1	ChemOS 2.0: an orchestration architecture for
2	chemical self-driving laboratories
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August 4, 2023

1 Abstract

Self-driving laboratories (SDLs), which combine automated experimental 2hardware with computational experiment planning, have emerged as powerful 3 tools for accelerating materials discovery. The intrinsic complexity created by 4 their multitude of components requires an effective orchestration platform to 5ensure the correct operation of diverse experimental setups. Existing orches-6 tration frameworks, however, are either tailored to specific setups or have not 7been implemented for real-world synthesis. To address these issues, we intro-8 duce ChemOS 2.0, an orchestration architecture that efficiently coordinates 9 communication, data exchange, and instruction management among modular 10 laboratory components. By treating the laboratory as an "operating system" 11 12 ChemOS 2.0 combines ab-initio calculations, experimental orchestration and statistical algorithms to guide closed-loop operations. To demonstrate its 13capabilities, we showcase ChemOS 2.0 in a case study focused on discovering 14organic laser molecules. The results confirm the ChemOS 2.0's provess in 15accelerating materials research and demonstrate its potential as a valuable 16 design for future SDL platforms. 17

1 **1** Introduction

2 Global humanitarian and ecological challenges have sparked an unprece-3 dented demand for novel functional materials across diverse industries, in-4 cluding clean energy technologies (renewable energy conversion and energy 5 storage) [1] as well as medicine and health care.[2] Motivated by the urgency 6 of these crises, researchers have realized the need to accelerate the often la-7 borious and empirical discovery process of designing, fabricating and testing 8 new materials.

Given this need, recent research efforts have shown remarkable progress in 9 automated experimentation for various steps of the materials discovery cycle, 10 including synthesis, formulation and device fabrication, functional characteri-11 zation, and computational simulations. Notable advances in this regard range 12from early examples of automated biomolecule synthesis, [3] flow chemistry 13and microfluidics for solution-phase synthesis [4, 5], high-throughput exper-14imentation for biological assays or reaction screening, [6, 7] to automated 15systems for fabricating solid-state or thin-film materials, [8, 9] as well as au-16 tomated computational tools [10–12] and the application of big data [13] for 17virtual screening. The merger of such automation platforms with advances 18 from "Artificial Intelligence" (AI) has given rise to the concept of "self-driving 19laboratories" (SDLs): the closed-loop integration of data-driven experiment 20planning with automated experiment execution. Such autonomous experi-21mentation systems have been successfully demonstrated to address diverse 22optimization problems in a sample-efficient (and thereby time-efficient) man-23ner, significantly reducing the required experimental resources. [14] While 24

early examples have mainly focused on reaction condition optimization, re cent SDLs have shown the potential to discover new materials compositions,
 e.g. for quantum dot synthesis,[15] thin-film devices,[8] nanoparticles [16] or
 solid-state materials.[17]

Whereas automated systems have enabled increased throughput and en-5hanced reproducibility compared to human experimentation, their flexibility 6 and reconfigurability has remained limited. Whilst this can be partly at-7tributed to the often human-centric hardware design, software integration 8 and the dynamic orchestration of automated workflows have remained a ma-9 jor challenge in automated laboratories. To address this challenge, a range 10 of software solutions such as ChemOS, [18] AresOS, [19] NIMS-OS, [20] among 11 others, [21–27] have been proposed for workflow management and hardware 12integration, with more ambitious approaches implementing complete frame-13works combining hardware and software, [28–30] and standardizing experi-14mental protocols.[31] However, existing frameworks overlook how researchers 15automate hardware, and do not provide flexible human-robotic integrations 16 or a proper universal framework. Moreover, current frameworks do not in-17corporate IoT breakthroughs like fog computing, which offer strong data 18 management and storage without relying on remote servers.[32, 33] Failing 19to embrace these cutting-edge technologies is a missed opportunity for op-20timizing SDL performance and making them more usable for experimental 21scientists. 22

Additionally, the lack of integration between experimental and computational simulations hampers the research capabilities of many laboratories by not incorporating theoretical insights provided by computations. An ideal orchestration framework should tackle all of aforementioned challenges to
 promote widespread adoption and continuous improvements of diverse kinds
 of SDLs.

Remarkably, the current state of the automated laboratory landscape 4 shows notable parallels to the early era of computer development in the 51950s and 1960s, where a multitude of specific devices, processing units, and 6workflows were developed with little flexibility and interoperability. Histori-7 cally, this has inspired the development of standardized, portable operating 8 systems (OS), which form the backbone of modern computer technology, 9 and have enabled the widespread adoption of computer systems. The UNIX 10 OS,[34] arguably the most prominent class of operating systems, are based on 11 three simple design concepts: (i) the development of small functional units 12for specific tasks, (ii) the robust inter-operation of these units and (iii) their 13 inter-communication through plain text streams.[35] 14

15Based on this UNIX philosophy, we propose ChemOS 2.0 (Figure 1), a versatile, adaptable and portable "Operating System" for automated lab-16 oratories, fostering a holistic approach to operate and orchestrate various 17experimental and computational units. In analogy to computational operat-18 ing systems, standardized plain-text communication protocols allow not only 19for the flexible integration of new software and hardware units, but enable the 20seamless interaction with human researchers. At the heart of our architec-21ture is the integration of a fog computing device, offering improved efficiency 22 and faster decision-making within the laboratory. Much like a traditional 23OS kernel, the fog computing device manages data, coordinates components, 24and empowers the lab to operate autonomously. We first describe the general 25



Figure 1: Features and capabilities of ChemOS 2.0: **a** web graphical interface to ease the user interaction, **b** package to assure full software reproducibility, **c** Bayesian optimizer platform for experimental planning, **d** DFT workflow manager connected to our high-performance computer cluster to orchestrate ab-initio DFT experiment, **e** SQL database server hosting both experimental and simulation databases and **f** Communication protocol to control laboratory instruments. **a,d-f** modules enable the communication layer with external agents.

architecture of ChemOS 2.0 along with its main design elements. Second, we
demonstrate the applicability of ChemOS 2.0 in our own laboratory, showcasing the full orchestration of a complex materials discovery workflow towards
novel gain materials for organic solid-state lasing devices.

5 2 Results

6 2.1 Software management

Meticulous control over the laboratory's software ecosystem is imperative 7 to enhance experimental reproducibility, increase transparency, and mitigate 8 production failures. As such, achieving complete transparency necessitates 9 10 stringent management of the software state within a laboratory with dependency conflicts due to incompatible software versions posing a well-recognized 11 challenge in this regard. [36] To address these concerns, the core design of 12ChemOS 2.0 incorporates an orchestration fog device that runs the necessary 13software layers for laboratory operations while keeping each of the laboratory 14 modular for streamlined integration. To ensure reproducibility, robustness, 15and seamless deployment, the fog orchestration platform is equipped with 16NixOS, a declarative package manager-based (Nix) operating system known 17 for its ability to provide precise control over system state and software ver-18 sions. [37] Nix provides precise control over the system state by enabling an 19accurate selection of software versions and dependencies. Defining local and 20global system states in NixOS revolves around the use of .nix files, contain-21 ing a declarative system state recipe. Researchers can use configuration files 22

to share digital experimental environments and deploy pre-configured oper-1 ating systems on different platforms. Thus, .nix files are pluggable modules, $\mathbf{2}$ whose addition or removal will change the state of the system. While some of 3 the code may be hardware-specific, these files serve as a foundation for build-4 ing unique SDL architectures. In our work, we have prepared a collection 5of .nix files containing the environmental state used for our experiments. 6 The configuration code and installation instructions can be found in the 7 ChemOS 2.0 repository.[38] 8

9 2.2 Data management

Ameliorating experimental reproducibility requires a proper data management plan involving the collection of experimental procedures, outcomes, and environment metadata from an SDL. Notably, we draw inspiration from the remarkable advancements in computational chemistry, where sophisticated data solutions have successfully ensured reproducibility in chemical simulations.[13, 39–43]

To streamline data management, our orchestration device is equipped 16with two independent relational databases: one for experimental, and an-17 other for simulation data. The first is designed to store information about 18 the laboratory state, including raw and processed data and metadata of the 19instruments, as well as the input and output of experimental processes. We 20implement this desired modularity in the database layout by defining key uni-21 versal sub-tables, device, job, and devicelog, and more specialized ones 2223 tailored to the needs of each instrument. This concise layout ensures max-

imum flexibility and a robust architecture for experimental data collection, 1 that is readily transferable to any SDL. A detailed layout of the experi- $\mathbf{2}$ mental database can be found in Note S1 and Figure S3. On the other 3 hand, the simulation database is managed by AiiDA, which provides a well-4 tested and robust design specifically tailored for simulation orchestration.[12] 5 These databases are not only used to keep track of all the data collected in 6 the laboratory, but they also serve as a broker to share data between differ-7 ent devices and software running in the laboratory. ChemOS 2.0's databases 8 can be easily exported and published into specialized databases to report 9 complete experimental information. As such, we gain a more comprehen-10sive snapshot of the laboratory, encompassing all instructions executed by 11 experimental devices and their corresponding metadata. 12

13 2.3 Device communication

Enabling seamless communication between hardware and applications is a 14crucial role of an operating system, particularly in the context of self-driving 15laboratories, where applications can be likened to chemical procedures with 16multiple steps. In ChemOS 2.0 the interaction between the system and hard-17 ware is facilitated through a core middleware software unit, operating on the 18terminals physically connected to the devices and the local network, as de-19picted in Figure 2 with the SiLA2 client/server standard managing the 20communications.^[27] In our implementation, the instruments themselves are 21 treated as SiLA2 servers, exposing all their valid actions to the local net-22work, while our orchestration device acts as a client capable of querying the 23



Figure 2: The self-driving lab is orchestrated using ChemOS 2.0, which leverages the SiLA2 client/server protocol to control laboratory devices. The client interacts with the servers on the network to access available actions. Each server operates as a daemon on the respective computer connected to the laboratory instrument. In our configuration, device-specific managers also run as daemons, providing a GUI for user interaction with the instrument. Communication between the SiLA2 servers and managers is facilitated through a computational socket, enabling command transmission via ChemOS 2.0 or the GUI. This setup empowers users to command various laboratory instruments: **a** *The Machine*, robotic organic synthesis platform [44], **b** Chemspeed platform, a robotic general synthesis platform, **c** an HPLC-MS module for characterization and **d** our custom-built automated optical characterization able to characterize lasing properties. Instruments **b-d** are physically connected, thus enabling direct transfer of materials.

devices to execute their operations. The SiLA2 package comes with a suite 1 of commands that generate, deploy and maintain the available actions of the $\mathbf{2}$ SiLA2 servers by defining XML files. Details of using SiLA2 in python can be 3 found in Note S2, and an example XML file can be found in Note S7. In 4 adherence with the third UNIX principle, job files to the SiLA2 servers are all 5in a human-readable json format for all of the instruments (See Note S15). 6The manager component often serves as a device driver, and often includes 7 highly abstracted code capable of executing complex actions. Commercial 8 solutions usually consist of graphical user interfaces (GUIs) tailored for indi-9 vidual operations and often lack an application programming interface (API) 10for direct communication. [45] Consequently, custom software modifications 11 are often required to exert control over these devices. The manager there-12fore provides a "workaround" for some instruments that are limited by their 13 provided user interfaces for automation, or a device driver for more bare-14bones/simplistic instruments. To bridge the communication gap between 15the (standardized) SiLA2 server and the (device-specific) manager, we im-16 plemented a socket server. Although the decoupling introduced by this con-17nection adds complexity to the code architecture, the socket communication 18 layer acts as a safeguard in case of a loss of connection during the execu-19tion of sensitive/hazardous operations. The socket layer also addresses the 20practical need for our researchers to sometimes operate instruments without 21ChemOS 2.0, and critically, ensure the continued operation of the instru-22ment in the event of a loss of connection between ChemOS 2.0 and the 23instrument. A deeper description of the SiLA2 server implementation and 24the socket server can be found in Notes S8, S9, S10 and Figures S1, S2, 25

S5, respectively. A code example of interacting with a SiLA2 server can be
 found in Note S11.

Lastly, we have successfully deployed the aforementioned middleware unit 3 in our experimental laboratory. Figure 2 illustrates our current setup, 4 which includes: (a) The Machine (Note S6): a robotic pump system ca-5pable of parallelized synthesis in solution, [44] (b) Chemspeed platform, an 6automated robotic framework for parallelized synthesis and characterization 7 workflows (Figure S3),[46] (c) a High-Performance Liquid Chromatogra-8 phy/Mass Spectrometetry (HPLC-MS) device (Note S4) for compound sep-9 aration and identification, and (d) the custom-built automated optical char-10 acterization: a flow setup for automated spectroscopy [47] (Note S5). The 11 available commands for each of the experimental units can be found in Ta-12bles S1-S5. To test the SiLA2 server before deployment, we used "simula-13 tion" versions of the workflow managers (Note S8), ensuring minimal inter-14ruptions of operations while the server is in development. The operations of 15each instrument are controlled by an independent computer connected to the 16 local network. The instruments of the laboratory can be used in-sequence or 17individually. 18

19 2.4 DFT integration

While experimental laboratories contribute significantly to scientific research, the forefront of chemical exploration relies on ab-initio simulations to attain profound insights into complex chemical processes. Many of these simulations, however, come with substantial computational demands and require



Figure 3: **a** building a 3D structure of the molecule from a SMILES string using Open Babel,[48] **b** searching for the lowest-energy conformer using the crest package,[49] **c** optimizing the ground state structure and calculating the corresponding Hessian of the lowest-energy conformer using the xTB-GFN2 semi-empirical Hamiltonian,[50] **d** evaluating the ground and excited state energies and gradient of both singlet and triplet states at the time-dependent DFT level using ORCA,[51] **e** determining the vibrationally coupled absorption and emission spectra using the vertical gradient approximation and **f** computing a proxy for lasing properties.[52]

specialized external computational facilities for execution. The need for sim ulations in chemical exploration to improve the quality and efficiency of re search makes it crucial to equip ChemOS 2.0 with a dedicated unit capable
 of handling such chemical simulations.

To tackle the computational challenges and ensure reproducibility, ChemOS 52.0 embraces the integration of the AiiDA software package[12]. AiiDA plays 6 a critical role in automating data transfers between the user's local envi-7 ronment and the high-performance supercomputing cluster. By utilizing the 8 SSH protocol, AiiDA submits calculations to a SLURM queue, retrieves out-9 puts, and stores the results in a centralized database. It also resolves relevant 10 dependencies between the different steps, helping to properly schedule their 11 execution. To ensure reproducibility, AiiDA stores the data and metadata 12for each step of the workflow in the simulation database and provides Python 13 bindings to ease the query. Additionally, AiiDA is prepared for distributed 14computing, enabling efficient utilization of computational resources. As a 15result, lightweight operations such as 3D molecular structure generation can 16 be performed locally, while computationally intensive tasks utilizing pack-17ages like ORCA [51] and xtb [50] can be executed on our high-performance 18 supercomputing cluster. 19

In this work, we leverage the capabilities of AiiDA to create a powerful DFT workflow for estimating the lasing performance of organic laser molecules. Taking a SMILES string as input, the AiiDA-enabled workchain efficiently executes the necessary calculations, monitors their status, and retrieves critical data related to the lasing performance. This data is subsequently used in a Bayesian optimization campaign, enabling researchers to make informed decisions and advance their chemical exploration efforts. The
workflow is depicted in Figure 3 and additional information can be found
in the Methods section.

4 2.5 Web interface

5 ChemOS 2.0 operates as a server-based system, primarily relying on usage via
6 command-line interactions. While this approach is well-suited for specialists,
7 it may not be the preferred method for chemists who are more accustomed
8 to graphical user interfaces (GUIs).

To facilitate the adoption of our system, we developed a user-friendly web 9 application interface, empowering any researcher to send experimental jobs 10 easily, monitor their progress, and analyze the resulting data. This layout is 11 12shown in **Figure S4**. The web application is built using the Streamlit package [53], is hosted on the orchestration device and includes a sidebar menu 13that enables toggling between the available devices of the laboratory. Once 14the user clicks into a tab, the web interface shows the actions of the device 15and the inputs needed for their execution. Users can then upload job files, 16visualize and download results, and control the Bayesian optimizer using the 17application. Workflows involving multiple steps need to be coded in Python 18 using scripts that send commands to the instruments and modules. More-19over, the SiLA2-type system offers a promising approach for implementing a 20no-code platform, enabling users to define workflows in a more user-friendly 21 22manner.

23

Overall, the introduction of this web application interface significantly



Figure 4: Web application for ChemOS 2.0. **a** sidebar for toggling between instruments/features. **b** job submission for the HPLC-MS. **c** data visualization of the HLPC-MS's job results.

simplifies the usability of our system and enhances its accessibility for researchers across diverse skill levels. In this work, we have implemented functionality for all the available hardware presented in **Subsection 2.3**. While a full-featured web interface would enhance the capability of ChemOS 2.0, its development would require substantial efforts from additional fields and is beyond the scope of this study.

7 2.6 Experimental planner

Experimental planners are the keystone of SDL prompting us to equip ChemOS 8 2.0 with Atlas, [54] a package for Bayesian optimization (BO) designed ex-9 plicitly for experimental sciences. Atlas is a general-purpose optimization 10 framework for expensive-to-evaluate black-box problems, capable of mixed-11 parameter and multi-objective optimization. Importantly, Atlas incorporates 12BO concepts particularly relevant to chemistry, such as a molecular kernel 13 function, [55] general experimental parameter optimization, [56] robust opti-14mization, [57] and asynchronous experimental execution. [58, 59] For more in-15formation, see Note S12 and the Ref. [54], where we show an additional 16closed-loop electrochemical campaign orchestrated by ChemOS 2.0. 17

18 2.7 Experimental campaign

To demonstrate a proof-of-concept of a fully closed loop of automated experiment planning and execution, we designed a multi-objective campaign for the synthesis of Bis[(N-carbazole)styryl]biphenyl (BSBCz) derivatives based on previous work.[47] The campaign goals are to simultaneously maximize the experimental gain cross section and the simulated lasing gain factor (produced via DFT simulations), involving BO-based experiment planning, automated synthesis, purification and functional characterization, as well as simultaneous computational simulation via the AiiDA module.

The search space of potential target molecules in this campaign is de-5fined by enumerating all products of a double Suzuki-Miyaura coupling be-6 tween the MIDA ester (MIDA = N-methlyiminodiacetic acid) of (E)-2-(4-7(N-Carbazoly)phenyl)-vinyl-1-boronic acid and 38 commercially available di-8 halides.[47] A detailed synthesis scheme can be found in **Figure S13**. This 9 space is navigated by Atlas using a gaussian process surrogate model [60] with 10 a Tanimoto similarity kernel function. [55] Initial recommendations were gen-11 erated by training the optimizer on two data points from the original work. 12The recommended target molecules are then synthesized and characterized 13 experimentally, while spectroscopic properties are simulated computation-14ally through the aforementioned workflow. We provide Atlas with the goal 15of maximizing both the simulated spectral gain factor (from the AiiDA work-16 flow), as well as the experimental gain cross section via an equally weighted 17expected hypervolume improvement acquisition function that jointly maxi-18 mizes all objectives. 19

20 2.8 Testing hardware functionality with *The Machine*

Before creating a fully closed-loop, we evaluated the experimental capabilities of our setup by performing human-in-the-loop orchestration test excluding an experimental planner or DFT simulations. The test involved the synthesis, characterization, and measurement of optical properties for a compound
 recommended by our experimental planner.

The synthesis was performed using *The Machine*. During the test, ChemOS 2.0 directed the synthesis of the suggested BSBCz derivative as recommended during the creation of the BO campaign by Atlas. The synthesis instructions were seamlessly communicated to *The Machine* through its SiLA2 server, and real-time data were logged in the experimental database.

Following synthesis, the crude reaction mixture was manually filtered and transferred to the HPLC-MS device for characterization. Purification (HPLC-MS) and spectroscopic characterization (custom-built automated optical characterization platform) were controlled by ChemOS 2.0 through SiLA2 commands. The desired product was successfully detected by HPLC-MS, and the purified product underwent downstream optical property analysis. All data produced during this test can be found in **Note S14**.

15 2.9 Building a closed-loop workflow with the Chem speed platform

17 Lastly, we deployed and executed a closed-loop workflow for the synthesis of 18 BSBCz derivatives. In addition to orchestrating the experimental component 19 of the campaign, we conducted DFT simulations parallel to satisfy the two 20 objectives required by the BO campaign **Subsection 2.6**. Details can be 21 found in **Note S16** and **Figure S16** For the closed loop case study, we used 22 Chemspeed to synthesize the BSBCz derivative. Creating the closed loop 23 encompassed sending the SiLA2 commands to the SiLA2 servers.



Figure 5: Results saved on ChemOS 2.0 for the synthesis of BSBCz derivatives. **a** First recommendation candidate made by the experimental planner. **b** Simulated fluorescence spectrum of BSBCz derivative produced by DFT workflows on ChemOS 2.0. **c** Logging information for organic synthesis on ChemSpeed. **d** Diode Array detector (DAD) chromatogram and **e** Extracted Ion Chromatogram (XIC) plots for the HPLCMS. **f** Time-Correlated Single Photon Counting and absorbance/fluorescence spectra of the custom-built automated optical characterization platform analysis. **a** Second recommendation made by the experimental planner based on the results of **b** and **f**. All results and raw data files are stored in the database during the execution of experiments.

The results and workflow are illustrated in Figure 5 showing the fol-1 lowing steps: (a) ChemOS 2.0 queries the Atlas Bayesian optimizer with $\mathbf{2}$ two literature-known "seed" observations and receives a recommendation for 3 which BSBCz derivative to synthesize. (b) Then, it instructs Chemspeed 4 to execute the synthesis. (c) When the reaction is complete, ChemOS 2.0 5sends the compounds to the HPLC-MS to detect the product in the crude 6mixture and transfers the purified BSBCz derivative to the custom-built au-7tomated optical characterization platform. (d) Finally, the optical character-8 ization platform measures sample fluorescence and absorbance spectra and 9 the emission lifetime to compute the gain cross section. (e) In parallel to 10the experimental loop, the computational job is sent to the AiiDA daemon 11 to obtain the simulated spectral gain factor. (f) The results from the two 12previous steps are used to re-train the Bayesian optimizer and query another 13 candidate. All logging information was stored in the databases using the 14database architecture described in **Subsection 2.2**. The experimental gain 15cross section value was estimated experimentally using fluorescence spectra, 16 relative quantum yields, and emission rates of the BSBCz derivatives using 17our automated optical characterization platform. Details of the calculation 18 can be found in previous work.[47] 19

In summary, ChemOS 2.0 was able to successfully orchestrate a full SDL loop, including manipulation of different instruments, an AI experiment planner, and stored all output data in an internal database.

1 **3** Discussion

We demonstrate that more general, transferable and multifaceted SDLs are
possible thanks to central lab orchestration. The modular nature of ChemOS
2.0 enables laboratories from different fields to configure it according to their
domain specific requirements.

Following the UNIX philosophy, ChemOS 2.0 acts an "operative system", 6 with tools and instruments working together to create workflows and present 7data in a human-readable format. Unlike monolithic designs in other orches-8 tration configurations, our approach reflects an operating system's design 9 philosophy, promoting flexibility and allowing users to easily modify layers 10 and incorporate new features into the setup, such as new instruments and ex-11 periment planners. The database design follows the same principles, allowing 12users to rapidly add new devices to automated workflows and data collection 13 schemes using a universal-specialized table scheme, as well as device-specific 14 additions. Thus, rather than building a framework specific to our setup, we 15have designed an architecture amenable to this experimental lab along with 16 a diverse set of laboratory settings. Moreover, by employing a central fog 17orchestration device as the core of our architecture, we ensure greater ro-18 bustness and adaptability, allowing an automated management of laboratory 19services and ensuring software reproducibility. 20

One of the remarkable advantages of our modular architecture is its support for flexible human/robot integration of automated tools. Instead of demanding a complete overhaul of laboratory layout and hardware, ChemOS 2.0 allows the automation of existing tools and minimally interrupts existing

workflows. A drastic transformation of existing labs is often impractical, 1 as it disrupts the research activity of academics and industry professionals. $\mathbf{2}$ This can discourage them from transitioning to digitization. ChemOS 2.0 3 has been designed with a hybrid integration in mind, allowing researchers 4 to gradually introduce automation into their workflows. Initially, the Nix 5configuration can be installed on a workstation in the laboratory and be 6 later expanded upon. Users can begin by integrating simpler devices, before 7 adding instruments one by one to their ChemOS 2.0 ecosystem. While test-8 ing connectivity between ChemOS 2.0 and the instrument servers, simulators 9 were used instead of the actual lab hardware. As such, the deployment of the 10SiLA2 servers and testing of the actual hardware was therefore minimized, 11 and regular operations of the laboratory were minimally interrupted. 12

Digitization, including the implementation of tools like ChemOS 2.0, rep-13 resent a considerable challenge for many laboratories, as it requires significant 14experience in the efficient use and integration of computational resources. We 15believe this creates the need for a new, emerging role in research laboratories: 16 a "digital manager", responsible for orchestration, workflow assembly, and the 17integration of new (digital) tools, which we believe will be crucial to the pro-18 liferation of self-driving laboratories. Moreover, while is a financial barrier 19for automating many laboratories, we remain optimistic for the future given 20that the cost of automated tools is steadily decreasing each year. [61] Follow-21ing digital managers and cost, another hurdle may be less straightforward to 22address: the API-type access to automated tools. To aid the proliferation 23of SDLs, manufacturers should comprehensive support for the automation of 24their hardware, and recognize that in doing so, they can actually encourage 25

1 more adoption of their products by academia, startups and industry.

 $\mathbf{2}$ Importantly, our work represents a prototype implementation of the discussed design principles, and leaves room for structural refinements and fur-3 ther software development. As self-driving laboratories become more preva-4 lent, the connection between orchestration devices will become a signifi-5cant consideration, presenting challenges related to scalability and cyber-6 7 security. Furthermore, the increasing complexity of laboratory environments will necessitate the development of more powerful and user-friendly inter-8 faces. Graphical interfaces and natural language processing, [62] enable users 9 to communicate with the laboratory and coupled with advanced data analy-10sis methods, will allow programming-averse users to leverage the features of 11 the ChemOS 2.0 platform effectively. 12

13 4 Conclusion

In conclusion, this work represents an advancement in promoting the adop-14tion of innovative digital tools by chemists in their laboratories. The inte-15gration of Bayesian optimization, experimental techniques, ab-initio simu-16lations, and data management within ChemOS 2.0 unifies automated labo-17ratories to conduct sophisticated workflows. Our hybrid approach not only 18 relies on experimental results but also incorporates in-depth sample analy-19sis through DFT calculations, enabling comprehensive data-driven research. 20The automation of data collection opens up exciting opportunities for ma-21 22chine learning and data science applications in chemistry, fueling accelerated research progress and discoveries. Looking ahead, we envision even greater 23

possibilities through enhanced communication and collaboration among multiple ChemOS 2.0 platforms, fostering seamless cooperation between different laboratories. ChemOS 2.0 lays a solid foundation for designing novel SDLs, making them more modular, robust and making their units transferable. This advancement supposes an step forward in the quest of revolutionize materials research through streamlined and efficient self-driving laboratories.

7 5 Methods

8 5.1 Experimental procedures

The synthesis of BSBCz derivatives was performed using the Chemspeed 9 10 SWING XL automated platform, available at the University of Toronto. For more details of the automation manager for the Chemspeed platform, see 11 Note S3. Automated Suzuki–Miyaura couplings were performed following 12the general slow-release conditions reported by Grzybowski, Burke and co-13workers.[44] Synthesis instructions were received from the SiLA2 client on 14 ChemOS 2.0. Reactions were performed in the ISYNTH reactor under a 15nitrogen atmosphere, established by five evacuate-backfill cycles. Reactants 16and reagents were transferred as stock solutions in 1,4-Dioxane or water, 17 respectively under a constant stream of nitrogen, using the 4-Needle liquid 18dispensing tool. The reaction mixture was heated to 100 °C under vortex 19stirring for 12 h. The reaction mixture was cooled down to room tempera-20ture for 1 h, and the crude reaction mixture was filtered over a short plug of 21 celite (using the Solid Phase Extraction module of the Chemspeed SWING 22

1 XL platform), eluting with tetrahydrofuran and collecting the eluate. Follow-2 ing communication with the HPLC-MS device through the respective SiLA2 3 client on ChemOS (details see below), the eluate is automatically injected 4 to the HPLC-MS using the on-deck injection valve equipped with a sample 5 loop.

6 5.1.1 Separation and identification in HPLC-MS

Analysis of crude reaction mixtures and product isolation was performed by 7 HPLC-MS on a ThermoFisher system, equipped with a Vanquish HPLC and 8 a QExactive mass spectrometer. Injection to the HPLC-MS system was real-9 ized through a 6-port injection value on the deck of the Chemspeed SWING 10 XL platform. Job submission and orchestration of operations between the 11 two devices was enabled by ChemOS 2.0. Upon submission of a job from 12ChemOS 2.0 to the HPLC-MS device, an HPLC-MS run is automatically 13 started. After the equilibration stage, ChemOS 2.0 can read the *ready* status 14from the HPLC-MS device, and commence the analyte transfer into the sam-15ple loop on the Chemspeed SWING XL. Data acquisition on the HPLC-MS 16device is started through an electronic trigger sent from the injection valve 17driver on the Chemspeed SWING XL, indicating the exact sample injec-18 tion time. Upon completion of the first analysis run, the target compounds 19are identified by matching peaks in the wavelength-averaged UV/vis chro-20matogram and their extracted ion chromatograms, respectively. The detailed 21workflow for peak identification is described in previous work.[47] All analysis 22 results are stored on ChemOS 2.0. In case of successful detection of the de-23sired reaction product, a second HPLC-MS run is initialized by ChemOS 2.0, 24

following the workflow detailed above. In this case, the fraction containing
the desired product is automatically collected using a downstream selection
valve, and is used for spectroscopic characterization (see below).

4 5.1.2 Custom-built automated optical characterization

The collected sample is automatically characterized in the spectroscopic 5workflow described in **Note S5**, orchestrated by ChemOS 2.0. Upon suc-6 cessful completion of the HPLC-MS run and automated fraction collection, 7 spectroscopic analysis can be initiated from ChemOS 2.0. On the custom-8 built device, the sample is transferred to different flow cuvettes using a sy-9 ringe pump. Steady-state absorption spectra are recorded using a white-10 light lamp (Ocian Insight DH-MINI) combined with a spectrometer (Ocean 11 Insight, QEPro XR). Steady-state emission spectra were recorded on the 12same spectrometer using a 365-nm solid-state LED (Thorlabs, M365FP1 13 with DC4100HUB) as the excitation source. Quantum yields were deter-14mined by integration of the emission spectrum, while simultaneously record-15ing the excitation transmission using a photodetector (Thorlabs, S120VC 16with PM100D). Quantum yields were referenced to a pre-measured sam-17ple of 4,4⁻-Bis[(N-carbazole)styryl]biphenyl ($\phi = 0.89$ in toluene).[63] Time-18 resolved emission spectra were recorded using time-correlated single-photon 19counting (TCSPC, PicoQuant TimeHarp 260 board) after excitation with 20a picosecond-pulsed laser (PicoQuant, LDH-D-C-375 with PL800-D), and 21the corresponding lifetimes were obtained by exponential fitting. Details 22 on the data analysis workflow are described in Ref. [47]. Upon completion 23of the analysis workflow, all analysis results are automatically stored on 24

1 ChemOS 2.0.

2 5.1.3 The Machine

The Machine consists of syringe pumps and selection values connected by 3 tubing and further to solution and reaction vials and N_2 supply. The atmo-4sphere handling was performed by inserting drawing gas from heal-space of 5vials solution consistently refilling N₂ and purge syringe connect to exhaust. 6 The automated ligand transfer was performed by washing the syringe with 7 desired solution by pumping from the source and dispensing to waste, fol-8 lowed by drawing a certain amount and dispensing to the destination vial. 9 Finally, flushing were required drawing N₂ and flushing tubing content to des-10 tination. Each hardware execution was recorded and streamed as standard 11 output. A final exit message was sent at the completion of the experiment. 12

13 5.2 Computational procedures

All SiLA2 servers were constructed using the Python implementation of the SiLA2 0.10.1 communication standard. The SiLA2 servers operate in a separate thread on the computers that control the driver for the instruments in the lab. Communication between the SiLA2 server and the instrument on the local computer is accomplished using either socket connections or via status folders and files. Meanwhile, all communication between the local instrument and other devices on the network is only done via the SiLA2 server.

21 ChemOS 2.0 uses NixOS 22.11 configuration files. Using this configura-22 tion file will produce an identical shell on any Linux device that has NixOS in-

stalled. The experimental database was constructed using SQLalchemy 1.4.41,[64] 1 and the simulation database was built by AiiDA.[12] Both databases use Post- $\mathbf{2}$ GreSQL 14.6 as the backend. Interaction with the database on ChemOS 2.0 3 is accomplished through the use of psycopg2 2.9.5.[65] All storage of data 4 in the database is done automatically through Python scripts executed on 5ChemOS 2.0. Connecting ChemOS 2.0 to the other devices (SiLA servers) 6 in the lab is easy and straightforward. One has to create a client Python 7 object and initialize it using the IP address and port of the targeted SiLA2 8 server. Afterwards, one can send any of the available commands to the SiLA2 9 server (the instrument), which are represented as methods of the SilaCLient 10 object. Calling a method of the client object returns a SiLA2 command in-11 stance. If a command is observable, it is possible to subscribe to the com-12mand and receive a stream of information as the command is executing. It is 13 through this mechanism that output data from the instruments is streamed 14to the Fog server. 15

Tracking the progress of experimental campaigns with Atlas 0.0.0 is ac-16 complished by using Olympus 0.0.1b0,[66] a benchmarking framework for 17Bayesian Optimization. Using Olympus' Campaign object, we can keep track 18 of the search space and previous observations over the course of the optimiza-19tion. To use the Atlas SiLA2 server The Olympus Campaign object is passed 20to the optimizer and ultimately to Atlas, which uses the observations at-21tribute of the Campaign as input for suggesting new parameters. Saving the 22 campaign state as a .pkl file is one way to track each successive step of the 23experiments. The Atlas SiLA2 server returns a parameter vector, which can 24then be added to the Campaign, and used to automate the next round of 25

1 experiments.

2 5.2.1 Density functional theory

Generation of molecular conformers was performed using crest 2.11.1.[49] 3 Semi-empirical geometry optimization and frequency calculations of S0 and 4T1 structures were performed at gfn2-xtb level of theory using xtb 6.4.1.[50] 5DFT geometry optimization and frequency calculations of S0 structure were 6 performed with ORCA 5.0.4 package, [51] at PBE0-D3/Def2-SV(P) level of 7 theory. TD-DFT single-point and gradient calculations were performed with 8 the ORCA 5.0.4 package, at PBE0-D3/Def2-SV(P) level of theory, with 9 Tamm-Dancoff approximation. The total electronic energies of S0, S1-S5 10 and T1-T5, and the gradients of S0, S1-S3 and T1-T3 were computed at the 11 DFT-optimized S0 structure. AiiDA 2.4.0 and AiiDA-shell 0.5.3 were used 12for workflow orchestration. [12, 67] 13

14 Data availability

As a showcase, the results of the DFT calculations have been uploaded toioChem-BD.[39, 68]

17 Code availability

All the code needed for this work can be found in our Gitlab repository.[38]
Tutorials can also be found to replicate the more generalizable parts of this
work.

1 Acknowledgements

This material is based upon work supported by the U.S. Department of En- $\mathbf{2}$ ergy, Office of Science, Subaward by University of Minnesota, Project title: 3 Development of Machine Learning and Molecular Simulation Approaches to 4 Accelerate the Discovery of Porous Materials for Energy-Relevant Applica-5tions under Award Number DE-SC0023454. A.A.-G. acknowledges support 6 from the Canada 150 Research Chairs Program as well as Anders G. Fröseth. 7Computations were performed on the Niagara supercomputer at the SciNet 8 HPC Consortium. SciNet is funded by: the Canada Foundation for Inno-9 vation; the Government of Malcolm Sim acknowledges tremendous support 10 from the Ontario Student Assistance Program's Ontario Graduate Scholar-11 12 ship; Ontario; Ontario Research Fund - Research Excellence; and the University of Toronto. 13

14 Author contributions

M. S., software, methodology, investigation, writing original draft. M. G. 15V., methodology, writing, conceptualization, architecture design. F. S.-K., 16preparation of experimental workflows, writing review & editing. H. H., 17preparation of simulation and experimental workflows. R. H., implementa-18 tion of the experiment planner, writing review & editing. S. M., conceptu-19alization, writing review & editing. S. P.-G., methodology, writing, concep-20tualization, supervision. A. A.-G., conceptualization, funding acquisition, 2122supervision, project. administration, writing review & editing.

1 Competing Interests Statement

2 The authors declare the following competing interests

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