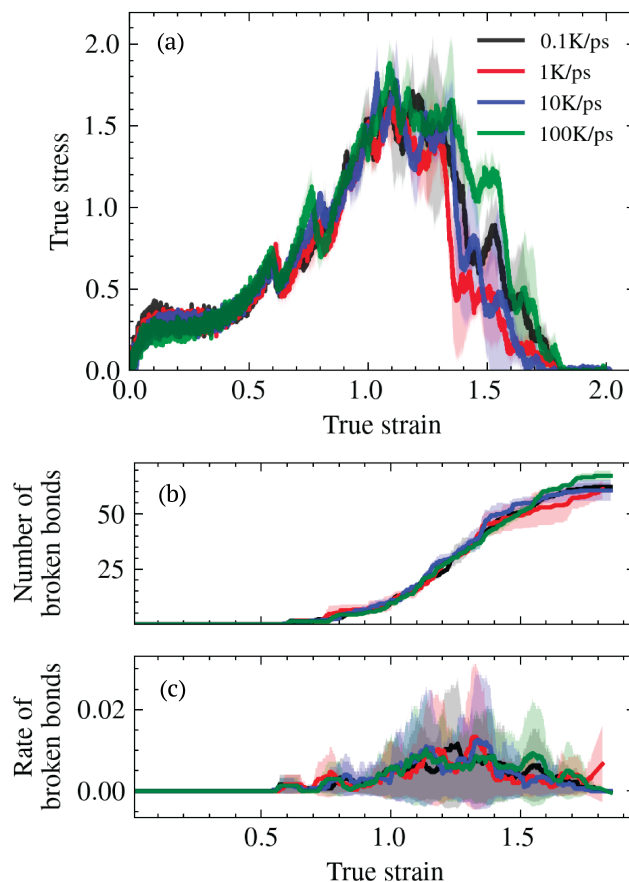


Figure 8: (a) Stress-strain curves of polymer networks with the same topology (98% crosslinked) but generated with different annealing (cooling) rates simulated by MLABT at 300 K and with a strain rate of  $4 \times 10^{10}$ /s. (b)-(c) Corresponding numbers and rates of the bond breaking events during deformation.

338 Furthermore, we study the effect of cooling rate in the melt-quenching process for synthesizing  
339 glassy thermosets on its bond breaking and fracture behavior by MLABT simulations. As glass  
340 is a non-equilibrium state below the glass transition, the cooling rate and the associated timescale  
341 for relaxation controls the temperature at which the supercooled liquid loses ergodicity and the  
342 amorphous structure becomes “frozen”.<sup>56</sup> Specifically, a smaller cooling rate results in a lower  
343 glass transition temperature, and thereby, a thermodynamically more stable glass state, i.e., a state  
344 located lower in the potential energy landscape. These more stable glasses show distinct atomic  
345 structures and materials properties compared to glasses with higher cooling rates, such as higher

346 density and higher mechanical strength.<sup>57,58</sup> Such a cooling rate effect is observed in the elastic  
347 regime of thermosets, as shown in Fig. 8A, as the elastic modulus and yield stress increase with  
348 reduced cooling rates (details summarized in Table S1 of the Supporting Information). Note that  
349 in the simulations, the initial structures have identical bonding topology but only are generated by  
350 different cooling rates in melt-quenching simulations initial configurations from 800 K to 300 K  
351 prior to deformation. Interestingly, the cooling rate effect does not survive in the plastic behaviors.  
352 As strain increases in the strain softening and the initial part of the strain hardening (till strain~0.6),  
353 the difference of stress induced in the elastic regime gradually disappears, suggesting that the  
354 effect of the initial glassy structures diminishes. Consequently, the following bond breaking effects  
355 and the fracture behavior are independent of the cooling rate, as shown in Fig. 8A-C. These  
356 observations can be understood by considering that the cooling rate in general determines the  
357 stability of initial glassy structures and therefore controls the elastic behavior (without structural  
358 change), however, as strain increases, the strain-induced structural modulation becomes dominant  
359 through the covalent bonded network, and the difference in the amorphous strained structures  
360 becomes negligible. We should also note that this limited cooling rate effect is an outcome of  
361 strong topological constraints of thermosets and the short length of strands used in the simulations.

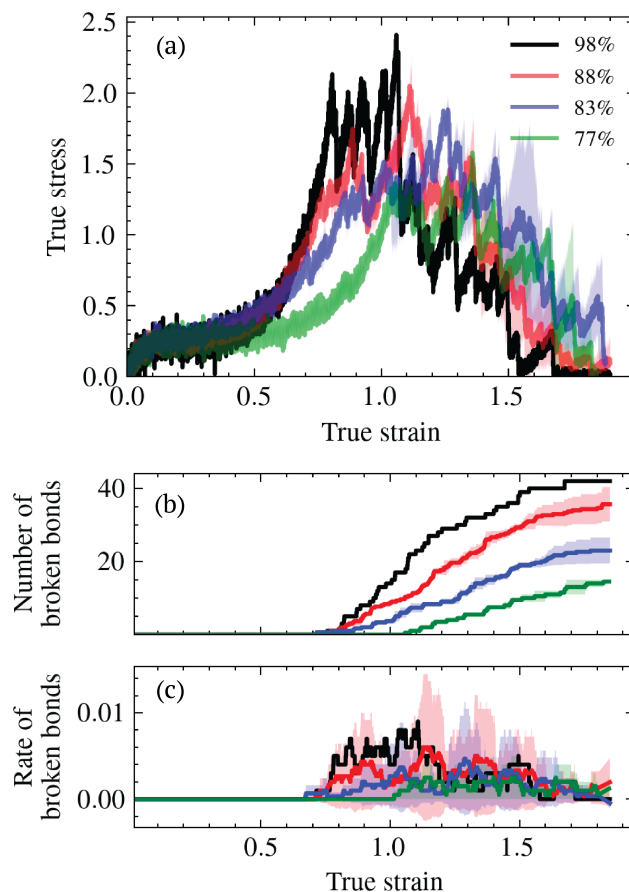


Figure 9: (a) Stress-strain curves simulated by MLABT for structures with different degrees of crosslinking at 300 K and with a strain rate of  $4 \times 10^9$ /s. (b)-(c) Corresponding numbers and rates of the bond breaking events during deformation.

363 Finally, we study how the degree of crosslinking affects bond breakage and fracture behavior of  
364 thermosets by MLABT simulations. In this work, the crosslinks are formed dynamically in MD  
365 simulations of curing reactions, and thus the degree of crosslinking is controlled by how long  
366 the curing process runs. As shown in Fig. 9, we prepare four structures with various degrees of  
367 crosslinking from 77% to 98% (all gels) and simulate their deformation responses with MLABT  
368 at 300 K with a strain rate of  $4 \times 10^9$ /s. Note that in this work, we do not provide statistically  
369 averaged results over various bonding topologies due to computational cost, however, the structures  
370 evaluated herein with the four degrees of crosslinking are generated from the same curing reaction  
371 in an effort to emphasize the influence of crosslinking degree.

372 In the system with a higher degree of crosslinking, while the elastic behaviors are subtly  
373 changed (due to smaller variations of crosslinking density<sup>59</sup>), the SSC in strain hardening in-  
374 creases more rapidly, and reaches the ultimate stress at a smaller strain value, as shown in Fig.  
375 9A. As the degree of crosslinking decreases, the ultimate stress shifts to a larger strain and the  
376 peak value decreases. Specifically, when the crosslinking degree decreases from 98% to 77%, the  
377 ultimate stress decreases by roughly 1/3 and the corresponding true strain increases by 1/3. This  
378 is generally consistent with results of previous simulations using ReaxFF.<sup>44</sup> This behavior of SSC  
379 can be understood from bond breakages in Fig. 9B and C. As expected, fewer bonds are broken in  
380 systems with lower crosslinking degrees, consistent with the lower ultimate stress values. More-  
381 over, the dominant bond breaking events, indicated by the maximum rate of bond breaking, occur  
382 at larger strains, accounting for the shift of ultimate strain. Depending on specific modification of  
383 bonding topology, the strain of fracture initiation might shift such that it is delayed to a larger strain  
384 at a crosslinking degree of 77%. We also note that although the effect of crosslinking degree is  
385 revealed here, the relationship between network fracture and network topology is intriguing yet  
386 more complex (the variance induced by topology at same degrees of crosslinking is illustrated in  
387 Fig. S4 of the Supporting Information), which warrants further investigation.

## 388 Discussion

389 The AL-DFT MLABT framework stands out as a promising approach for accurately modeling  
390 thermoset fracture, as bond breaking during fracture is performed at nearly quantum chemical  
391 accuracy while computational cost is kept similar to that of classical MD. Specifically, the AL  
392 modification of MLABT presents two distinct advantages: i) Integration of AL enables incorpora-  
393 tion of diverse training data across thermodynamic and configurational conditions, improving the  
394 transferability of models to new conditions. ii) By actively pinpointing the most informative data  
395 for training, the AL framework is roughly an order of magnitude more efficient in the generation  
396 of training data than our previous MLABT model. This heightened efficiency permits utilization

397 of more accurate (and computationally costly) QM methods, such as DFT.

398 Importantly, these two advantages of the AL-DFT MLABT framework manifest in the po-  
399 tential generalizability of the methodology across chemical space, an area where other reactive  
400 models (e.g. ReaxFF) can struggle. As MLABT leverages widely-accepted classical force-fields,  
401 such as OPLS and Amber, as its baseline simulation method, the high performance of common  
402 quantities such as density and low strain mechanical response is ensured across a broad chemical  
403 space. By adding on a QM-quality bond breaking prediction, mediated by ML, to these classical  
404 simulations, the MLABT approach is inherently adaptable to new chemistries for which accurate  
405 classical force-fields exist. Moreover, the ML component responsible for bond breaking is also  
406 inherently adaptable as it leverages structural representations (SOAP vectors) and is informed by  
407 QM calculations, making it agnostic to specific chemistries. This flexibility allows for the efficient  
408 adaptation of the MLABT framework to new chemistries, a process further streamlined by the AL  
409 approach introduced in this study. In contrast, empirical methods like ReaxFF demand a cumber-  
410 some and iterative parameterization process.<sup>60</sup> Transferability of the parameter sets in ReaxFF are  
411 a well-known (and expected) deficiency compared to classical FF as the prediction task required  
412 is more much challenging.<sup>61</sup> Provided these advantages, MLABT may be a suitable and easily  
413 implementable alternative to ReaxFF for unparameterized chemistries, especially when a trusted  
414 classical FF is already known.

415 As mentioned in the Methods section, a minor limitation of the current MLABT implementa-  
416 tion is the necessity for a small timestep (0.25 fs as opposed to 1 fs commonly used in standard MD  
417 simulations). This issue is primarily due to the instability introduced by broken bonds when using  
418 classical force fields. However, this drawback can be fixed in future developments of MLABT, ei-  
419 ther through optimizing the force fields or by appending hydrogens to atoms involved in the bond  
420 rupture. Importantly, the MLABT simulations conducted in this study did not employ these modi-  
421 fications, ensuring that our reported outcomes remain free from any influence of mechanoradicals  
422 that could otherwise alter network dynamics and subsequent bond breakages. The role of these  
423 mechanoradicals in subsequent bond breaking processes is a challenging topic reserved for future



424 works.

425 The computational efficiency of MLABT relative to other QM-informed bond-breaking ap-  
426 proaches also enables a number of crucial insights into the nature of fracture in epoxy thermosets.  
427 Specifically, we are able to simulate multiple replicas of our networks both in phase space and  
428 topology with DFT accuracy at minimal computational cost. From this added computational sam-  
429 pling, we observe that thermal fluctuations in the fracture process (as mediated by differing initial  
430 seeds in the velocity distribution) have a small impact on the resulting fracture process until the  
431 point of material failure. Although the exact bond breaking sites can differ due to randomness in  
432 the initial velocity distribution, the variations in the SSC and bond breaking are small during strain  
433 hardening. After the ultimate stress, these variations become larger due to accumulated topological  
434 differences.

435 Importantly, the MLABT results demonstrate that the polymer network topology plays a more  
436 important role in controlling fracture behavior than fine details of the polymer's glassy structure.  
437 Specifically, although the elastic mechanical properties depend on the cooling rate in the melt-  
438 quenching of thermosets, the plastic properties and bond breakages are independent of it (Fig. 8),  
439 suggesting that the influence of glassy structure blurs due to strain-induced rearrangement beyond  
440 the elastic regime. On the other hand, the degree of crosslinking (Fig. 9) and the topology varia-  
441 tion at the same degree (Fig. S4) primarily determine the fracture behavior, such as the ultimate  
442 strain/stress and the fraction of broken bonds. This again confirms the importance of topological  
443 perspective for understanding the fracture mechanisms of polymer networks.<sup>7,9,62</sup>

444 Lastly, our results show that time and temperature, the superposition of which is often posited  
445 to understand the viscoelastic behaviors of polymers, play different roles in the network fracture.  
446 Specifically, temperature does not affect bond breakages but slightly changes the resultant stress  
447 due to the local relaxation of glassy structures. However, the strain rate can strongly determine the  
448 strain-stress behavior by influencing the rate of bond breakages. At large strain rates, the strain-  
449 induced structural evolution can propagate faster than the release of stress via network topology  
450 immediately after bond scission. As a consequence, additional “unnecessary” bonds break, result-

451 ing in a more fragile network with lower ultimate stress. Note that although this physical scenario  
452 seems reasonable from the atomistic perspective, it cannot explain the general trend observed in  
453 experiments that a decrease in temperature or an increase in strain rate leads to more brittle frac-  
454 ture behaviors. This point is further related to the long-recognized anomaly of ductile fracture  
455 in molecular modeling of thermosets,<sup>63</sup> a phenomenon whose root cause is still under debate.<sup>64</sup>  
456 Given that the MLABT method already offers the QM-level accuracy in bond breaking, yet still  
457 demonstrates fragile fracture, and considering the revealed atomistic strain-rate effect is unlikely to  
458 contribute to a brittle fracture (when extrapolated at experimental strain rates), modeling at larger  
459 lengthscales is imperative to bridge the gap between experiments and simulations. One reasoning  
460 is that in typical simulation lengthscales, the crosslinking density ( $\sim 0.1$  mole/cm<sup>3</sup>) significantly  
461 exceeds the experimental values (0.001-0.01 mole/cm<sup>3</sup>).<sup>65,66</sup> This discrepancy hinders the forma-  
462 tion of polymer chain entanglements in current molecular dynamics simulations of thermosets.  
463 Such entanglements could potentially expedite the fracture towards the elastic regime and exhibit  
464 a distinct temperature dependence through chain reorganization.<sup>67-69</sup>

## 465 **Conclusion**

466 We have combined AL with MLABT to create a framework for the atomistic modeling of ther-  
467 moset fracture with DFT-accuracy and classical FF cost. This integration offers heightened pre-  
468 dictive accuracy across thermodynamic and configurational space while simultaneously improving  
469 efficiency during model training. Moreover, the adaptability of MLABT with AL enables re-  
470 searchers to explore polymer fracture across diverse chemistries, provided a suitable classical FF,  
471 avoiding the pitfalls of cumbersome parameterization in other reactive methods. We have applied  
472 the MLABT framework to understand the molecular determinants of fracture in polymer networks,  
473 finding that the network topology largely dictates fracture behaviors, while the intrinsic stability  
474 of the glassy structures has little influence. Interestingly, strain rate, rather than temperature, pre-  
475 dominantly impacts network fracture at atomic scale, deviating from conventional paradigms in

476 elasticity. Looking ahead, MLABT-based models of thermoset fracture form a potentially useful  
477 basis for the establishment of chemically generalizable bond-breaking models applicable to a di-  
478 verse set of polymer chemistries while leveraging the vast array of existing, and high-accuracy,  
479 classical force-fields.

## 480 **Supporting Information**

481 Uncertainty and convergence of the AL MLABT model, effect of MLABT bond scanning fre-  
482 quency on failure, comparison of MLABT with a simple model based on bond lengths, effect of  
483 network topology on fracture, time-temperature superposition in polymer network fracture.

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