Graph Neural Networks for Prediction of Fuel Ignition Quality

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Abstract

Prediction of combustion-related properties of (oxygenated) hydrocarbons is an important and challenging task for which quantitative structure-property relationship (QSPR) models are frequently employed. Recently, a machine learning method, graph neural networks (GNNs), has shown promising results for the prediction of structure-property relationships. GNNs utilize a graph representation of molecules, where atoms correspond to nodes and bonds to edges containing information about the molecular structure. More specifically, GNNs learn physico-chemical properties as a function of the molecular graph in a supervised learning setup using a backpropagation algorithm. This end-to-end learning approach eliminates the need for selection of molecular descriptors or structural groups, as it learns optimal fingerprints through graph convolutions and maps the fingerprints to the physico-chemical properties by deep learning. We develop GNN models for predicting three fuel ignition quality indicators, i.e., the derived cetane number (DCN), the research octane number (RON), and the motor octane number (MON), of oxygenated and non-oxygenated hydrocarbons. In light of limited experimental data in the order of hundreds, we propose a combination of multi-task learning, transfer learning, and ensemble learning. The results show competitive performance of the proposed GNN approach compared to state-of-the-art QSPR models making it a promising field for future research. The prediction tool is available via a web front-end at `www.avt.rwth-aachen.de/gnn`.

1 Introduction

The worldwide increase in CO_2 emissions and the depletion of fossil resources call for the development of renewable fuels. A wide range of non-oxygenated and oxygenated hydrocarbons derived from renewable resources such as biomass has been investigated as pure-component fuel or blend components for use in internal combustion engines.[1–7] To determine how suited a molecule is for a fuel application, combustion-related properties need to be evaluated. The cetane number (CN) or derived cetane number (DCN), the research octane number (RON), and the motor octane number (MON) are commonly employed to characterize the auto-ignition/knocking behavior of a particular fuel. Fuels with a high RON

(MON) exhibit low knocking tendency and are therefore suitable for spark-ignition (SI) engines, whereas fuels with a high (D)CN (approx. above 40) exhibit a short ignition delay which is required in compression-ignition (CI) engines.[4,8,9] Experimental RON, MON, and (D)CN values are available for a range of different fuel molecules,[10–12] however, for many interesting molecules such data is not readily available. For these molecules predictive models are required that enable rapid estimation of fuel ignition quality.[4,13]

In the past decades, several models have been developed to predict (D)CN[12–28] and RON/MON[12,16,29–32] of (oxygenated) hydrocarbons by utilizing quantitative structure-property relationship (QSPR) modeling. In QSPR, the modeling process can be broken down into two steps: First, QSPR models introduce molecular descriptors $\boldsymbol{D} = [d_1, d_2, ..., d_n]^T$ that depend on the structure of a molecule m. Second, a regression model $F(\boldsymbol{D}) : \boldsymbol{D} \mapsto \hat{p}$ is fitted that predicts a property $\hat{p}$ as a function of $\boldsymbol{D}$.[33] The regression model is either linear or nonlinear, depending on the QSPR. Group contribution methods[34–36] are a particular type of QSPR model where the molecular descriptors $\boldsymbol{D}$ are structural group counts, i.e., the number of occurrences of basic functional groups, e.g., methyl ($-CH_3-$) or methylene ($-CH_2-$), in a molecule m.

QSPR models for DCN, RON, and MON differ in the way they encode the molecular structure. Various descriptors have been used including structural group counts (e.g., in[12–14,21,29–32]), the number of aromatic bonds (e.g., in[13,27]), and topological indices, such as the Wiener Index[37] or branching indices (e.g., in[20,26,31]). Previous models have also used a variety of techniques for the regression step, e.g., linear or nonlinear regression,[13,14,21,26,29,30] or artificial neural networks (ANNs).[12,17–19,22,24,27,30–32] Development of QSPR models, however, highly depends on the choice of informative descriptors, a selection process that requires domain knowledge and intuition.

Deep learning allows to learn representations of data with multiple abstraction levels. This has shown remarkable success for end-to-end learning in various domains surpassing previously performed manual feature selection.[38] In particular, graph neural networks (GNNs)[39,40] have recently shown promising results for the prediction of structure-property relationships of molecules.[41–46] GNNs utilize graph representations of molecules, where atoms correspond to nodes and bonds correspond to edges. For each atom, its local environment is learned by graph convolutions. These atom environments are then combined into a molecular fingerprint by applying pooling functions.[47] Finally, an ANN maps the fingerprint to the molecular property of interest. Since the graph convolutions and pooling functions are differentiable, the full model can be trained with the back-propagation algorithm. In contrast to QSPRs, the processes of choosing molecular descriptors and performing property regression are thus merged into a simultaneous training step. This enables supervised end-to-end training from the molecular graph to the property. In particular, the molecular fingerprints adapt during training and learn molecular structure information that is important for the property of interest.

We propose the first GNN model for the prediction of DCN, RON, and MON. The model is trained on literature data and is applicable to a wide range of oxygenated and non-oxygenated hydrocarbons. The GNN architecture includes state-of-the-art higher-order molecular graph features[46] and is provided open-source.[48] Furthermore, we provide a web front-end that can be easily accessed online to make predictions. The web front-end takes SMILES strings as input and automatically predicts DCN, RON, and MON (`www.avt.rwth-aachen.de/gnn`).

One of the main challenges in GNN training in the context of fuel ignition quality is the limited availability of training data. To mitigate this issue, we propose three model extensions that reduce data requirements while achieving competitive prediction accuracy: First, we propose a multi-task learning approach where DCN, RON, and MON are trained jointly. This approach shares the graph convolutions and the molecular fingerprint among all prediction tasks and thus takes advantage of correlations

between DCN, RON, and MON data sets. Second, we perform a transfer learning approach that utilizes a broader data set from different (D)CN measurement techniques for pretraining of our final model. Third, we perform ensemble learning averaging out random model variations.

The remainder of this paper is structured as follows: In Section 2, we provide a general background on graph representations of molecules and GNNs. Then, we briefly describe the databases of this work in Section 3. Afterwards, we propose the GNN architecture in Section 4. Furthermore, we briefly describe the considered learning methods: multi-task learning, transfer learning, and ensemble learning. In Section 5, we present the results, discuss the different learning methods, and compare our GNN model to state-of-the-art QSPR models. Finally, we conclude our findings and show potentials for future research (Section 6).

2 Fundamentals of graph neural networks

In this section, we present a brief background on graph representations for molecules and GNNs. Furthermore, we introduce the concept of higher-order GNNs that is fundamental to our modeling approach.

2.1 Molecular graphs

Any molecule can be represented as a molecular graph where nodes $w, v \in V$ correspond to atoms. Edges $e_{vw} \in E$ correspond to bonds between two atoms.[49,50] Furthermore, a feature vector is assigned to each node and each edge that includes information about atom types, e.g., C atom, and bond types, e.g., double bond. The node feature vectors $\boldsymbol{f}^V(v)$ can contain additional atom information such as orbital hybridization. To reduce the size of molecular graphs, hydrogen atoms can be implicitly included in the feature vectors of nodes of heavy atoms by using a hydrogen count, resulting in an H-depleted molecular graph.[51] Similarly, bond feature vectors $\boldsymbol{f}^E(e_{vw})$ can provide additional information, e.g., on ring structures. GNNs operate on graph structures, i.e., they take the molecular graph and its feature vectors as inputs.

2.2 Graph neural networks

As illustrated in Figure 1, GNNs have two main phases: (i) the message passing phase and (ii) the readout phase.[43] In the message-passing phase, graph convolutional layers are commonly applied with a large variety of layer structures existing.[41,43,47,52,53]

Figure 2 illustrates the basic concept of graph convolutional layers. The overall goal of the graph convolutional layer is to combine node information of a considered node (here #2 in red) with node information of its neighbors (here #1,3,4 in yellow) and bond information (green). To this end, node state vectors and edge state vectors are combined through message and update functions as explained in more detail in the following. The result of the graph convolutional layer is an updated node state vector of the considered node.

Within a graph convolutional layer, information about a node's neighborhood $N(v) = \{w \mid e_{vw} \in E, w \neq v\}$ is aggregated and passed to the respective node.[43] The message $\boldsymbol{m}_v^l$ is passed along edges to a node by applying a message function $\boldsymbol{M}_l$, i.e.,

$$\boldsymbol{m}_v^l = \sum_{w \in N(v)} \boldsymbol{M}_l \left(\boldsymbol{h}_w^{l-1}, \boldsymbol{f}^E(e_{vw}) \right) ,$$

where $\boldsymbol{h}_w^{l-1}$ denotes the hidden state of a neighbor in layer $l-1$. The 0-th hidden state vector is initialized with the input feature vector of a node, i.e., $\boldsymbol{h}_v^0 = \boldsymbol{f}^V(v)$. The message function $\boldsymbol{M}_l$ depends on the previous hidden states of the neighbors $\boldsymbol{h}_w^{l-1}$ and the features of the respective edges $\boldsymbol{f}^E(e_{vw})$, with the dimension of the hidden state vector for layers $l > 0$ being a hyperparameter. The hidden state of the considered node $\boldsymbol{h}_v^{l-1}$ is then updated to $\boldsymbol{h}_v^l$ by an update function $\boldsymbol{U}_l$ that combines its hidden state from the previous layer with the received message containing information of its

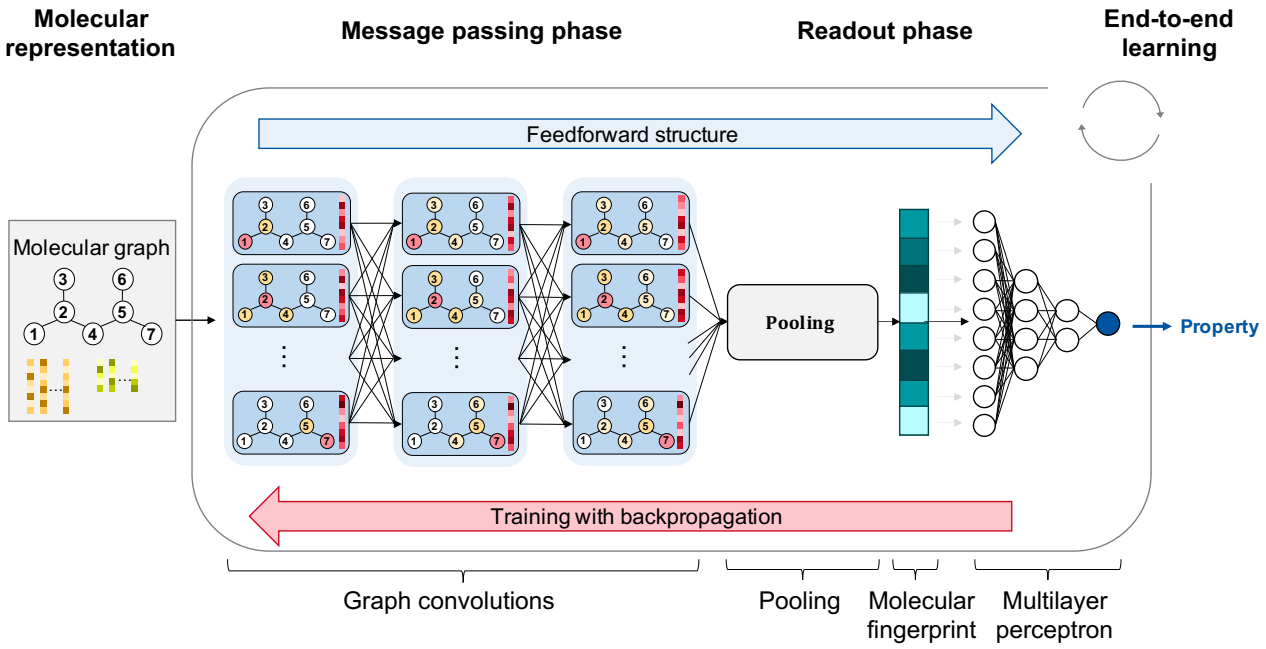


Figure 1: Overview of a graph neural network model for property prediction.

neighbors:

$$\boldsymbol{h}_v^l = \boldsymbol{U}_l\left(\boldsymbol{h}_v^{l-1}, \boldsymbol{m}_v^l\right)$$

The message passing and updating is repeated for a fixed number of iterations which results in multiple graph convolutional layers $l \in \{1, 2, ..., L\}$. After L graph convolutions, the hidden states of nodes $\boldsymbol{h}_v^L$ contain local information of environments with a radius of L nodes.

In the readout phase, the hidden node states of the last convolutional layer are combined into a graph representation vector $\boldsymbol{h}_G$, i.e., molecular fingerprint, by using a pooling function $\boldsymbol{h}_G = \boldsymbol{p}(\boldsymbol{h}_1^L, \boldsymbol{h}_2^L, ..., \boldsymbol{h}_{|v|}^L)$ where $\boldsymbol{p}$ is commonly chosen as the mean, sum, or max function.[52] Finally, the molecular fingerprint vector $\boldsymbol{h}_G$ is utilized for regression of molecular properties of interest, e.g., using a multilayer perceptron (MLP), i.e., $\hat{p} = \mathrm{MLP}(\boldsymbol{h}_G)$.

A strong advantage of this method is that all functions from the molecular graph to the property are explicit and differentiable allowing for supervised training using backpropagation. This enables end-to-end learning of GNNs, whereby the graph convolutions and the molecular fingerprint adapt during training to extract information of the molecular graph that is relevant for the property to be predicted.[41,43,54]

2.3 Higher-order graph neural networks

Morris et al. have recently extended the message passing to higher-order graph features.[46] Here, the message passing step does not only apply to the initial molecular graph but also to modified higher-dimensional molecular graphs. For these higher-dimensional graphs, the nodes are k-dimensional subsets s of the nodes in the initial graph, $s = \{v_1, ..., v_k\} \in [V]^k = \{U \subseteq V \mid |U| = k\}$ for $k > 1$. Hence, any combination of k nodes from the original graph (atoms in the molecular graph) are combined in a separate node.

The neighborhood of a k-dimensional node s is defined as $N(s) = \{t \in [V]^k \mid |s \cap t| = k - 1\}$ for $k > 1$. This means that two k-dimensional nodes s and t with k atoms each are adjacent to each other if the cut set of the two nodes consists of $k - 1$ atoms. This concept of higher-order neighborhood is illustrated in Figure 3, where we consider a red node and its yellow neighbor in the initial molecular graph (1-GNN) as well as higher-order graphs.

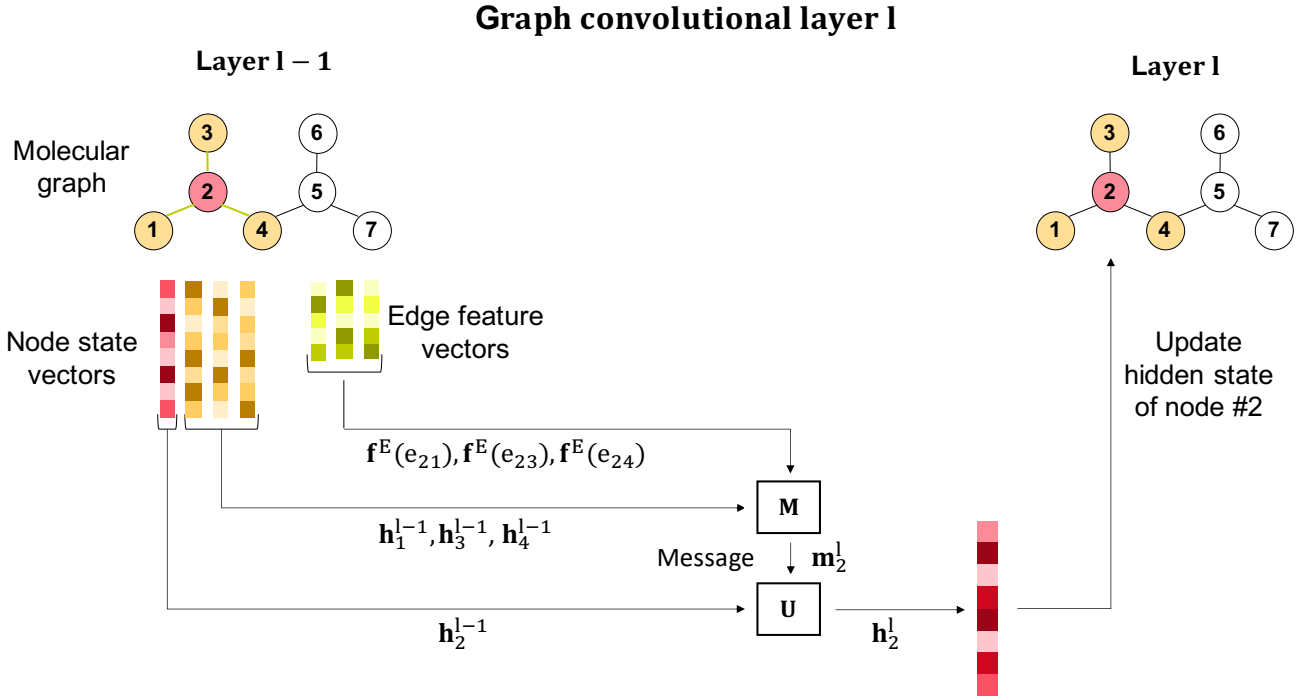


Figure 2: Illustration of a graph convolutional layer. We consider the update of the node state vector of the considered atom (#2 in red). The atom information is given as node state vectors of considered node and its neighbors (#1, 3, 4 in yellow). Furthermore, bond information is given as edge feature vectors (green). The message function $\boldsymbol{M}$ generates the message and the update function $\boldsymbol{U}$ computes the update for new state vector of the considered node.

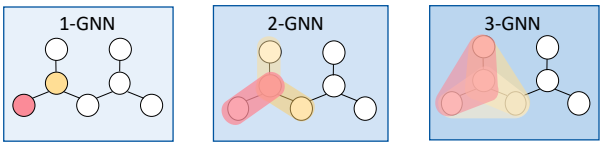


Figure 3: Illustration of the neighborhood in k-dimensional graphs. We highlight the yellow neighbors of a red node.

The message passing phase for the initial molecular graph is referred to as 1-GNN. The message passing phase for higher-dimensional graphs with nodes consisting of k nodes from the original graphs, the structure is called k-GNN.[46] When considering k-dimensional nodes, the initializations of the hidden node states cannot simply be atom types and features, but rather must be combinations of the respective individual atom types and features. At first, the initialization of the hidden node state of a k-dimensional node s contains the isomorphic type $\boldsymbol{f}_{\text{iso}}(s)$.[46] For example, the initial H-depleted molecular graph ($k = 1$) of oxygenated hydrocarbons, the isomorphic type of the node v corresponds to the atom type {{C},{O}} and is included in the initial feature vector of a node. For the 2-GNN ($k = 2$) of such hydrocarbons, the isomorphic type of the set $s = \{v_1, v_2\}$ corresponds to the 2-set of atom types: {{C,C},{C,O},{O,O}}.

Furthermore, the k-GNN model usually works in a hierarchical manner such that the outputs of the (k-1)-th GNN serve as inputs for the k-th GNN.[46] Therefore, in addition to the isomorphic type, the respective hidden node states of the last graph convolutional layer L of the preceding GNN are combined by a pooling function, e.g., mean function, and used for initializing the hidden state of a k-dimensional node. Note that this does not refer to the pooling of the molecular fingerprints in the readout phase. Hence for the 2-GNN, the hidden node states of a subset $s = \{v_1, v_2\}$ are initialized with the concatenation ($\|$) of the isomorphic type and the averaged hidden node states of

the two respective nodes from the 1-GNN, i.e., $\boldsymbol{h}_s^{2,0} = \boldsymbol{f}_{\text{iso}}(s) \parallel \text{mean}(\boldsymbol{h}_{v_1}^L, \boldsymbol{h}_{v_2}^L)$.

3 Data basis for fuel ignition quality

We collect DCN, RON, and MON data of non-oxygenated and oxygenated hydrocarbons from different literature sources. The number of species per molecular class and fuel ignition quality indicator is shown in Table 1. Note that we provide our full data set in the Supporting Information (SI).

The cetane number (CN), an indicator for CI fuel quality, is determined in a cooperative fuel research (CFR) reference engine.[55] In comparison to the CFR engine, testing methods in a variety of constant-volume combustion chambers (CVCCs) require lower fuel quantities and shorter measurement times, but yield so-called derived cetane numbers (DCNs)[11] instead of true CFR CN. Our objective is to predict DCN values determined by a particular CVCC-based experimental setup, i.e., the ignition quality tester (IQT) which is standardized by the ASTM D6980[56] and widely used to assess diesel fuel ignition quality.[13,57] To this end, we consider IQT-DCN data from the Compendium of Experimental Cetane Numbers provided by Yanowitz et al.[11] for 236 different species.

Although (D)CN values from non-IQT experiments cannot be expected to closely match IQT-DCN,[13] we utilize such data for a transfer learning approach. Specifically, we consider (D)CN values for 479 species from various measurement setups from the Compendium of Experimental Cetane Numbers.[11] We exclude the test set compounds, use the remaining 447 molecules for pre-training, and subsequently refine the resulting model based on IQT-only data. We provide the different data sets created for model development online.[48]

RON and MON are used to quantify the knocking tendency of a fuel and are suitable ignition quality indicators for SI engines. They are measured according to the ASTM D2699[58] and ASTM D2700[59] standards, respectively. As a database for our model, we take RON (MON) values for 335 (318) species from literature.[2,10,12,32,60–67] For all reported data (RON, MON, DCN), we take average values whenever multiple values have been reported for a single species.

4 Modeling approach

In this section, the GNN model development is described (cf. Figure 4). First, the workflow of the molecular representation is explained in Section 4.1. Then, the basic architecture of the GNN model is outlined in Section 4.2. Finally, the model extensions for multi-task learning (Section 4.3), transfer learning (Section 4.4), and ensemble learning (Section 4.5) are described.

We use PyTorch Geometric,[68] an open-source library for deep learning on graphs in Python. The implementation is adapted from our previous work on k-GNNs.[46] Our open-source code for training as well as the trained models can be retrieved on.[48] Additionally, for more convenient use, the model can be accessed freely via a web front-end (`www.avt.rwth-aachen.de/gnn`) to make predictions.

4.1 Molecular representation

For generating the representation of molecules that serve as an input to the GNN, SMILES strings[69] are transformed into molecular graphs. Each node and each edge is assigned a feature vector. The features are selected according to previous literature[41,43,44] and are shown in Table 2 and 3 for nodes and edges, respectively. Each feature is represented as a one-hot encoder with the size of the number of possible values for this feature and a single entry with value one at the index corresponding to the value of the feature. Furthermore, RDKit[70] is used for SMILES strings transformation and calculation of features.

Table 1: Data basis assembled for this work: Number of species per molecular class and fuel ignition quality indicator.

	IQT-DCN	**(D)CN**	**RON**	**MON**
n-alkanes	9	18	7	7
iso-alkanes	17	39	43	42
cycloalkanes	20	34	74	65
alkenes	15	33	87	84
cycloalkenes	10	12	22	22
alkynes	1	1	8	4
aromatics	13	63	41	43
alcohols	22	39	14	13
cyclic alcohols	2	2	–	–
aldehydes	7	7	–	–
ketones	9	9	8	7
cyclic ketones	5	5	2	2
ethers	17	27	5	5
hydrofurans	7	7	3	3
other cyclic ethers	4	4	2	2
esters	39	133	12	12
lactones	4	4	1	1
furans	5	5	3	3
acetals	2	2	1	1
carboxylic acids	–	5	–	–
more than one type of oxygen functionality	28	30	2	2
Total	**236**	**479**	**335**	**318**

Table 2: Atomic features used as initial node states, similar to.[41,43,44] All features are implemented as one-hot encoders.

Feature	**Description**	**Dimension**
atom type	type of atom (C, O)	2
is in ring	whether the atom is part of a ring	1
is aromatic	whether the atom is part of an aromatic system	1
hybridization	sp, sp2, sp3, sp3d, or sp3d2	5
# bonds	number of bonds the atom is involved in	6
# Hs	number of bonded hydrogen atoms	5

Table 3: Bond features used as edge features, similar to.[41,43,44] All features are implemented as one-hot encoders.

Feature	**Description**	**Dimension**
bond type	single, double, triple, or aromatic	4
conjugated	whether the bond is conjugated	1
is in ring	whether the bond is part of a ring	1
stereo	none, any, E/Z, or cis/trans	6

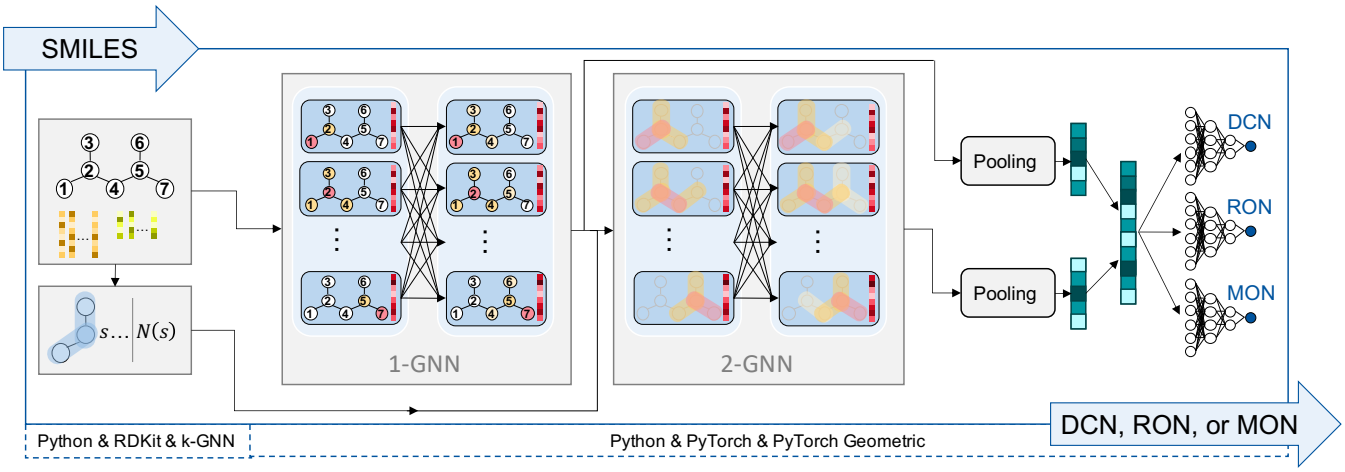


Figure 4: Workflow of the multi-task GNN model for predicting DCN, RON, and MON of hydrocarbons with SMILES strings as input. The model works in a hierarchical manner in which the outputs of the 1-GNN part are used as inputs for the 2-GNN. The outputs of both, the 1-GNN and 2-GNN part, are concatenated and represent the molecular fingerprint. This serves as the input for the three MLP channels predicting the target properties.

4.2 Model architecture

The proposed GNN model combines our higher-dimensional GNNs[46] with recurrent neural network architectures.[43,71,72] By using higher-dimensional GNNs, higher-order characteristics of a molecular graph can be extracted. The recurrent neural networks allow us to share parameters within the message passing phase of a GNN. We use gated recurrent units (GRUs) as recurrent neural networks, because GRUs avoid the vanishing gradient problem while having fewer parameters than long short-term memories (LSTMs) and thus have the potential to generalize faster on small data sets.[71] As illustrated in Figure 4, we apply two GNN structures in the message passing phase: (i) 1-GNN and (ii) 2-GNN. Thereby, atom environments in a molecule are first examined locally and then interactions between different atom environments are studied.

First, in the 1-GNN, an edge feature network and a GRU explore local atomic environments within the molecular graph. In particular, the updated hidden state in layer l, i.e., $\boldsymbol{h}_v^l$, is computed as

$$\boldsymbol{h}_v^l = \mathrm{GRU}\left(\boldsymbol{h}_v^{l-1}, \sigma\left(\theta_v \cdot \boldsymbol{h}_v^{l-1} + \boldsymbol{m}_v^l\right)\right) \ ,$$

where the message $\boldsymbol{m}_v^l$ is given by

$$\boldsymbol{m}_v^l = \sum_{w \in N(v)} \boldsymbol{h}_w^{l-1} \ \cdot \ \mathrm{ANN}_{\theta_e}\left(\boldsymbol{f}^E(e_{vw})\right) \ .$$

Herein, the edge feature network is a feedforward ANN, i.e., ANN_{θ_e}, that maps edge features $\boldsymbol{f}^E$ to a parameter matrix θ_e. Then, the parameter matrix θ_e is multiplied with the hidden states of a node's v neighbors, $\boldsymbol{h}_w^{l-1}$ with $w \in N(v)$, to calculate the message $\boldsymbol{m}$. The message is added to the hidden state of the considered node $\boldsymbol{h}_v^{l-1}$ multiplied with a parameter matrix θ_v. This result is transformed with an activation function σ, here rectified linear unit (ReLU). By applying a GRU, the updated hidden state in layer l, i.e., $\boldsymbol{h}_v^l$, is finally computed. Note that the initial hidden states $\boldsymbol{h}_v^0 = \boldsymbol{f}^V(v)$ are mapped to the dimension of the following hidden states by a shallow ANN with ReLU activation.

Secondly, a higher-dimensional message passing process is applied to enable interactions between atom environments (cf. Section 2.3). By combining the final atom representations of the 1-GNN into higher-dimensional nodes on which another message passing phase is applied, long-range effects of atom groups within a molecule can be captured. In this work, we found a 2-GNN architecture to have superior model per-

formance compared to that of a 3-GNN or a simple 1-GNN, thus the 2-GNN architecture is used to learn higher-dimensional graph features. Accordingly, we call the hierarchical combination of the 1-GNN and 2-GNN structure 1,2-GNN in the remainder of this work. We update the hidden states in the 2-GNN message passing similarly to the previously described 1-GNN, except that the edge feature network is replaced by a simple parameter matrix θ_2^k as there are no features for edges of the higher-order graph.[46]

After the message passing process, the model employs sum pooling for aggregating the hidden node states of the 1-GNN and 2-GNN resulting in two graph representation vectors. Sum pooling is applied, since the nature of DCN, RON, and MON is expected to be extensive at a microscopic level, similar to group additivity models.[12,13] After pooling, the two graph representation vectors are concatenated to the molecular fingerprint, i.e., $\boldsymbol{h}_G = [\boldsymbol{h}_{G_{1-GNN}}^T, \boldsymbol{h}_{G_{2-GNN}}^T]^T$. Finally, the molecular fingerprint is fed into a deep MLP for the prediction of DCN, RON, and MON, $\hat{p} = \mathrm{MLP}(\boldsymbol{h}_G)$.

4.3 Single- and multi-task learning

Having several prediction tasks, machine learning models can be trained in single- or multi-task manner.[73–75] In single-task learning, individual models are trained for each task. In multi-task learning, some representation is shared among the different tasks. For ANNs, this means that weights and bias parameters of hidden layers are shared between multiple tasks, i.e., they have equal values. Besides the shared layers, further individual hidden layers are employed for each task. The shared representation captures general information that is relevant to all tasks.[74] In the individual layers, task-specific information is extracted. In this way, the model learns more general input representations in the first layers compared to single-task models and overfitting can be reduced.[74] This is particularly relevant when the data sets are considerably small. Furthermore, multi-task learning can enable knowledge transfer between different prediction tasks.[75] In previous literature, this has been shown to yield superior results to single-task models in multiple molecular applications.[41,76,77]

In our model, we utilize multi-task learning by sharing the graph convolutional layers to create a general molecular fingerprint on which three individual MLPs (also called channels) are used for predicting DCN, RON, and MON. As cetane and octane numbers are known to correlate negatively,[4,8,12,13,78,79] multi-task learning is particularly promising in this context.

4.4 Transfer learning

Another technique enabling knowledge transfer in machine learning is transfer learning.[80,81] In transfer learning, knowledge learned in one domain is transferred to another domain, i.e., to the target task.[81] One way to perform transfer learning concerns pre-training of ANNs on a (source) task related to the target task. Afterward, the parameters of the pre-trained model are used to initialize parameters of a model trained on the target task data. Thus, transfer learning is particularly relevant for problems where the target data basis is small.

Transfer learning has recently been applied in the context of molecular property prediction with GNNs. For example, Grambow et al. pre-trained GNNs for thermophysical property predictions on large data sets from quantum-mechanical calculations and retrained parts of the GNN on a smaller experimental data set.[82]

We aim to improve our IQT-DCN prediction by transferring information from additional (D)CN data, i.e., from measurement techniques other than IQT (cf. Section 3). Thus, we propose a transfer learning approach, where CN and DCN data from various measurement setups are utilized for pre-training and then models are retrained on IQT-only DCN data.

4.5 Ensemble learning

Ensemble learning is a technique in machine learning where multiple models are trained and utilized for a single prediction task.[83–85] In most applications, several individual models are

trained independently on a randomly drawn subset of the training data. Then, the predictions of the individual models are averaged to receive a more accurate prediction. This way, prediction can be improved as random model errors are averaged out. Averaging single model predictions is also known as bootstrap aggregating or bagging.[83] This is particularly relevant for models with low bias and high variance which is the case for complex GNNs. Furthermore, small data sets can lead to high variance.

We train independent GNN models with randomly selected training and validation sets. To ensure an unbiased model comparison, all models share the same independent test set. While some advanced ensembling techniques apply weights to models, e.g., boosting,[86] we use a standard bagging technique that applies the same weight to all models.

5 Results and discussion

In this section, we first briefly summarize the general training settings (Section 5.1) and hyperparameter selection (Section 5.2). Then, we analyze the prediction accuracy of the proposed model developments: multi-task learning (Section 5.3), transfer learning (Section 5.4), and ensemble learning (Section 5.5). Finally, we compare the proposed model to state-of-the-art QSPR models (Section 5.6).

5.1 General training settings

As described in Section 3, the data set of DCN values extracted from the Compendium of Experimental Cetane Numbers[11] includes DCN measurements of 236 different components measured with the IQT method. We use this high-quality DCN data set and the RON and MON data sets for the training of the single and multi-task models (cf. Section 5.3). As typically done in machine learning, the data sets are standardized to zero mean and standard deviation of one for each target property, i.e., DCN, RON, and MON. Then, the data sets are randomly split into a training (85%) and test (15%) set. The test set is separated from the rest of the data and not used until the final testing of the model. For training the model, an internal validation set (15% of the original data set) is separated randomly from the training data and used for early stopping.

For each data point, the molecular graphs are generated as described in Section 4.1. Then, the model is trained based on the training set. Here, the mean squared error is used as the loss function. During training, the model performance regarding the internal validation set is measured in each epoch. The learning rate is decreased by a factor of 0.8 after every 3 consecutive epochs in which the error on the internal validation set did not decrease. Training is stopped either after a maximum number of 300 epochs was reached or if the internal validation error did not decrease in the 50 preceding epochs, according to early stopping. The error on the internal validation set is also used for comparison of the different model structures and the selection of hyperparameters. The training and random selection of the internal validation set are repeated 40 times for all models.

5.2 Hyperparameter selection

The proposed GNN model exhibits several hyperparameters that need to be chosen. To identify a suitable model architecture, relevant hyperparameters are varied within the given ranges: initial learning rate $\in \{0.0005, 0.001, 0.005\}$, hidden states size $\in \{32, 64, 128\}$, number of graph convolutional layers $\in \{1, 2, 3, 4, 5\}$ for the 1-GNN part and number of graph convolutional layers $\in \{1, 2, 3\}$ for the 2-GNN part, and message passing function $\in$ {without GRU, with GRU}. We performed an a priori extensive hyperparameter analysis on a preliminary data set. Based on the results of the parameter study, we use message passing with GRU, two graph convolutional layers in the 1-GNN part, two graph convolutional layers in the 2-GNN part, the size of the hidden node states is set to 64, and the initial learning rate is set to 0.001.

The remaining hyperparameters are described in the following and selected based on literature

and expert knowledge. Trial and error attempts to change these other hyperparameters did not lead to improved results. We use atom and bond features as described in Section 4.1. We apply an edge feature network with three layers and the following number of neurons: #1: 12 (i.e., number of edge features), #2: 128, #3: 4096 (i.e., number of hidden state squared). The MLPs constitute five layers with #1: 128, #2: 64, #3: 32, #4: 16, #5: 1 neurons.

5.3 Single- and multi-task learning

The aforementioned model settings were used for single-task and multi-task learning. The mean absolute errors (MAEs) of the two approaches on their validation and test set are displayed in Figure 5. The respective box plots illustrate the distribution of MAEs over the 40 individual training runs for each model.

Figure 5 shows that the model performance exhibits a high variance. This is mainly caused by the small data size for training, validation, and testing. As the validation sets of the 40 independent model runs are selected randomly, they show a larger variance of the MAE. In contrast, all 40 independent models share the same test set. Thus, the MAE distribution on the test set is more narrow. One methodology against high model variance is bootstrap aggregation which is performed in Section 5.5.

Table 4 summarizes the MAEs on the training, internal validation, and independent test set averaged over the 40 training runs for comparison. The averaged results show that the multi-task training approach improves the prediction accuracy on all test sets and for all predicted properties. For instance, the MAE of the DCN on the test set is reduced by about 17% from 6.6 to 5.5.

The results indicate that the simultaneous learning of DCN, RON, and MON leads to a better generalization of the graph convolutional layers and thus molecular fingerprint. One reason for the synergies are believed to be the correlations between DCN, RON, and MON.[4,8,12,13,78,79]

5.4 Transfer learning

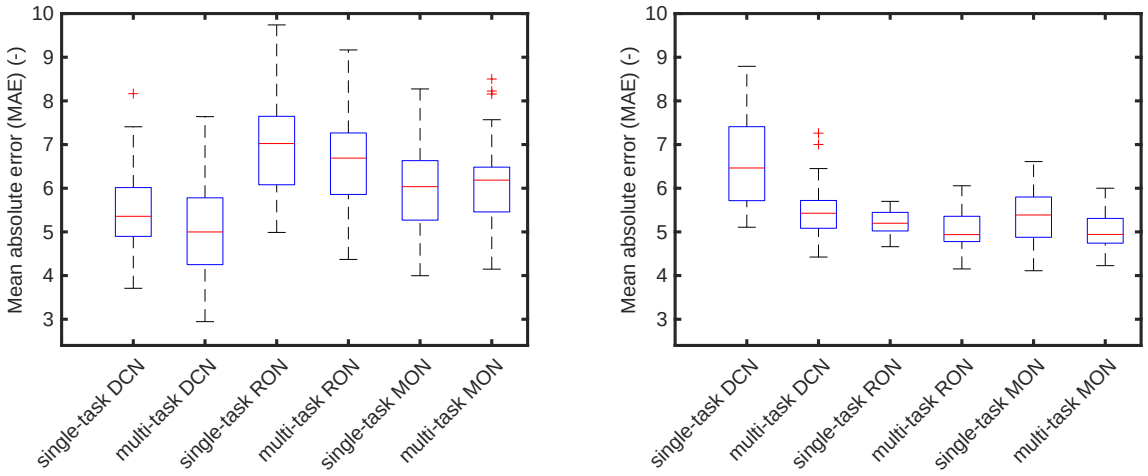
For the transfer learning approach, we pre-train the single-task DCN model on data from all different (D)CN measurement methods, i.e., we use (D)CN data of 447 components collected by Yanowitz et al.[11] (cf. Section 3). Then, the learned parameters are used to initialize the parameters in the graph convolutions and the MLP of the single-task DCN and also the multi-task model. For the latter, only the parameters of the MLP for predicting the DCN are transferred from the pre-training since RON and MON values are not subject to transfer learning. Finally, we retrain the models by only considering IQT-DCN data.

The results of the transfer learning approach are summarized in Table 4. Transfer learning improves the MAE of the single-task model for predicting the DCN from 6.6 to 6.1. For the multi-task model, however, transfer learning does not improve prediction accuracy: Test MAEs for RON and MON are almost the same with and without transfer learning. Furthermore, test MAE for DCN even increases from 5.5 to 6.0 with transfer learning. One possible reason for the poor performance of transfer learning in the multi-task learning is that the pre-training is essentially a single-task problem because we use only (D)CN data for pre-training. Thus, the pre-trained model could be biased towards (D)CN which then could lead to poor generalization of the multi-task model. As a consequence, we do not use the transfer learning approach for our final model.

5.5 Ensemble learning

After developing a suitable model architecture, model ensembling is applied to address the observed high variation (cf. discussion in Section 5.3). As described in Section 4.5, ensemble learning averages the response of multiple models and mitigates random model variations. Herein, we utilize the previously trained 40 model instances. We perform the ensemble learning on the multi-task architecture without transfer learning.

The results are summarized in Table 4. They



(a) MAE on validation set

(b) MAE on test set

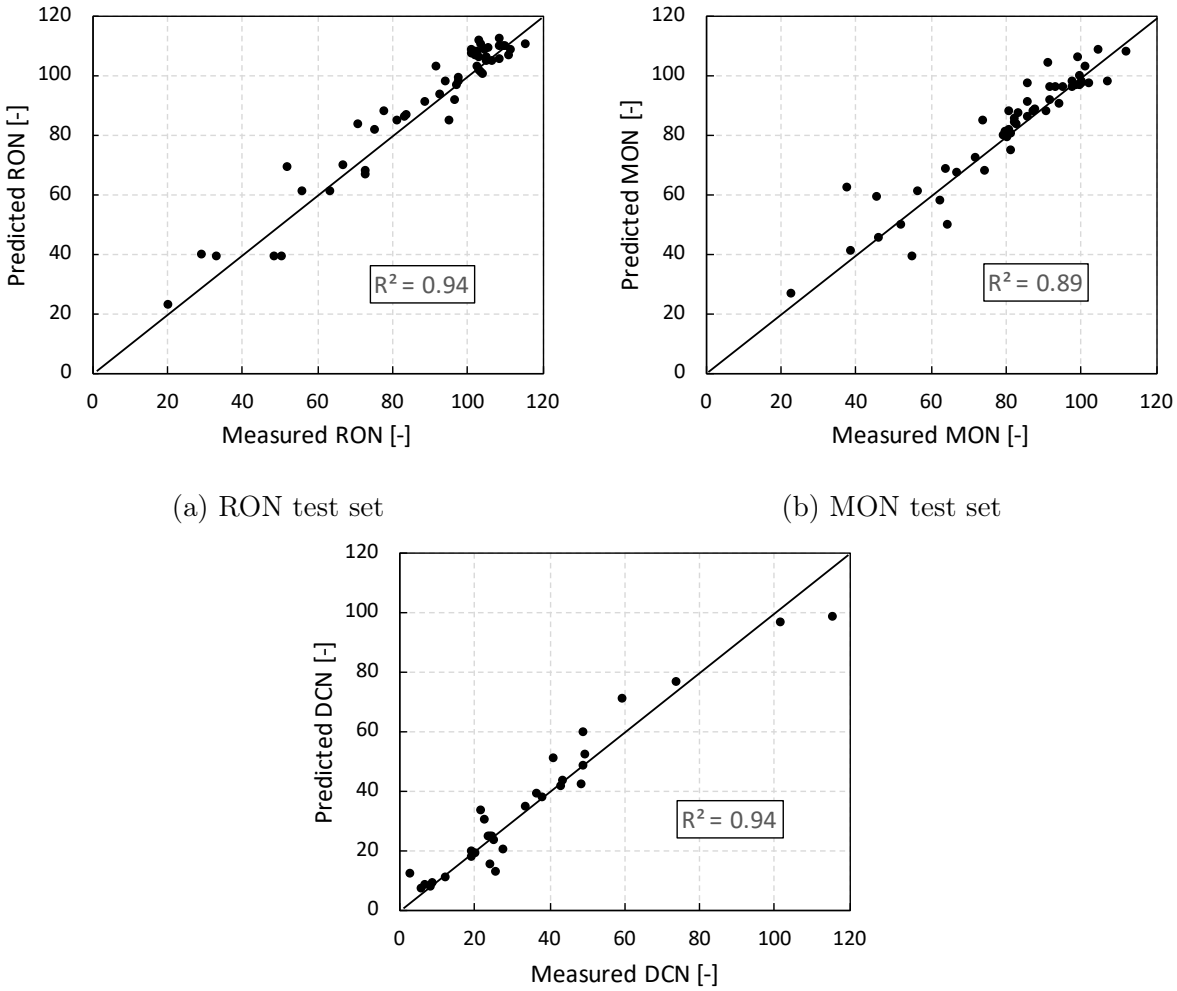
Figure 5: Comparison of the MAE of the single-task learning and the multi-task learning approach on the validation and test sets. The box-plots indicate the lowest and largest MAE (excluding outliers), the lower and upper quartile, and the median of the MAE over 40 independent model instances. Note that points that are more than 1.5 times the interquartile range away from the top or bottom of the box are marked as outliers.

Table 4: Mean absolute error (MAE) of training, validation, and test set averaged over 40 training runs. The table includes single-task learning (STL), multi-task learning (MTL), transfer learning (TL), and ensemble learning (EL). Lowest test set errors are highlighted in bold.

	DCN			RON			MON		
	Train.	Val.	Test	Train.	Val.	Test	Train.	Val.	Test
STL	2.7	5.5	6.6	3.7	7.0	5.2	3.1	6.0	5.4
MTL	1.8	5.1	5.5	2.8	6.7	5.0	2.3	6.1	5.0
STL & TL	2.2	4.6	6.1	–	–	–	–	–	–
MTL & TL	1.8	5.2	6.0	3.2	6.6	5.1	2.6	6.0	4.9
MTL & EL	1.8		**4.4**	2.9		**4.5**	2.3		**4.4**

show the averaged MAE on the test set and the combined training and validation set. The error on a validation set is shown as part of the training set because the averaged 40 model instances have individual randomly selected validation sets. Ensemble learning reduces the MAE of the DCN, RON, and MON significantly from 5.5 to 4.4, from 5.0 to 4.5, and from 5.0 to 4.4, respectively. The bootstrap aggregation compensates for the previously identified large model variations.

Figure 6 illustrates the parity plots for the independent test set of the proposed ensemble model. Herein, every point represents the averaged prediction of 40 multi-task models for a data point in the test set. The plots show high coefficients of determination for all three properties, i.e., $R^2_{\text{DCN}} = 0.94$, $R^2_{\text{RON}} = 0.94$, and $R^2_{\text{MON}} = 0.89$. For the MON, the higher number of outliers causes a slightly weaker coefficient of determination. Note that the parity plots show an uneven distribution of the data in the test set. For instance, there exist few data points with DCN numbers above 100 or RON numbers below 50.



(a) RON test set

(b) MON test set

(c) DCN test set

Figure 6: Multi-task GNN model ensembling: Parity plots for (a) RON, (b) MON, and (c) DCN test sets.

5.6 Comparison to state-of-the-art models

We compare our GNN model with three previous literature models. Our own previous model follows a group contribution approach for predicting IQT-DCN.[13] The model by Kubic et al. (2016)[12] combines group contributions with a multi-task ANN for the regression of CN, RON, and MON values. The model by vom Lehn et al. (2019)[31] also combines group contributions with ANNs for predicting the RON and the octane sensitivity, i.e., the difference between RON and MON, of alkanes, alkenes, cyclic alkanes, and alcohols

We summarize the reported literature results and the performance of our final model, i.e., the model resulting from multi-task and ensemble learning, in Table 5. We emphasize that a fair comparison of the GNN model to previous DCN, RON, and MON models is difficult for multiple reasons. First, the different models have been developed from different training data sets, leading to different applicability domains and potentially poor performance if models are evaluated outside their applicability domain. Second, previous literature does not always provide full test, training, and validation data sets and results. Different metrics (e.g., MAE and R^2) cannot be converted without the actual predictions of all data points. Third, different validation techniques have been applied in literature to quantify model performance, e.g., cross-validation or validation with

an unbiased test set.

Table 5 reports MAE and R^2 for the test sets of the respective models and indicates that the proposed GNN model achieves competitive prediction accuracy compared to the previous models for all three properties. Importantly, we provide our model, the training scripts and all data sets open-source. In comparison to our previous DCN group contribution model,[13] the GNN model is trained on a substantially larger data set and thus has a potentially larger applicability domain.

The development of QSPR and GNN models differs significantly from each other. Most notably, QSPR modeling requires to choose a set of descriptors, e.g., structural group counts, as potential explanatory variables. This step may facilitate understanding of the prediction problem (the human learns through model development) and can encode physical understanding into a tailored model structure. However, this also means that QSPR models inherently rely on assumptions about the underlying phenomena, i.e., the descriptors or structural groups of potential value. In contrast, the presented GNN method is trained in an end-to-end learning approach, as it relies on only few atomic and bond features (cf. Tables 2 and 3), and thus provides a flexible model structure that can possibly learn a broad variety of properties. End-to-end learning with graph convolutions, however, comes at the cost of higher computational effort for training.

6 Conclusion

Predictive models for fuel ignition quality play a crucial role in the development of novel fuels. We propose a data-driven graph neural network (GNN) model for the prediction of three important fuel auto-ignition indicators, i.e., the derived cetane number (DCN), the research octane number (RON), and the motor octane number (MON). Our model is applicable to a wide spectrum of non-oxygenated and oxygenated hydrocarbons, shows competitive performance to state-of-the-art models, and can be easily accessed via a web interface.

From the methodological point of view, our GNN-based model offers the advantage that, in contrast to previous works based on QSPR modeling, no molecular descriptors or structural groups, have to be selected, because GNNs achieve end-to-end learning from the molecular structure to the properties of interest. While such a data-driven approach is often believed to require extensively large data sets, this work demonstrates that good model accuracies can indeed be achieved for small data sets (order of hundreds) by using multi-task and ensemble learning. Given the expected future increase in measurement data available for training, we expect further potential for GNNs in fuel ignition quality prediction. We provide the corresponding training code and the final model open-source making it a viable tool for further development. Finally, this work may constitute a prototype for rapid, versatile property prediction beyond DCN, RON and MON and thus for property prediction in various disciplines.

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Supporting Information Available

The following files are available free of charge.

- RON, MON and (D)CN data (XLSX)

Table 5: Performance comparison of the proposed model to other published models. Errors are reported for the respective test sets.

	GNN model		Dahmen & Marquardt[13]		Kubic et al.[12]		vom Lehn et al.[31]	
	MAE	R^2	MAE	R^2	MAE	R^2	MAE	R^2
DCN	4.4	0.94	5.8	0.84	–	0.90	–	–
RON	4.5	0.94	–	–	–	0.93	4.0	0.92
MON	4.4	0.89	–	–	–	0.91	–	–

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Graphical TOC Entry